

WES Annual Conference 2018



Project Progress Updates

File Contents

- Control Systems – starting page 2
- Structural Materials and Manufacturing Processes – starting page 26
- Novel Wave Energy Converter – starting page 49
- Power Take-Off – starting page 79

WES Annual Conference 2018



Project Progress Updates: Control Systems, Stage 2

File Contents

- MaxSim Ltd – Cost of Energy Optimisation by Reinforcement Learning [4 pages]
- Queen Mary University – Adaptive Hierarchical Model Predictive Control of Wave Energy Converters [12 pages]
- Wood – IMPACT – Integrated Marine Point Absorber Control Tool [8 pages]

Wave Energy Scotland Annual Conference, Elevator Pitches, 6th December 2018

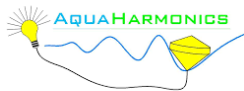
CEORL – Cost of Energy Optimised by Reinforcement Learning – Control Systems, Stage 2

Max Carcas, Caelulum Ltd



Contributors:

Paul Stansell, MaxSim
Richard Crozier, Power Enable Solutions
Joseph van t' Hoff, Marine Systems Modelling
David Forehand, The University of Edinburgh
Alexandra Price, Wave Conundrums Consulting
Max Ginsburg and Alex Hagmüller, Aquaharmonics
Max Carcas, Caelulum
David Pizer
Chris Retzler, Mocean Energy
Jørgen Hals Todalshaug, CorPower Ocean
Ross Henderson, Quoceant



MaxSim

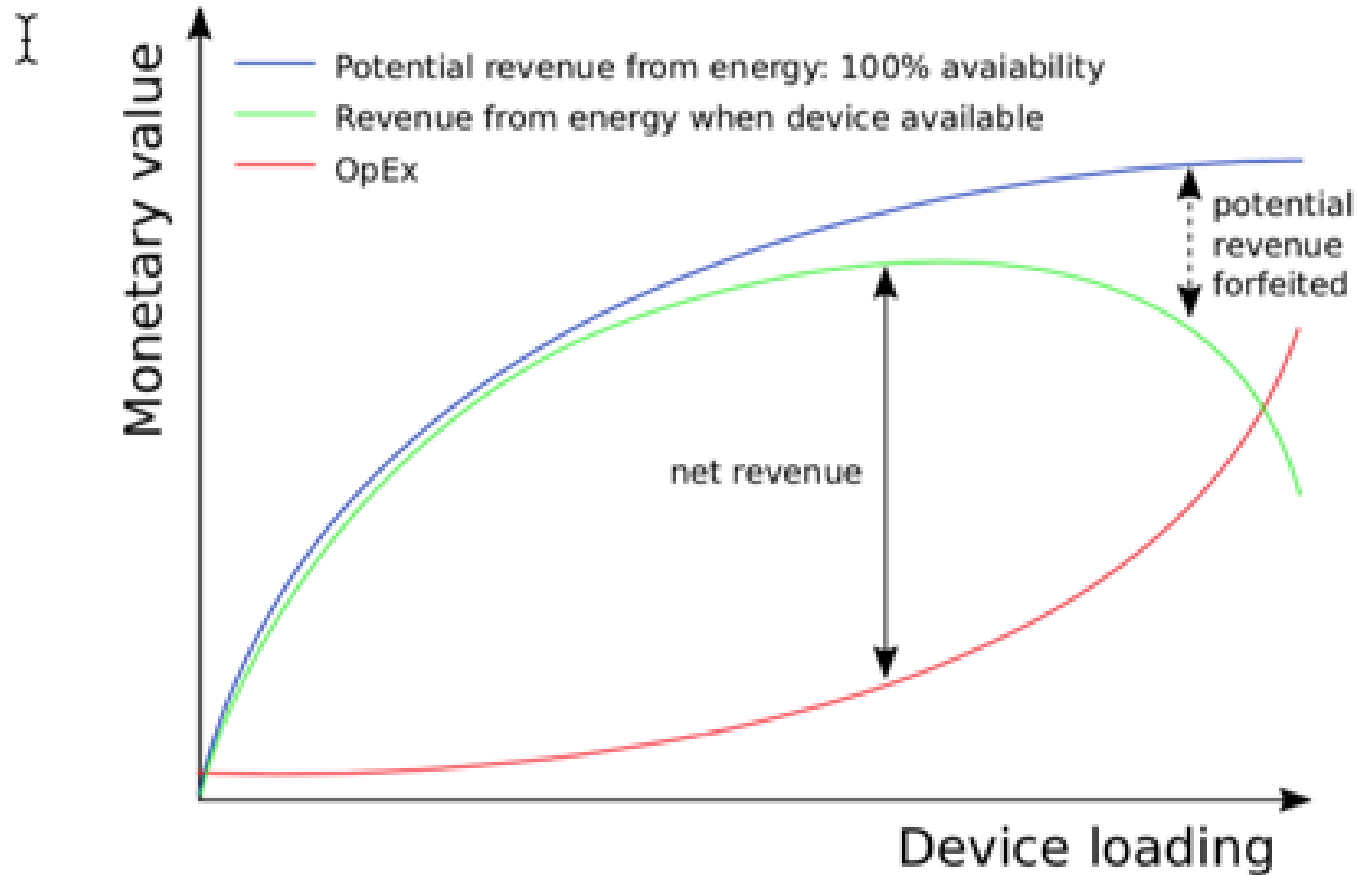


THE UNIVERSITY
of EDINBURGH CAELULUM



Highlands and Islands Enterprise
Iomairt na Gàidhealtachd 's nan Eilean

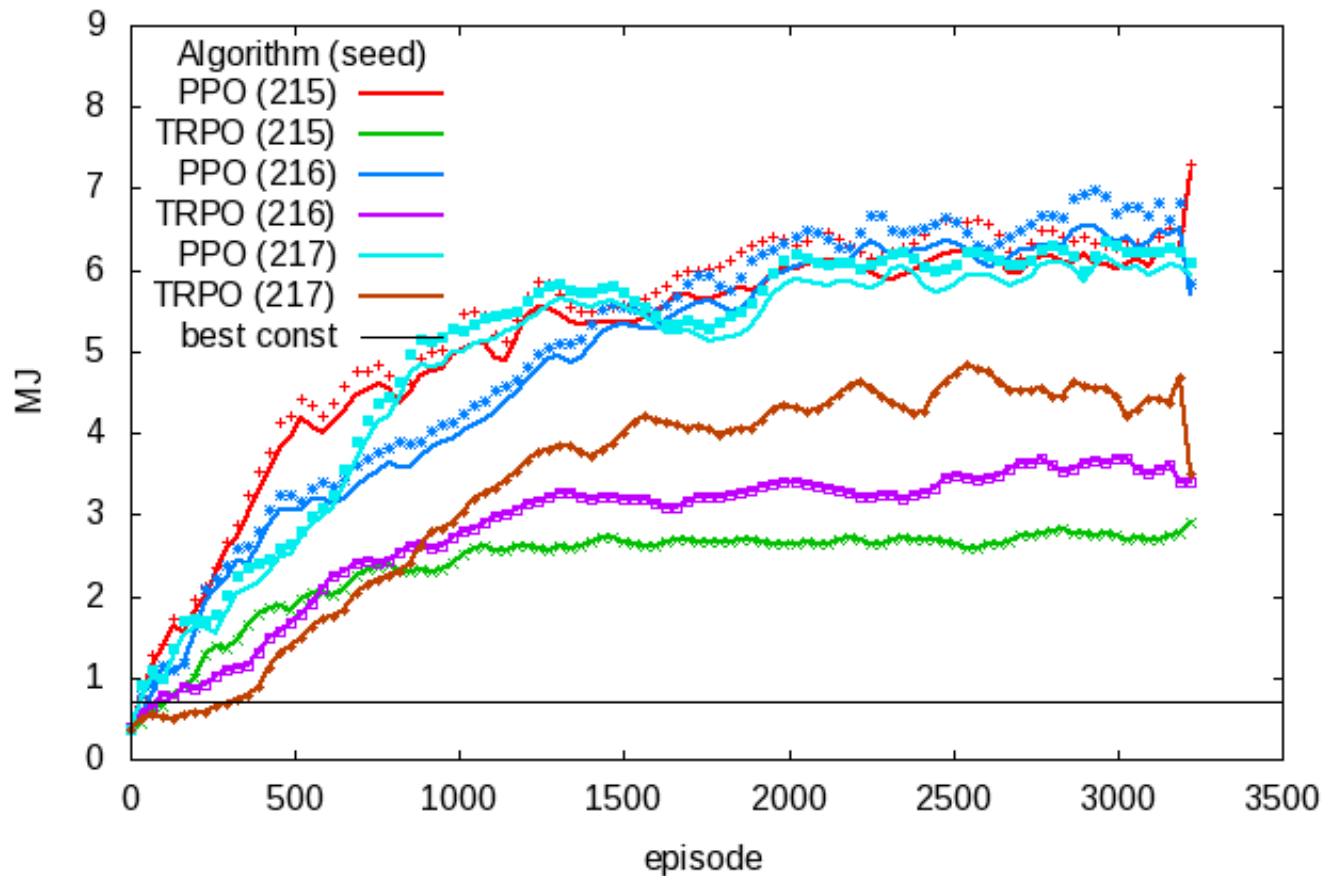
Project Aim: Minimise LCOE



RL convergence

(simple model)

Energy and reward: states = [eta, eta_t, xi, xi_t],
actions = [b_c, k_c] = [4 mod Z {0,1}, k_c_0 {-1,1}]



Project Summary

- Control policy–Reinforcement Learning
- All controllable aspects:
 - PTO load (impedance, limits, etc.)
 - Device specific: mooring pretention, generator, etc.
- For this WES project: case-study partner is AquaHarmonics

Challenges

- How to express LCOE (long timescale) as a reward (short timescale)
- Transferability of policies between simulations and physical devices
- Stability of controller

Technical product or integration offering

- Wave-by-wave vs sea-state control:
 - Best use of load/stroke range
 - Timescale - wave groups & tidal interaction
- Pre-trained on a model
- Customised on physical device
- Uses only standard on-board sensor data
- Goal: minimise LCOE vs maximise power

Skills expertise or technology required

- For Stage 3 of WES Control call:
 - WEC developers - advice on specifications
 - PTO developers - advice on specifications
 - Space for hardware-in-the-loop tests
 - Tank for validation trials
 - Standard supervisory controller
- After WES programme:
 - WEC developers - case studies

Adaptive Hierarchical Model Predictive Control of Wave Energy Converters

STAGE 2 Control System Project of Wave Energy Scotland

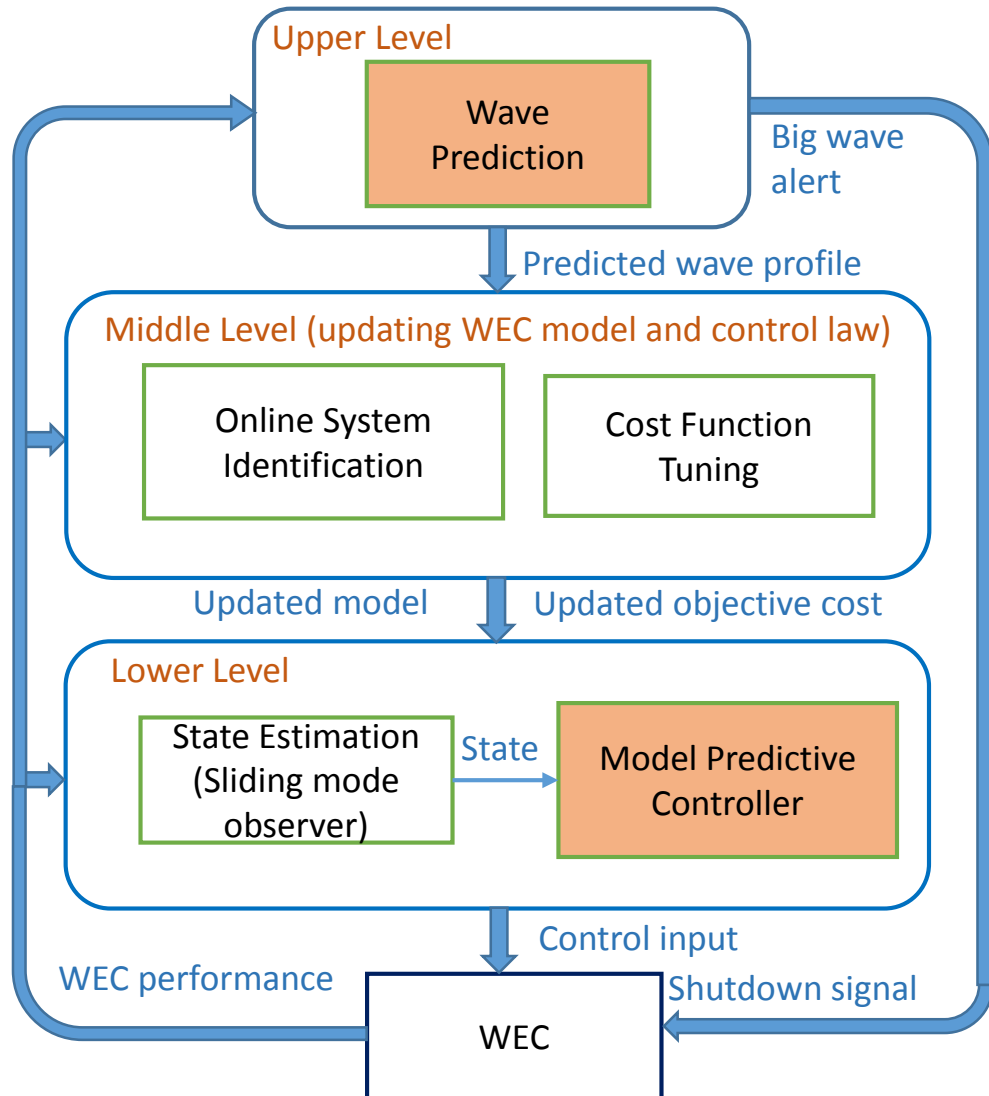
Queen Mary University of London

Mocean Energy Ltd

University of Exeter

06/Dec/2018

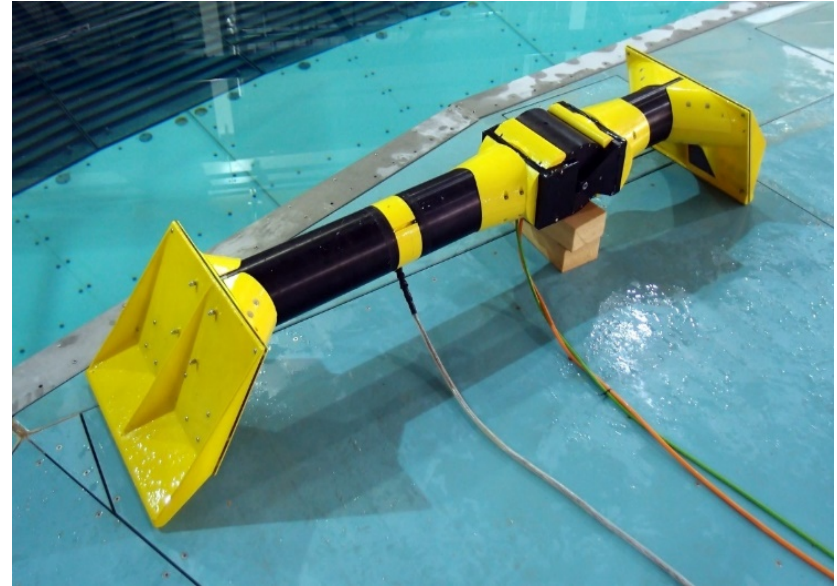
The proposed control framework



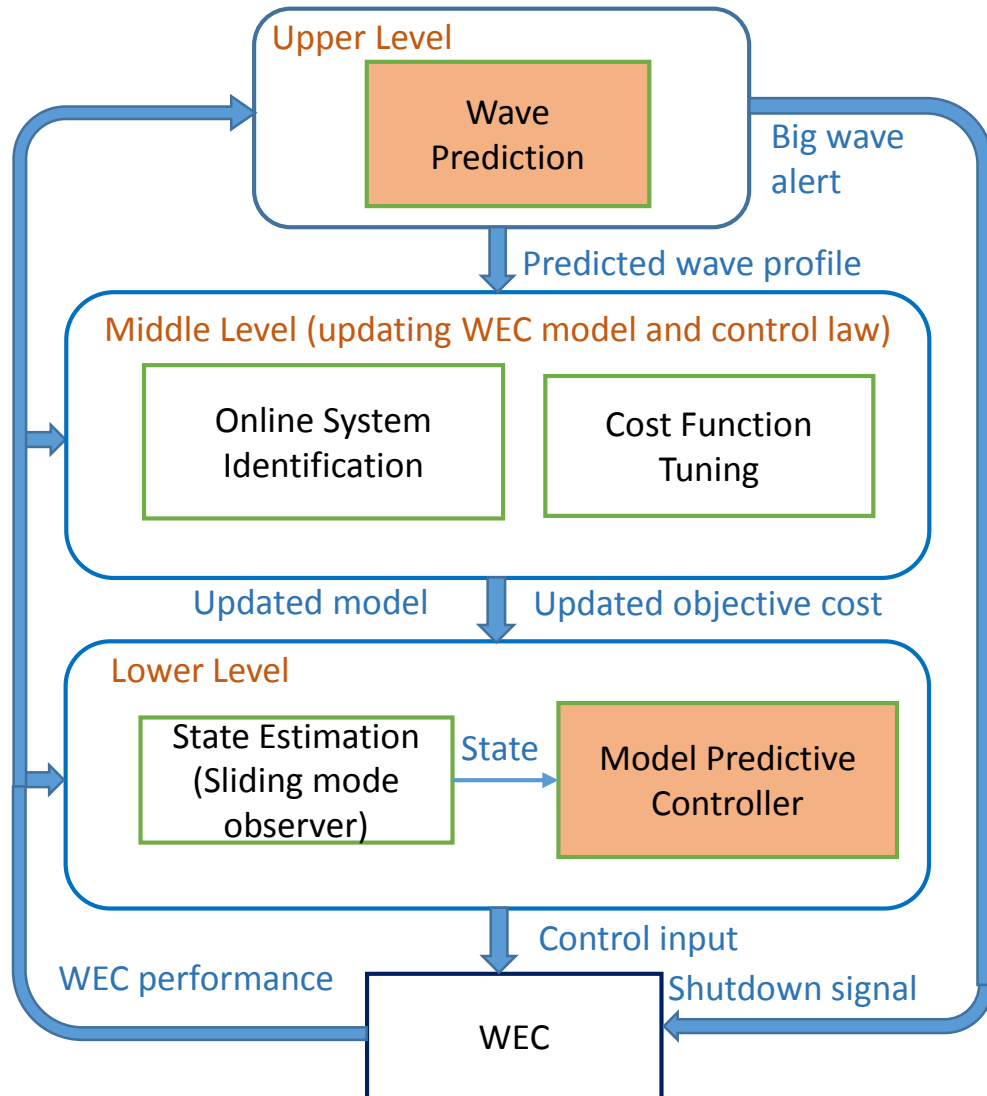
- We aim to develop a hierarchical control framework to
- maximise the energy conversion efficiency of a single WEC, and
 - guarantee safe operation in different sea states.

The Device for Demonstration

- We are using the device developed by Mocean Energy Ltd.
- Attenuator type of device with two-floats and multi-motion.
- More complicated dynamics compared to the single-motion and single float device, e.g. point absorber.
- Thus modelling and control are more challenging!



The proposed control framework

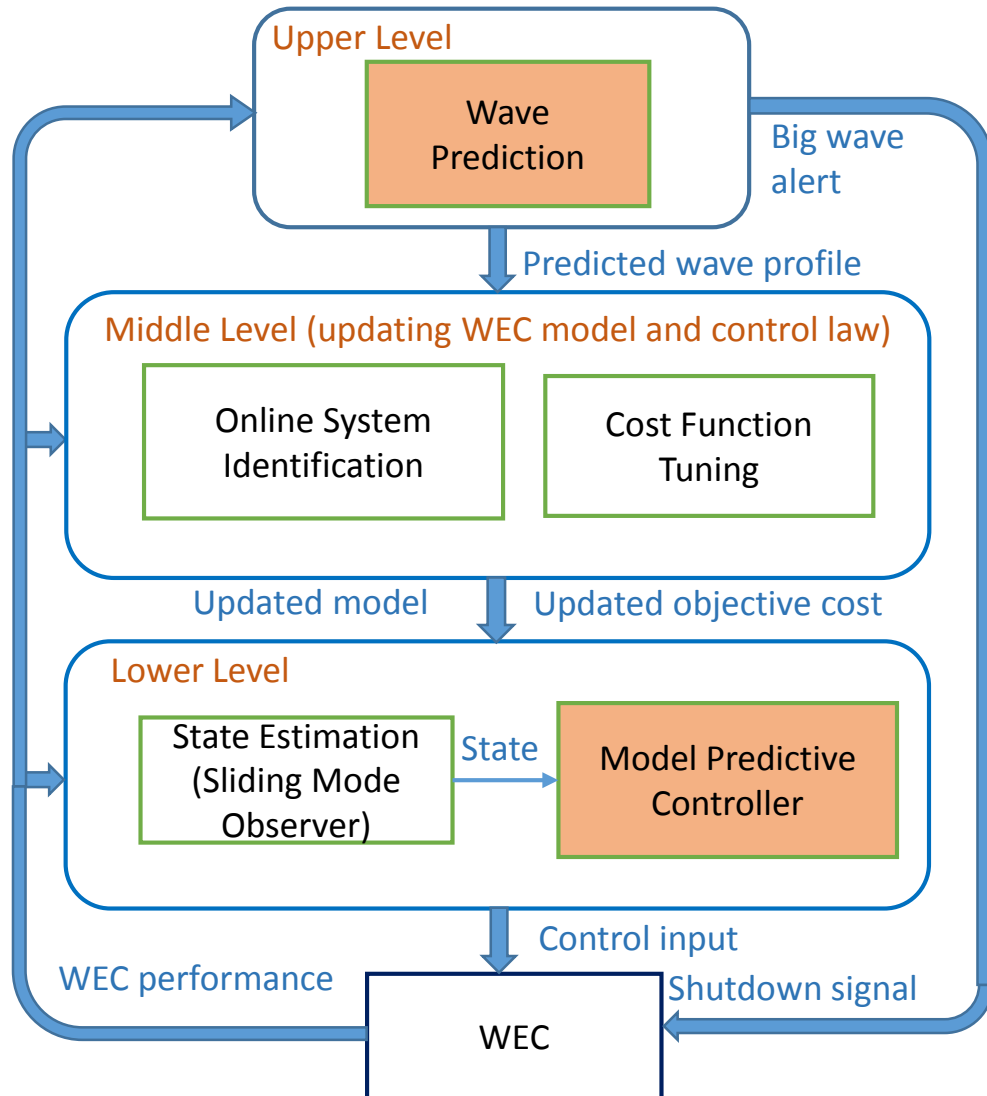


How it works:

- ***Upper level – wave prediction***

- Quiescent Period Wave Prediction** technique to send detrimental wave alert to shut down WEC.
- Deterministic Sea Wave Prediction** to predict wave profile.

The proposed control framework



How it works:

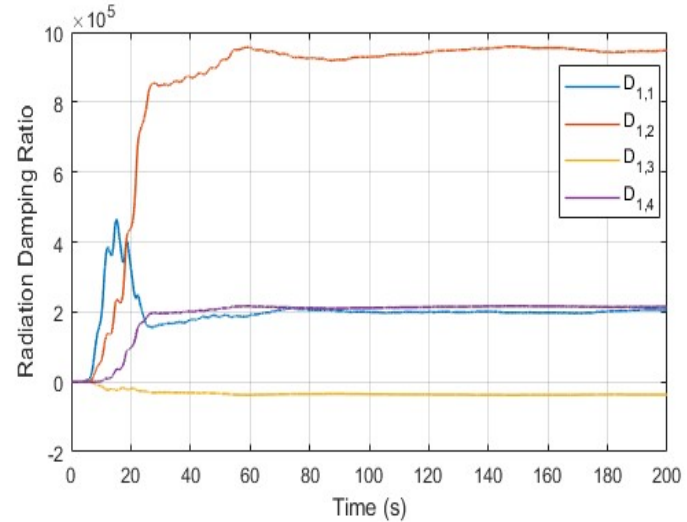
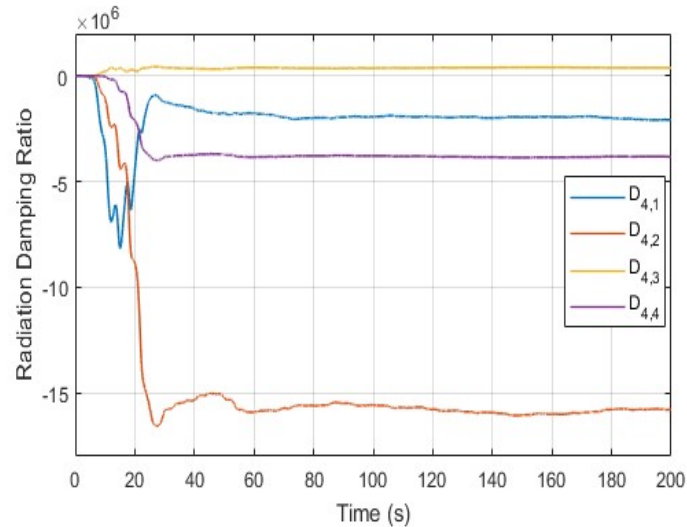
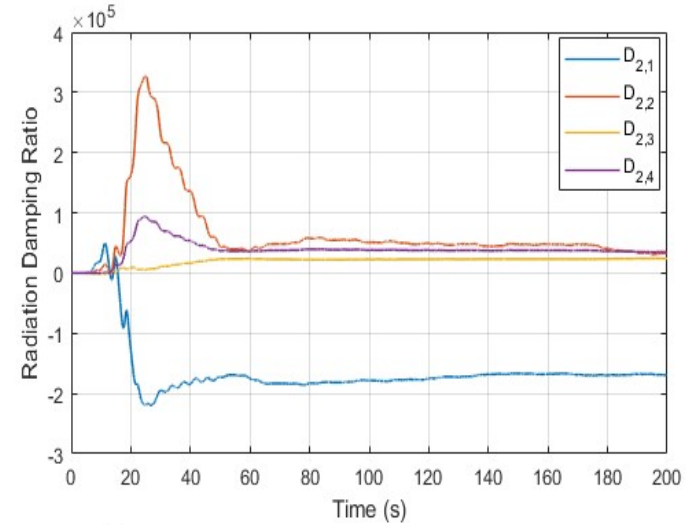
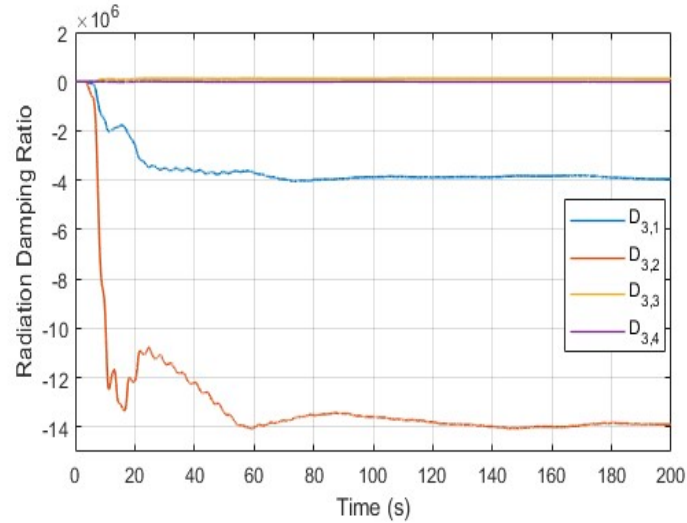
- **Upper level – wave prediction**

- i. **Quiescent Period Wave Prediction** technique to send detrimental wave alert to shut down WEC.
- ii. **Deterministic Sea Wave Prediction** to predict wave profile.

- **Middle level – update WEC model and control law**

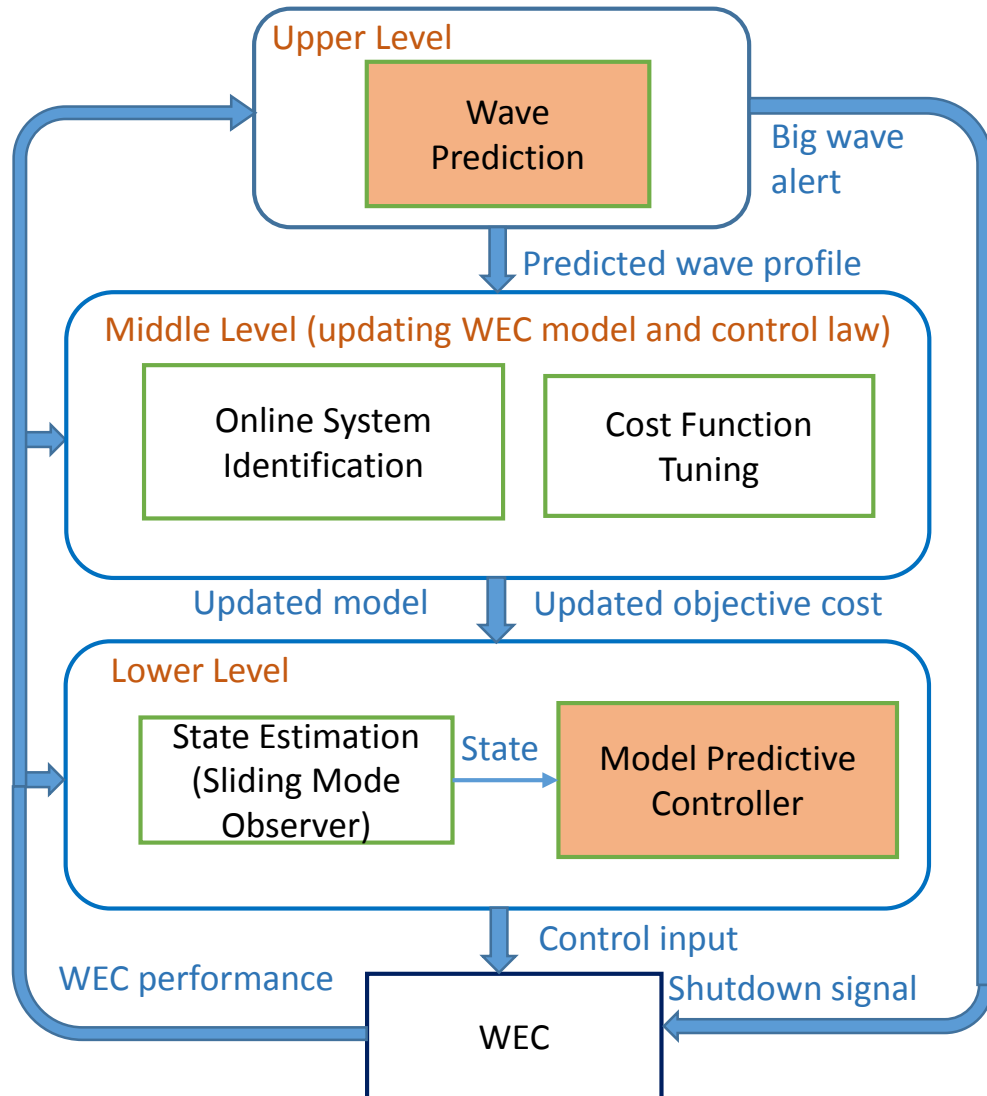
- i. Online WEC model identification using **adaptive parameter estimation**.
- ii. Adaptive tuning of control law.

Fast convergence of adaptive online parameter identification of dynamic parameters



Key dynamics parameters identified by Adaptive Neural Networks converge to accurate values very rapidly.

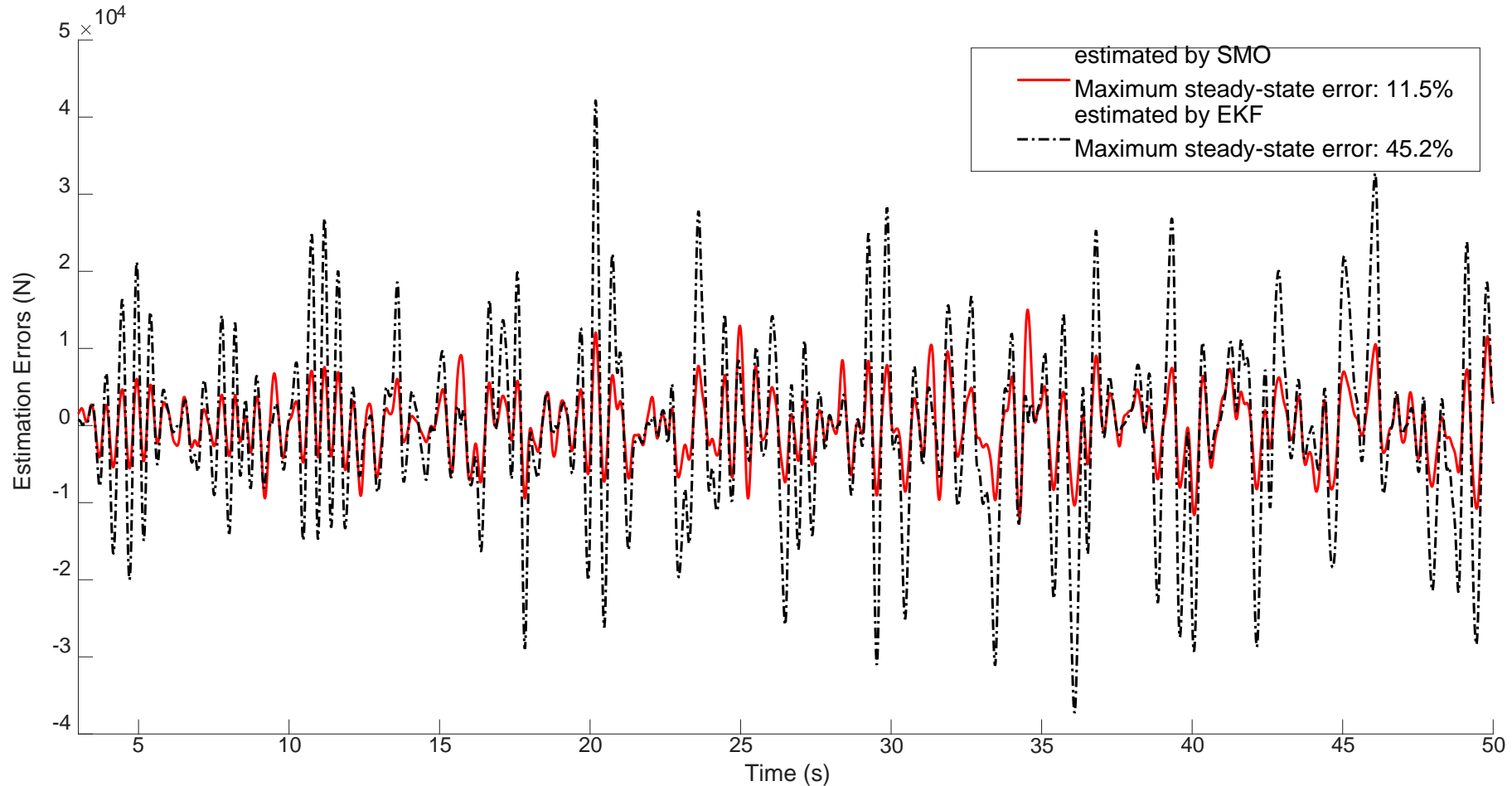
The proposed control framework



How it works:

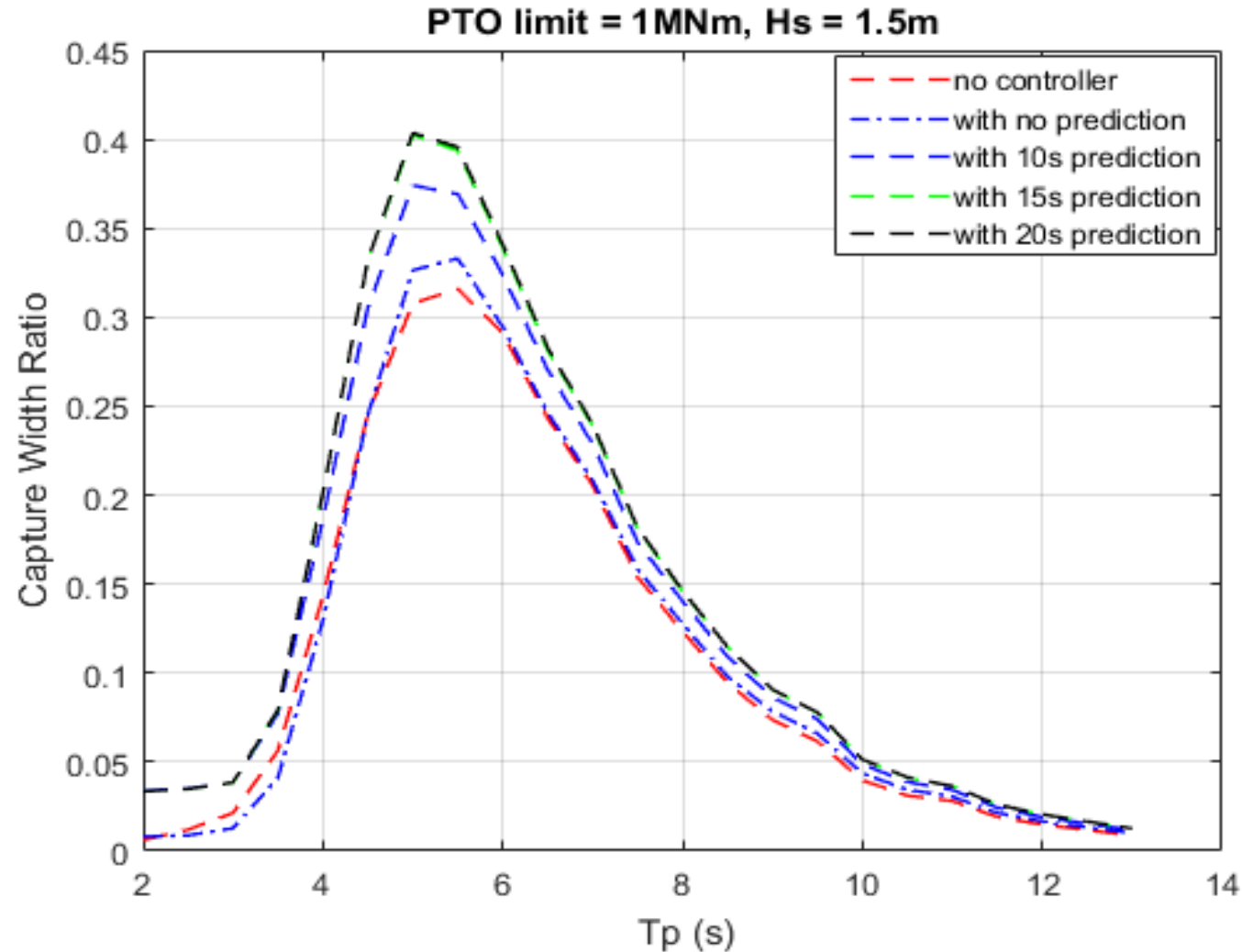
- **Upper level – wave prediction**
 - i. **Quiescent Period Wave Prediction** technique to send detrimental wave alert to shut down WEC.
 - ii. **Deterministic Sea Wave Prediction** to predict wave profile.
- **Middle level – update WEC model and control law**
 - i. Online WEC model identification using **adaptive parameter estimation**.
 - ii. Adaptive tuning of control law.
- **Lower level – energy maximisation control**
 - i. Accurate estimation of excitation force and states by **Siding Mode Observer**.
 - ii. Non-causal energy maximisation control subject to constraints by **Model Predictive Control (MPC)**.

Sliding Mode Observer provides more accurate excitation force estimation than EKF



Sliding mode observer enables more accurate excitation force estimation than Extended Kalman Observer

Model Predictive Control performance - Capture Width Ratio



The main findings

- Energy output can be improved by 30%-90% by proposed control strategies in different scenarios.
- Wave prediction plays a major role in achieving this improvement.
- The proposed control scheme is very robust to a) wave prediction accuracy, b) modelling uncertainties, c) change of sea states.

Selected publications partially supported by this project

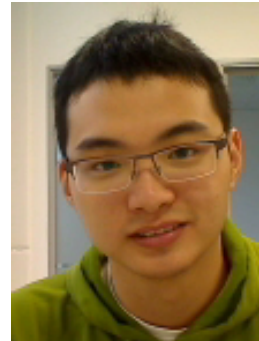
- S. Zhan and G. Li*, Linear optimal noncausal control of wave energy converters, IEEE Transactions on Control Systems Technology, published online.
- J. Na, B. Wang, G. Li*, S. Zhan, and W. He, Nonlinear Constrained Optimal Control of Wave Energy Converters with Adaptive Dynamic Programming, IEEE Transactions on Industrial Electronics, published online.
- J. Na, G. Li*, B. Wang, G. Herrmann, S. Zhan, Robust Optimal Control of Wave Energy Converters Based on Adaptive Dynamic Programming, IEEE Transactions on Sustainable Energy, published online.
- S. Zhan and G. Li, A reliable optimal controller design method for seawave energy converters, the 12th European Wave and Tidal Energy Conference, Cork, Ireland, September, 2017.
- S. Zhan, B. Wang, J. Na, G. Li*, Adaptive Optimal Control of Wave Energy Converters, to be presented at the 11th IFAC Conference on Control Applications in Marine Systems, Robotics, and Vehicles, Opatija, Croatia, Sep. 10-12, 2018.
- Z. Liao, G. Nian, P. Stansby and G. Li*, Control-Oriented Modelling for Wave Energy Converter M4, the 4th Asian Wave and Tidal Energy Conference (AWTEC 2018), Taipei, Taiwan, Sep. 9-13, 2018.
- J. Na, G. Li*, S. Zhan, Online Optimal Control of Wave Energy Converters Via Adaptive Dynamic Programming, American Control Conference, Milwaukee, June, 2018.

The Team

QMUL:



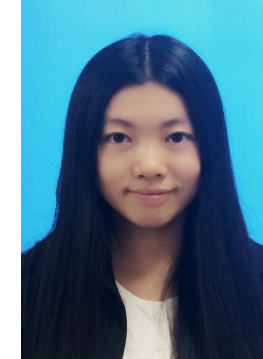
Dr Guang Li
(Project Leader)



Dr Siyuan Zhan
(Controller design)



Mr Zhijing Liao
(Modelling)



Dr Yao Zhang
(State/force estimation)

Mocean:



Dr Cameron McNatt
(Hydrodynamic modelling)



Dr Chris Retzler
(System configuration)

Exeter:



Prof Mike Belmont
(Wave prediction)



Prof Chris Edwards
(Uncertainties)



wood.

IMPACT – Integrated Marine Point Absorber Control Tool

Wave Energy Scotland Annual
Conference 2018

woodplc.com

IMPACT – Integrated Marine Point Absorber Control Tool

Project Overview

- Milestone 1
 - Development of 4 “exemplar WEC” models
 - Design basis for controller design
 - Controllers for WEC types 1 and 2
- Milestone 2
 - Controllers for WEC types 3 and 4
- Milestone 3
 - Open source control tool for model development and controller design
 - User manual for the control tool
- Milestone 4
 - Physical testing FEED report
 - Controller hardware FEED report
 - Implementation on a software model of a real WEC
 - Final reporting

Project Team



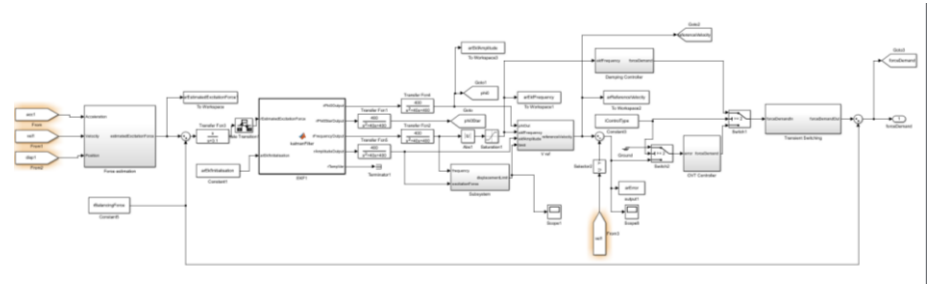
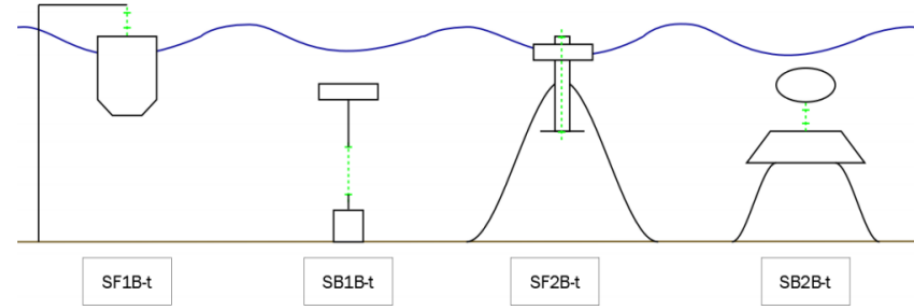
Thanks for valuable additional input from the industry advisory board and also particularly from Carnegie and Trident, who have provided much of the required information for the activities in Milestone 4.



IMPACT – Integrated Marine Point Absorber Control Tool

IMPACT toolbox

- IMPACT allows the design of Optimal Velocity Tracking (OVT) controllers for the four types of WEC shown
- As well as OVT, adaptive linear damping (linear damping with a variable gain based on the excitation force) can also be implemented.
- Models generated by IMPACT could also be used to help develop MPC techniques
- IMPACT has an easy to use General User Interface (shown on the next slide) to allow control models and controllers to be quickly designed and assessed.
- IMPACT also includes a data analyser to make interrogation of WEC-Sim simulations much easier



Model **IMPACT model loaded**

Current Model

Frequency range (rad/s) --

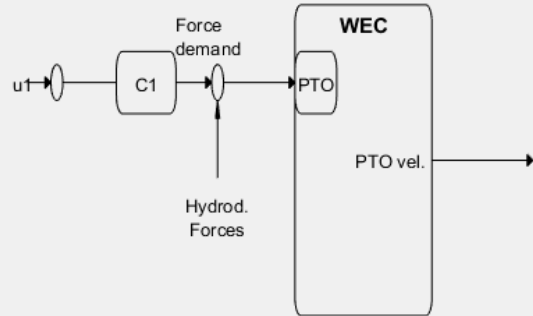
Response

Input	Output
u1	Relative velocity
PTO Force Demand	
u2	

Closed loop

Open loop

Hold on



Controller

Current set of controller

PTO controller (C1)

PTO Controller X (C2)

Additional transfer functions

Floater impedance

Spar impedance

Excitation floater

Excitation spar

Floater impedance X

Spar impedance X

Excitation floater X

Excitation spar X

Fit transfer functions automatically:

Floater Impedance

Order num.

Order den.

Fitted transfer function

Controller settings

Controller type

Constraint PTO displacement

PTO maximum displacement (m)

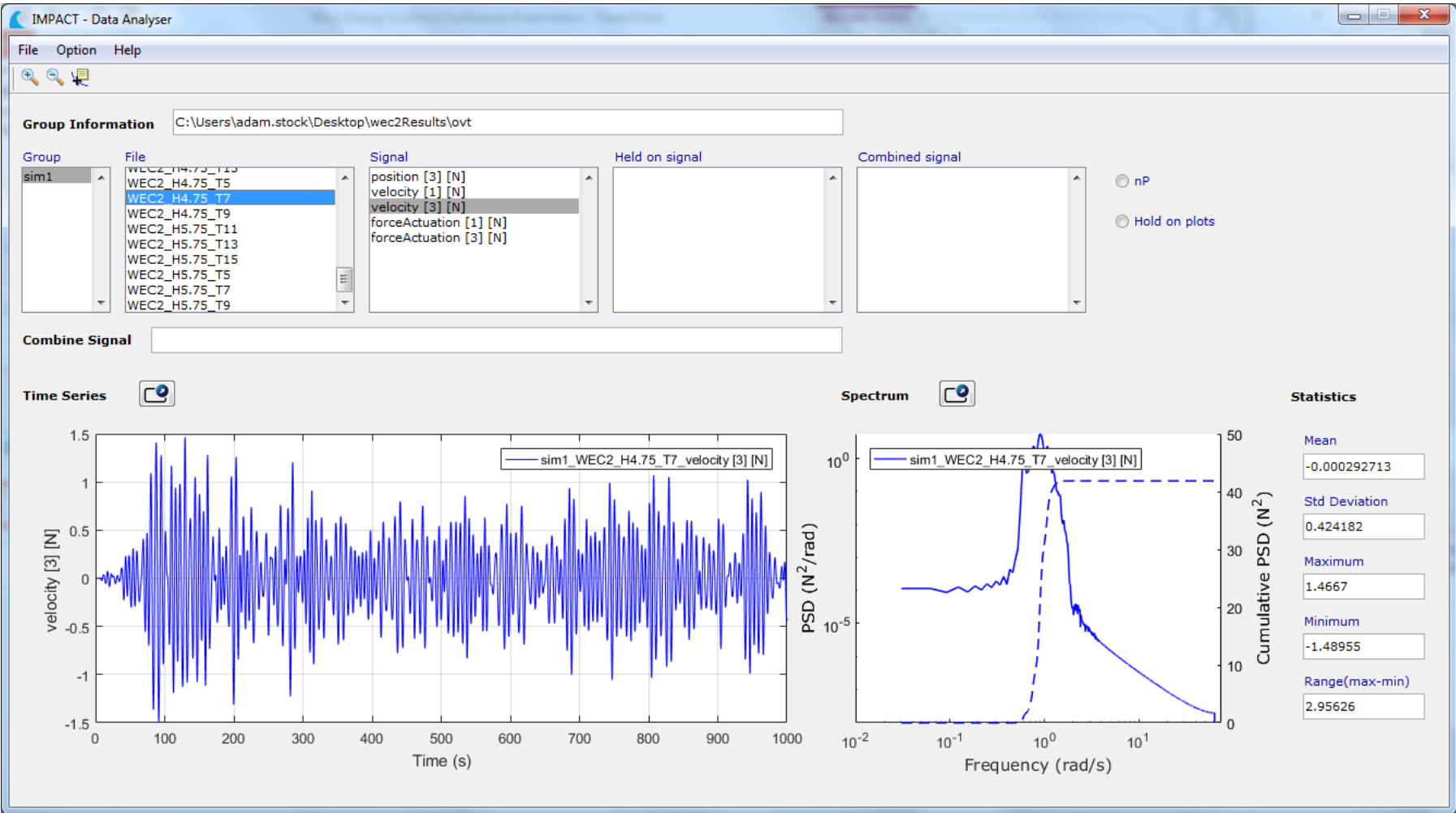
PTO maximum force (N)

PTO minimum force (N)

Start of controller ramp time (s)

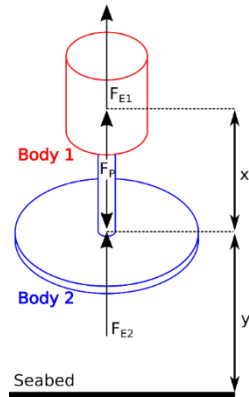
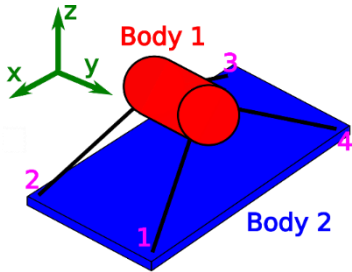
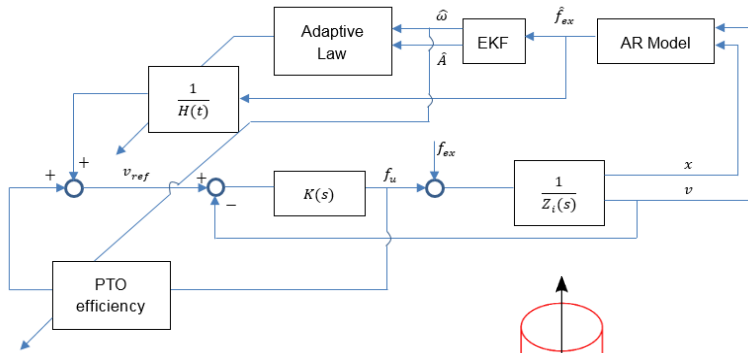
Duration of controller ramp time (s)

Output sample time



IMPACT – Integrated Marine Point Absorber Control Tool

Optimal Velocity Tracking

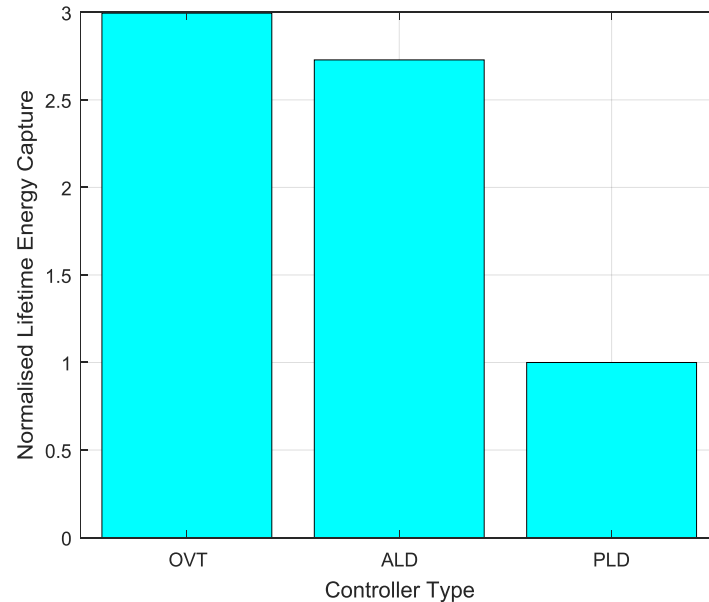
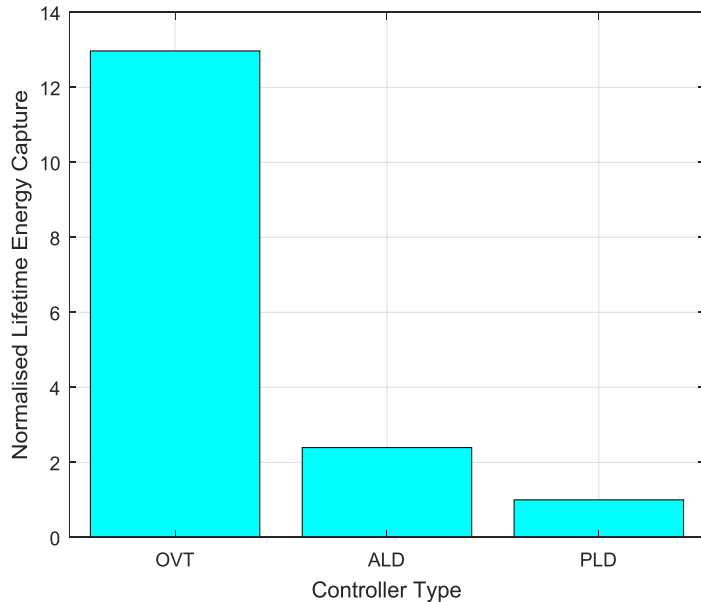


- The controller used is based on the Optimal Velocity Tracking (OVT) controller methodology proposed by Fusco and Ringwood
- Estimates of the excitation force, including its amplitude and frequency inform an optimal speed
- The optimal speed is tracked by a set-point tracking controller
- No expensive equipment required:
 - Lean algorithm
 - Minimal sensing requirements
- Applied to two body WECs for the first time

IMPACT – Integrated Marine Point Absorber Control Tool

Controller Performance

- Examples are given below of the increase in energy output for OVT and ALD compared to passive linear damping for WEC types 1 (left) and 3 (right) over a typical range of Scottish waters sea conditions. It is clear that the WEC design has a large effect on the amount of extra energy OVT can capture



The background is a solid teal color. It features three overlapping semi-circular shapes of varying shades of teal. One large semi-circle is on the left, another larger one is in the center, and a smaller one is on the right. The text 'Thank-you' is positioned on the left side, overlapping the first semi-circle.

Thank-you

WES Annual Conference 2018



Project Progress Updates: Structural Materials and Manufacturing Processes, Stage 2

File Contents

- Arup – Concrete as a Technology Enabler [8 pages]
- CorPower – HydroComp [8 pages]
- Tension Technology International – NetBuoy [5 pages]

WES CREATE

Concrete as a Technology Enabler

WES Annual Conference | December 2018

ARUP

cruz atcherson
CONSULTING ENGINEERS

mpa
The Concrete Centre

George Walker | Arup
george-a.walker@arup.com
+44 20 7755 2502

DOOSAN

mocean energy

Carnegie
wave energy

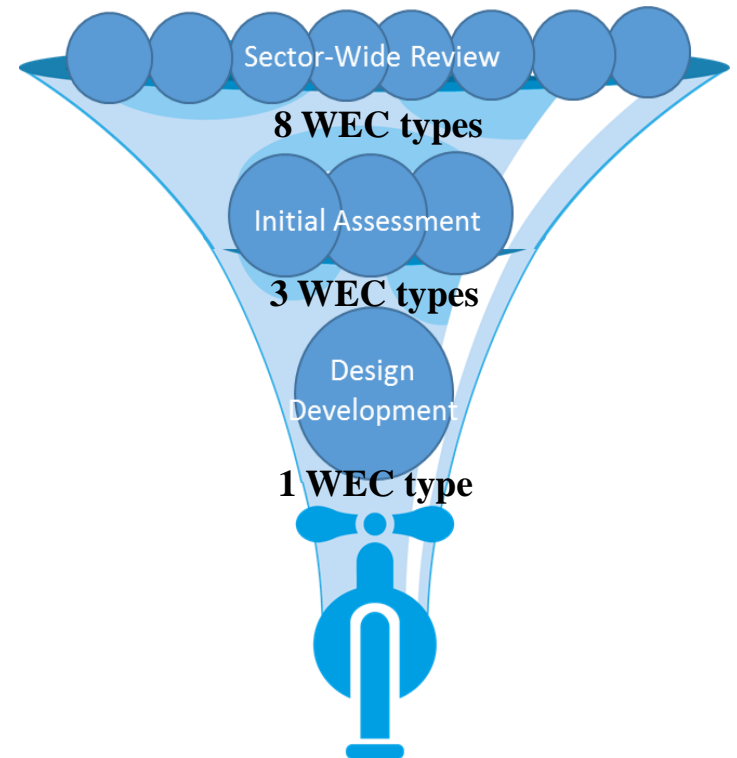
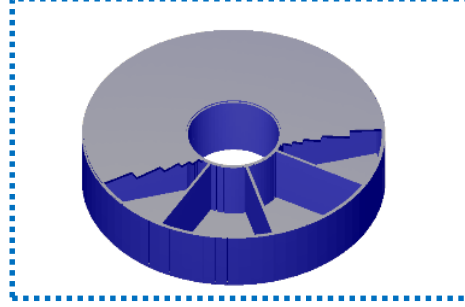
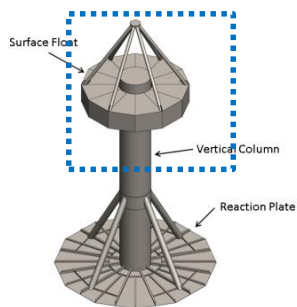
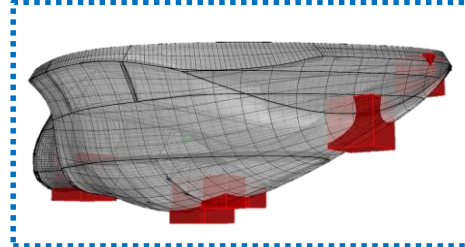
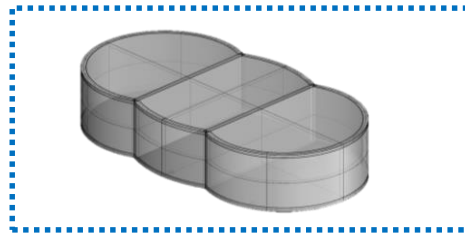
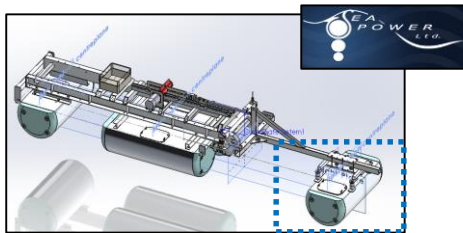
Design Choice: Reinforced Concrete vs. Steel

Reinforced concrete has the potential to offer a **robust and low cost solution** taking advantage of a **mature supply chain**: the focus of the CREATE project.

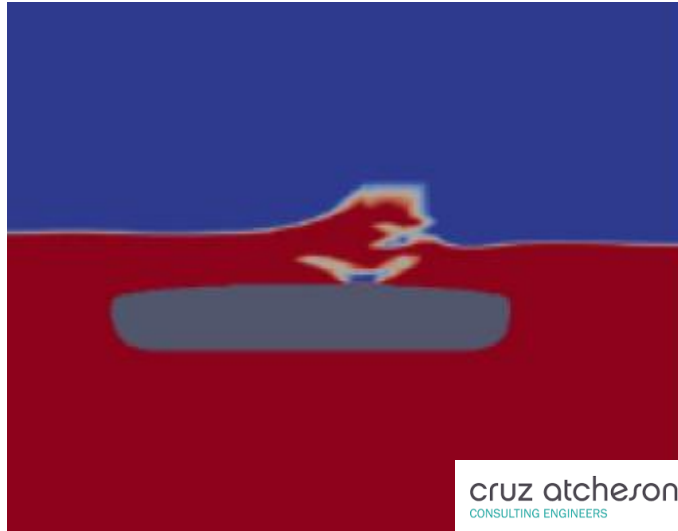
	Reinforced Concrete	Steel
Material Properties	Strength ~ 50 MPa Density ~ 2600 kgm ⁻³	Strength ~ 350 MPa Density ~ 8000 kgm ⁻³
	<i>Concrete solutions are likely to be heavier than steel</i>	
Lower Unit Cost	Lower unit and fabrication cost	Higher unit and fabrication cost
High TRL and Mature Supply Chain	Mature supply chain with simpler fabrication available at more locations	More specialist and less available fabrication methods
High Durability	<ul style="list-style-type: none">• Corrosion resistant• Less maintenance overhead• Better fatigue performance (typically)	<ul style="list-style-type: none">• Corrosion protection required• Worse fatigue performance (typically)

CREATE Stage 1: Engineering Design Study

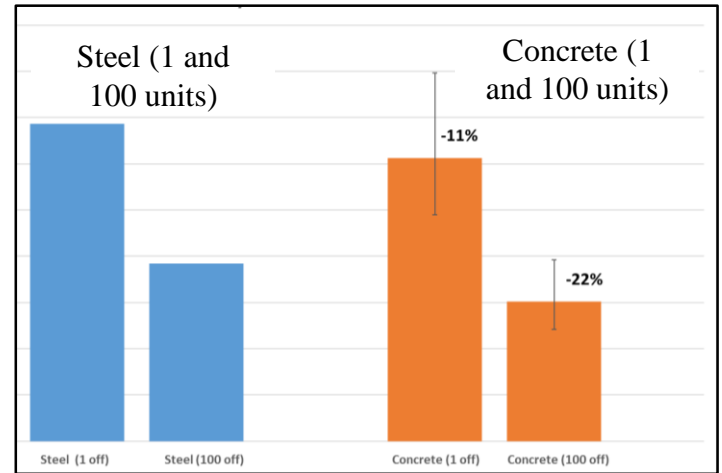
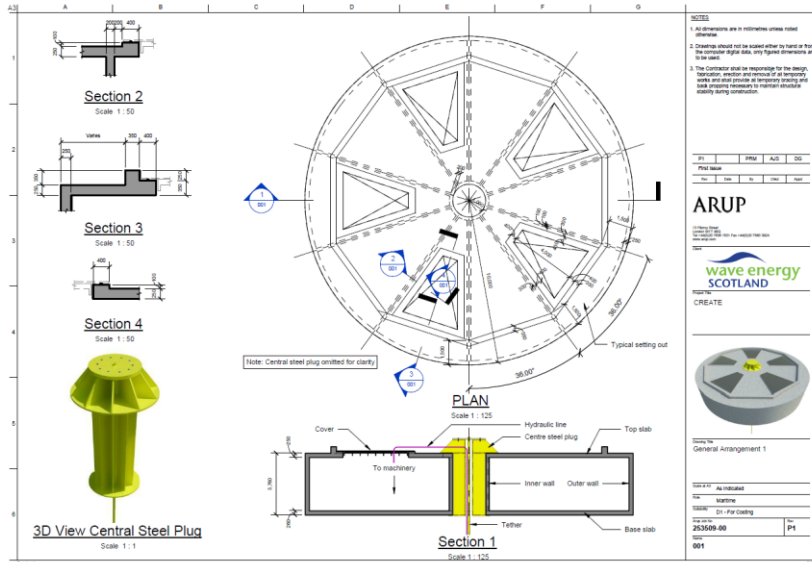
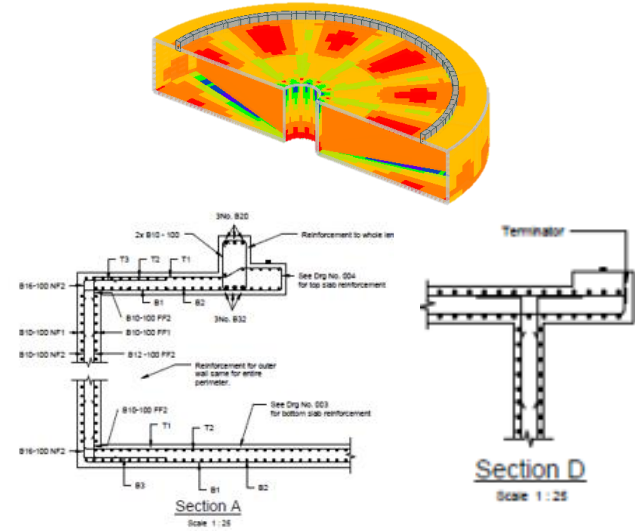
Stage 1 of the CREATE project (2017) took a **sector wide approach** to identify where concrete had potential for WEC structures and developed the **most promising option to a pre-FEED level** with potential for commercialisation.



CREATE Stage 1: Engineering Design Study



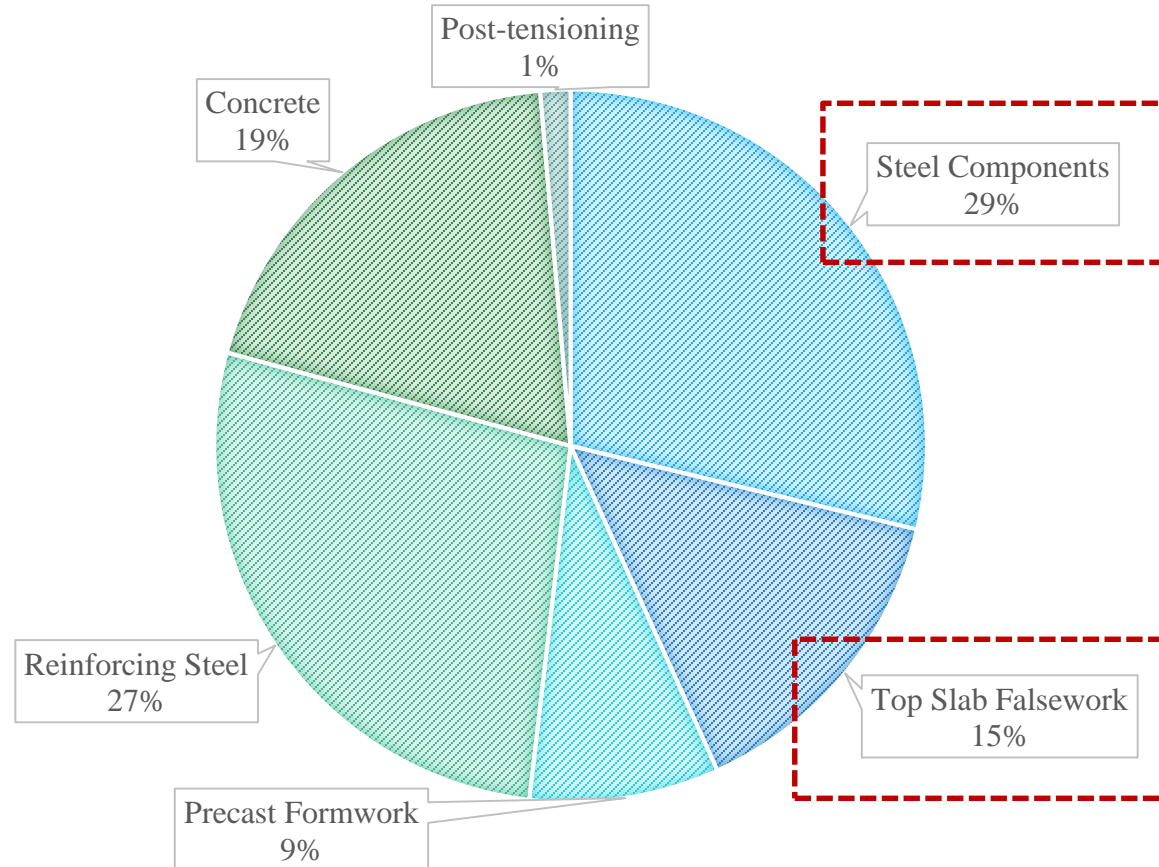
cruz atcherson
CONSULTING ENGINEERS



BA CAPEX Comparison

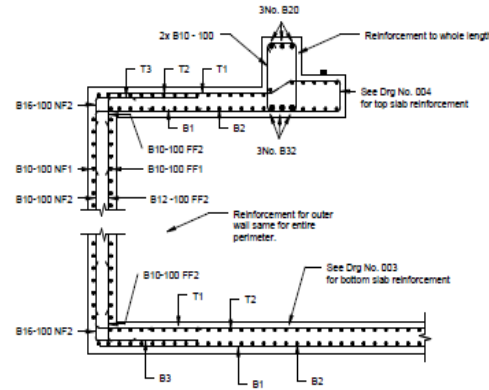
CREATE Stage 2: Cost and Risk Reduction

Stage 2 of the CREATE project aims to **mitigate key technical risks** identified in Stage 1 and provide confidence that **concrete can provide a step change in LCoE** for WECs.

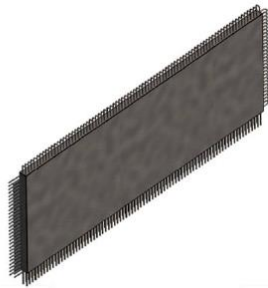


Carnegie Concrete CETO 6 BA: Cost Breakdown

CREATE Stage 2: Cost and Risk Reduction



Optimisation of Key Cost Centres



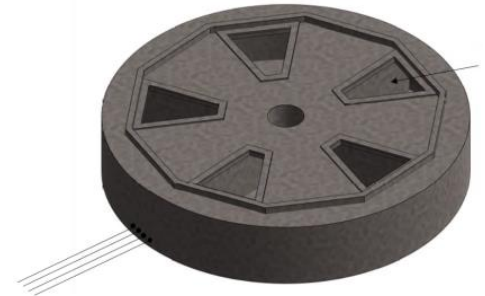
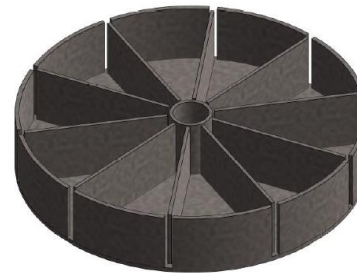
10 no. flat wall panels



10 no. curved panels



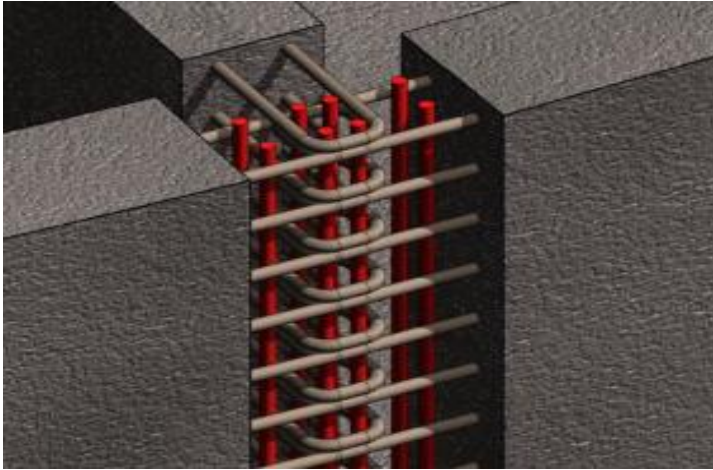
1 no. core



Design for Manufacture: Precast Concrete BA



CREATE Stage 2: Cost and Risk Reduction



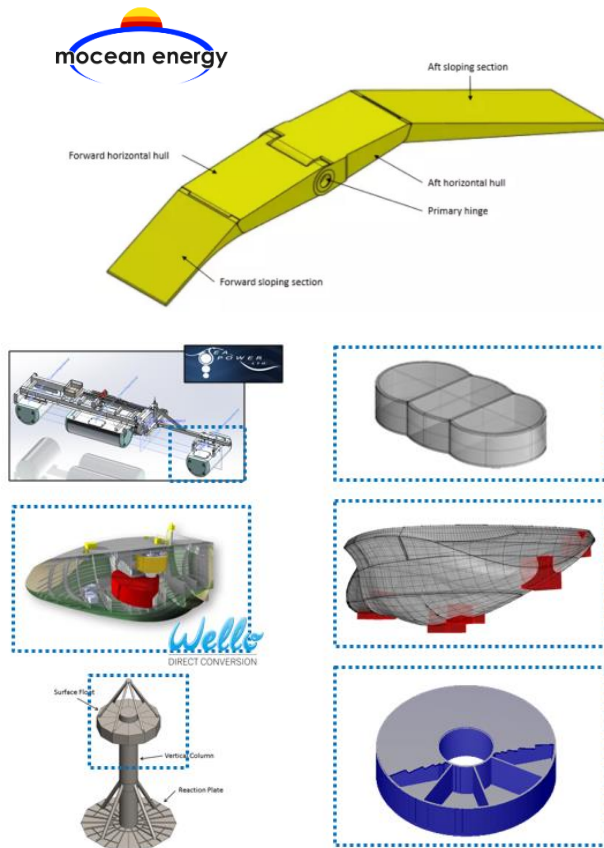
Precast Concrete Connection: Watertightness Testing



Independent Cost and Manufacturing Assessment

CREATE Stage 2: Conclusions

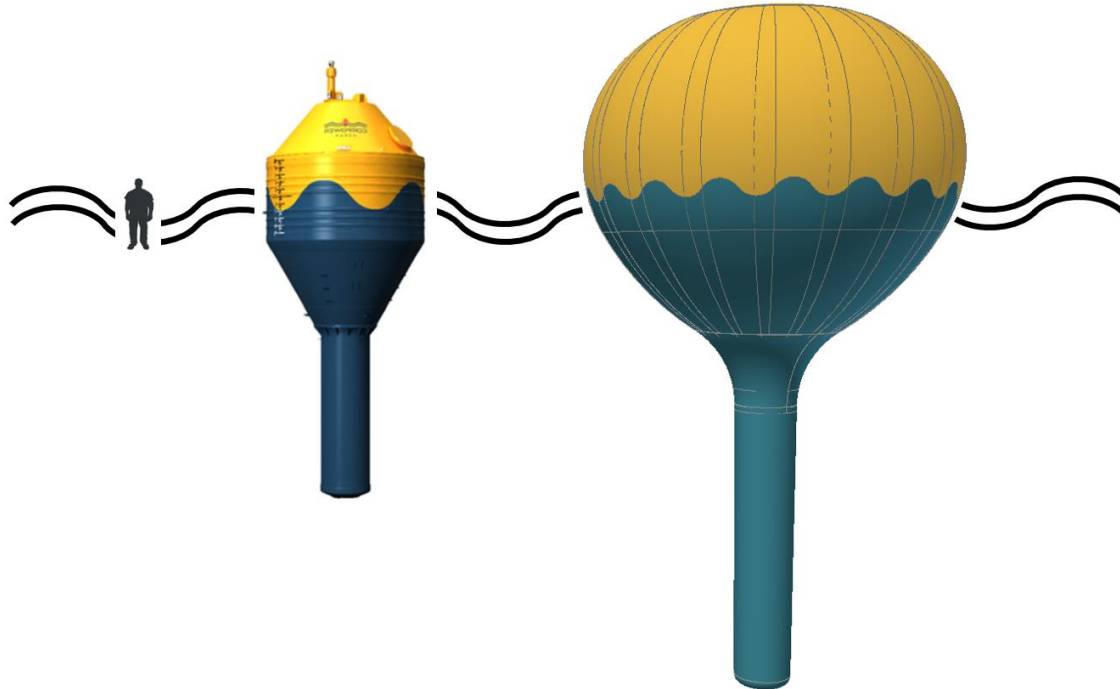
Stage 2 of the CREATE project aims to **mitigate key technical risks** identified in Stage 1 and provide confidence that **concrete can provide a step change in LCoE** for WECs.



Demonstration of the Versatility of Concrete for WECs

Low Cost, High TRL Solution Ready for Detailed Design

HydroComp Stage 2 - SMMP

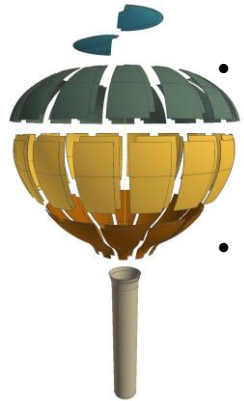


HydroComp Stage 2 - SMMP

Project Summary

Stage 2 Aim - Successful demonstration of the HydroComp Stage 1 solution through material testing and techno-economic performance assessment

Stage 1 Hull



- Hull Design
- Panel-only
- Material
- GRP composite

Design Refinement

Practical Testing

Stage 2 Hull

- Hull Design
- Thinner panels + internal frame
- Material
- HE-Glass

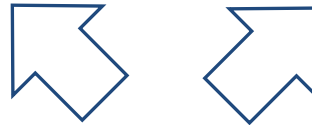


HydroComp Stage 2 - SMMP

Challenges

Performance

- Minimise panel deflection
- Reduce drag
- Increase buoyancy
- Computational Assessment



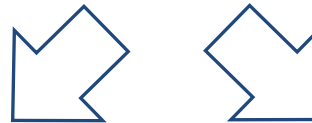
Hull

Affordability

- Material cost
- Ease of assembly
- Supply-chain logistics
- Transportation

Availability




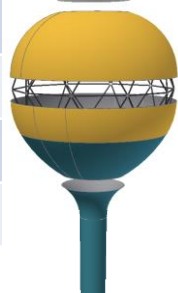

- Maintenance access
- Repair of damaged hull sections
- Hull maintenance



Survivability

- Material performance
- Bond performance
- Exposure to marine environment
- 20 year life expectancy

HydroComp Stage 2 - SMMP

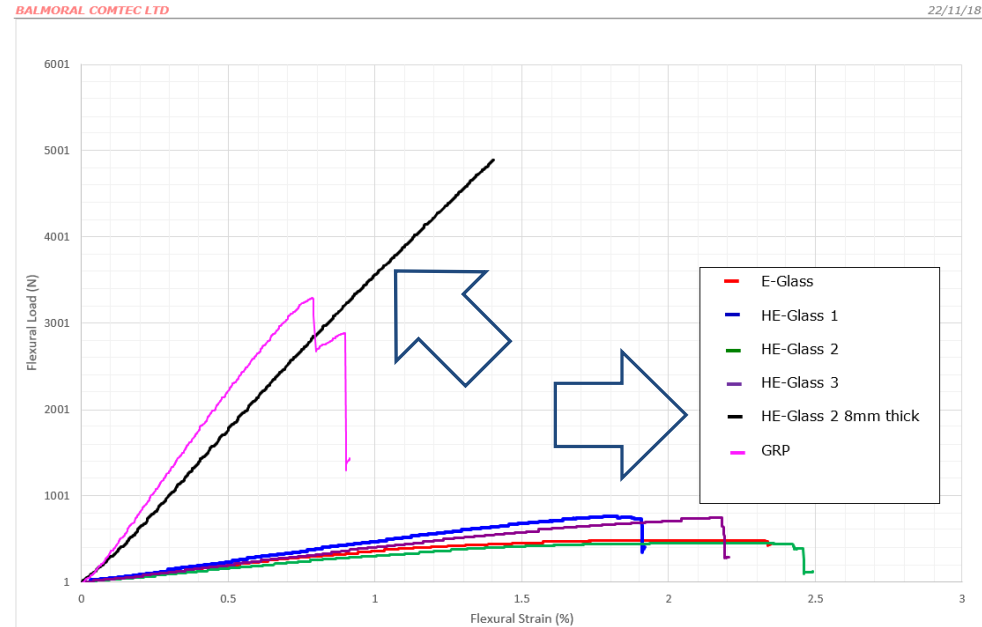
	Configuration options					
	Panels			Wound		
	Panels-only	Panels + sub-frame		Parts	One-piece	
	Reinforced	Constant thickness				
	(achieved via thin panels + thicker panels)	Minimal sub-frame	Substantial sub-frame	inc. sub-frame	inc. sub-frame	
Performance						
Manufacture						
Assembly						
Logistics						

HydroComp Stage 2 - SMMP

Material Change

HE-Glass 2

- HE-Glass 2 optimises ply weight and resin percentage for HydroComp Project
- 8mm. thick HE-Glass 2 (compared against 10mm. thick GRP material from Stage 1)
- Manufacturing costs of panels for GRP are significantly higher than HE-Glass

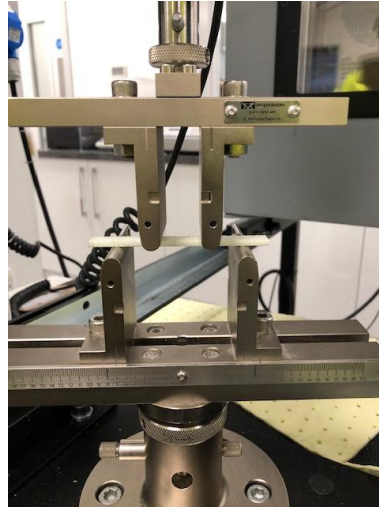


HydroComp Stage 2 - SMMP

Technical Testing

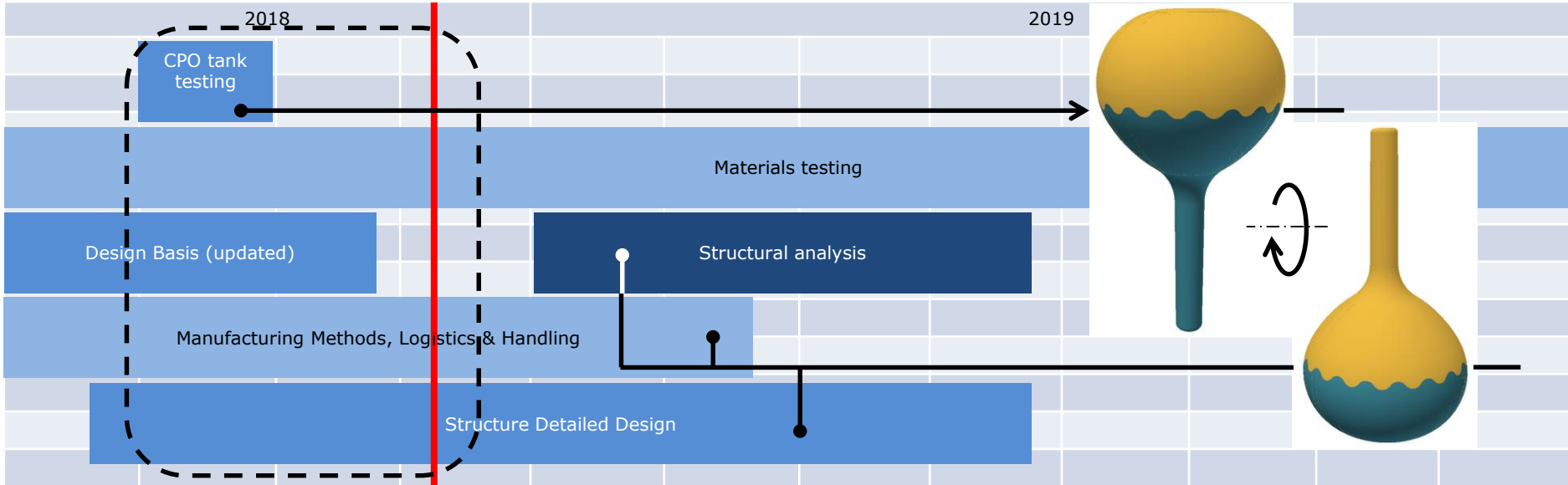
HE-Glass

- Material Performance
 - 4-point bend
 - Tensile
- Bond Performance
 - 4-point bend
 - Tensile
- Exposure to marine environment
 - Weathering testing

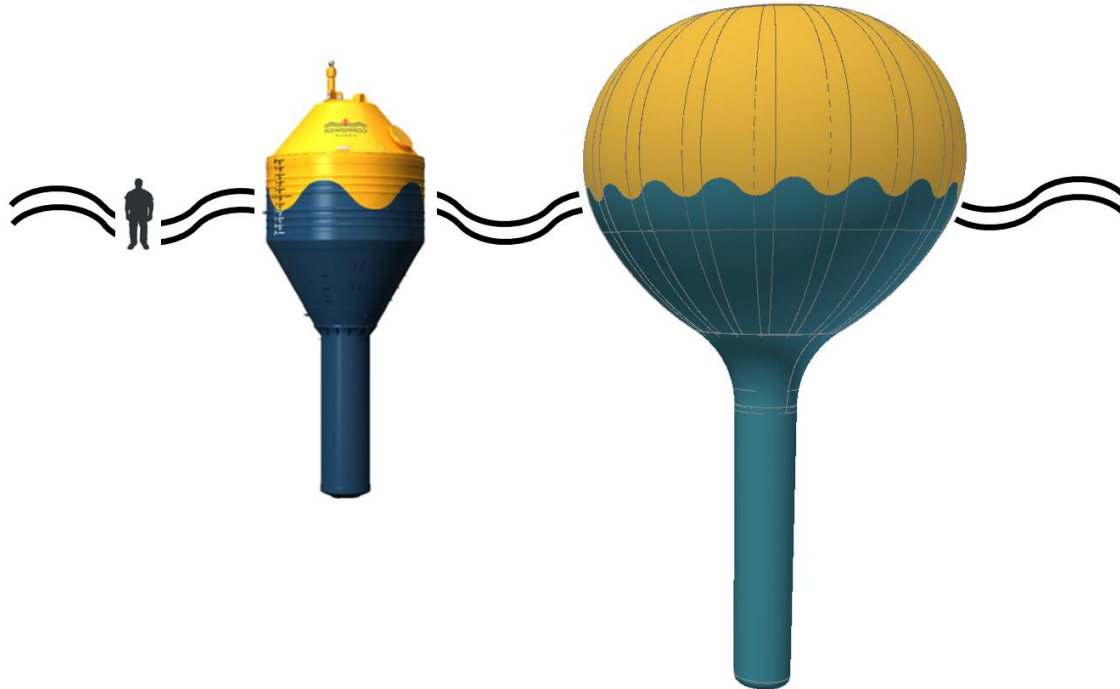


HydroComp Stage 2 - SMMP

Project timeline



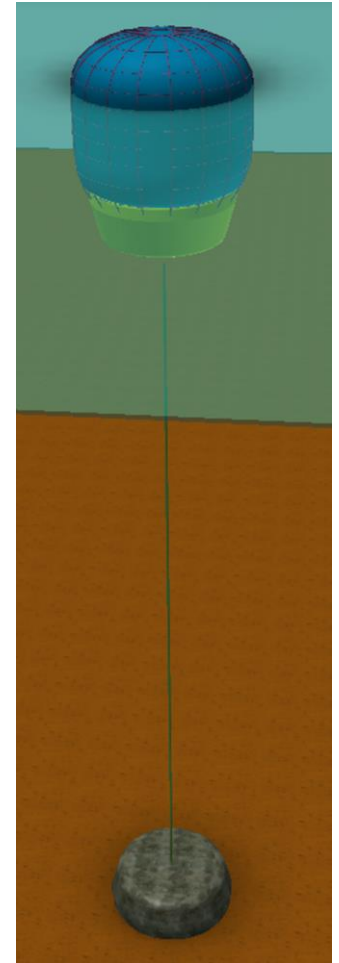
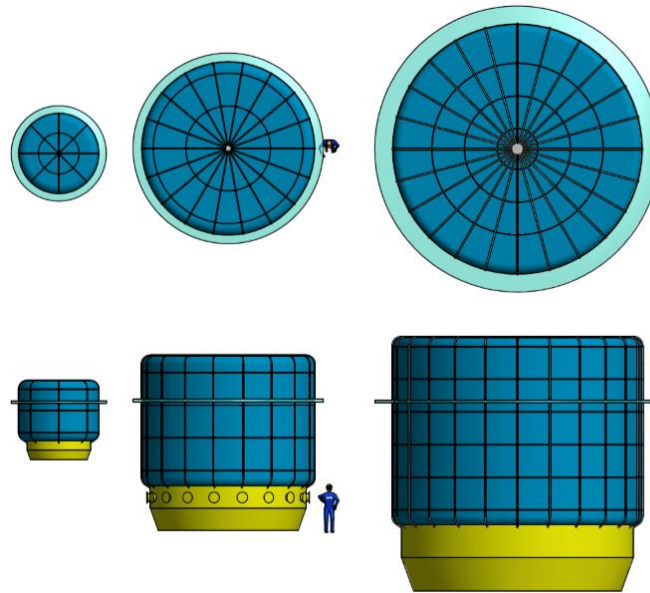
HydroComp Stage 2 - SMMP





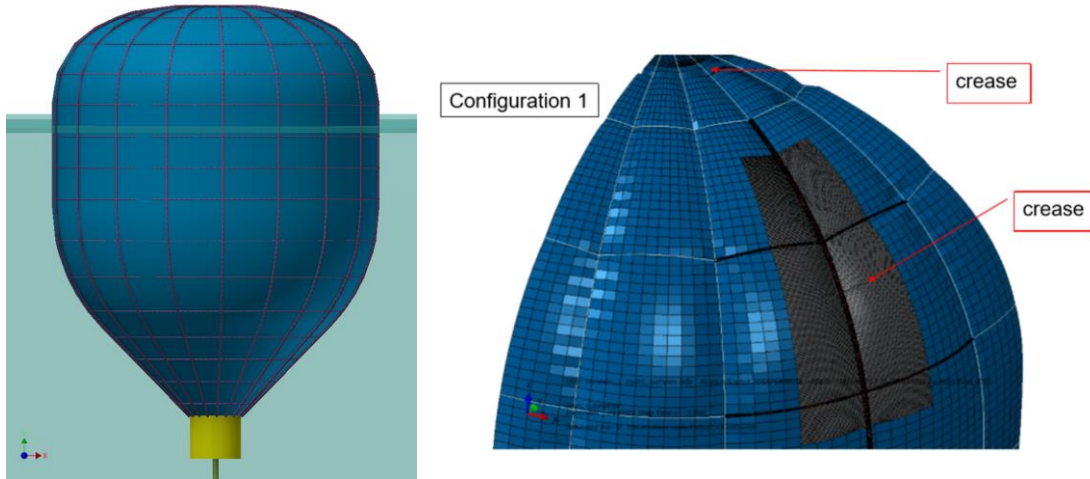
TTI NETBUOY STAGE 2 PROJECT

Lead Contractor:
Tension Technology International Ltd, Inverness





TTI NETBUOY STAGE 1 update

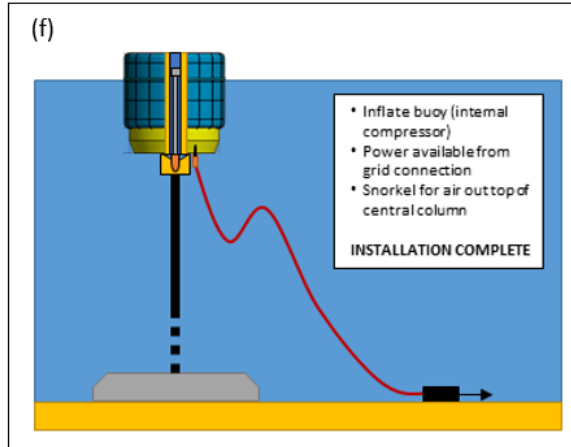
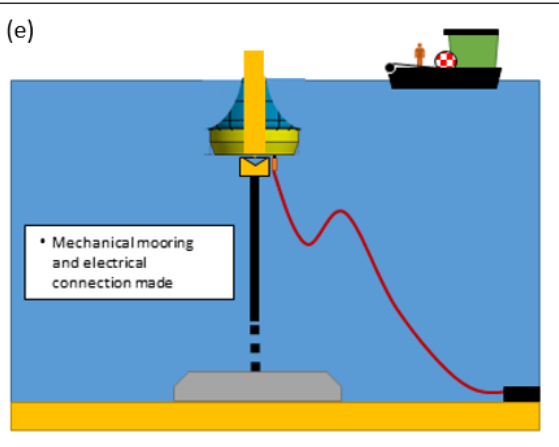


Completed concept design engineering. Including

- Material Selection
- Non-linear FEA
- Orcaflex net-modelling
- Manufacturing assessment

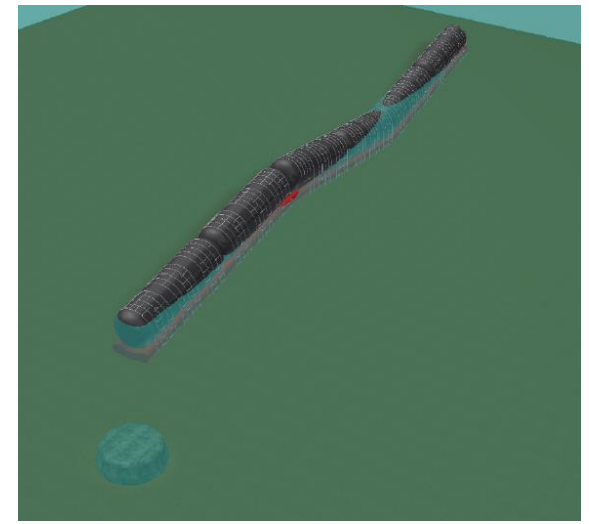
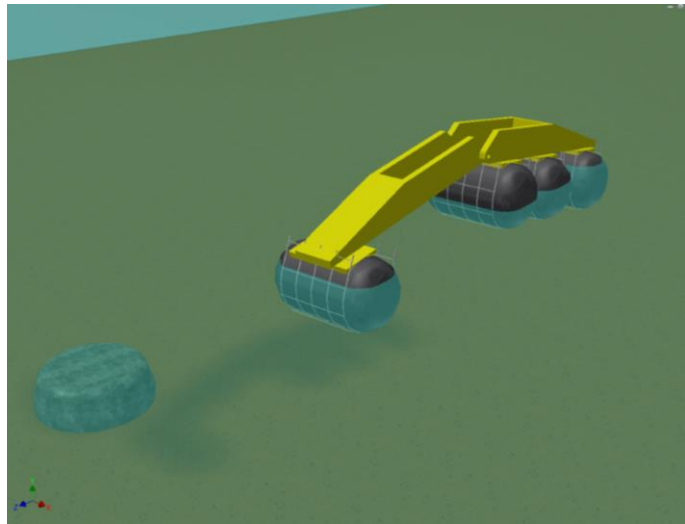
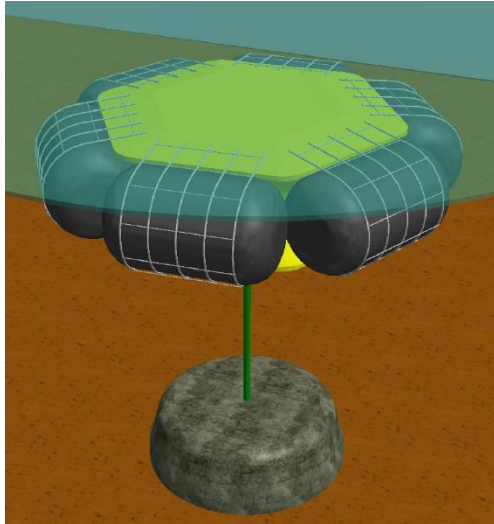
Benchmarking Netbuoy with Steel based point absorber

- Impact on LCOE
- Marine transportation & installation studies





TTI NETBUOY STAGE 1 update

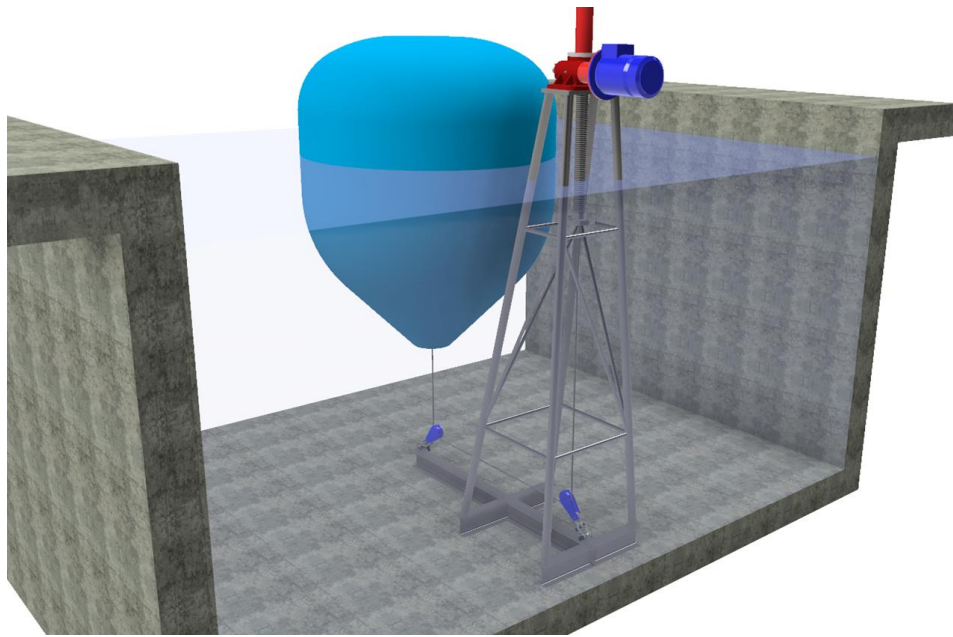


Applicability of Netbuoy technology to other WEC categories

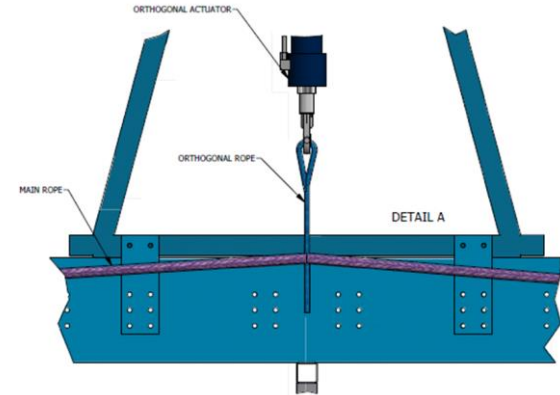


TTI NETBUOY STAGE 2 -Tests

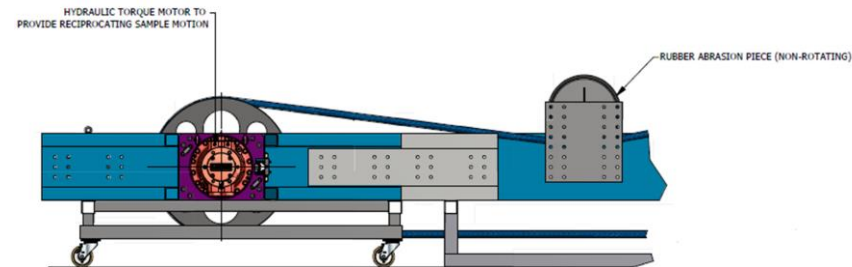
Examples of proposed technology qualification tests
(Ref: DNVGL-RP-A203)



Scale full-system tank tests
(Hydrostatic & Dynamic)



Full-scale subsystem tests on net joints



Full-scale component net on buoy abrasion



TTI NETBUOY STAGE 2 -Tests

Thank you
For more information contact

Ben Yeats

yeats@tensiontech.com

Tom Mackay

mackay@tensiontech.com

WES Annual Conference 2018



Project Progress Updates: Novel Wave Energy Converter, Stage 2

File Contents

- 4cEngineering – ACER 2 [8 pages]
- AWS – Improved Archimedes Waveswing [10 pages]
- Checkmate – Anaconda [5 pages]
- Mocean – Mocean WEC [6 pages]

4c Engineering

ACER 2 Overview

Andy Hall, Director
4c Engineering



ACER 2 Project Overview

- Where did this project begin?
- What did we do?
- Where are we going?

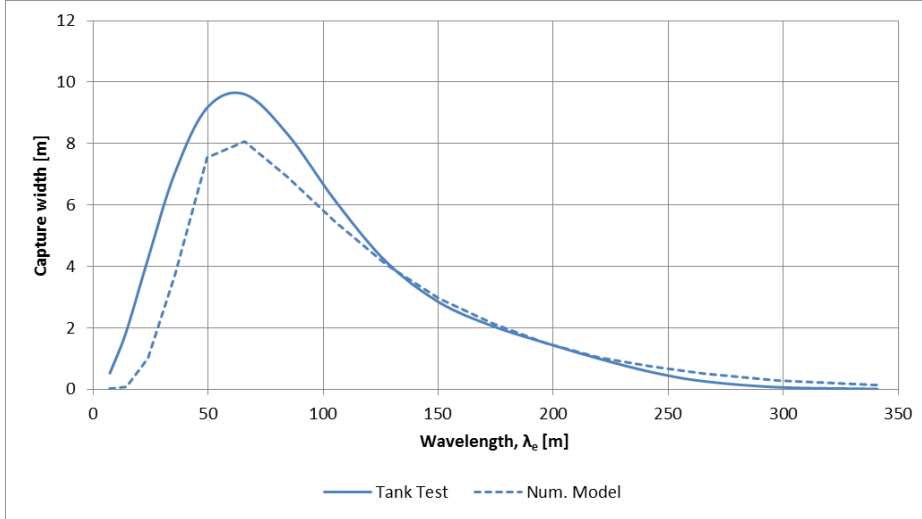
ACER 2 Project Overview



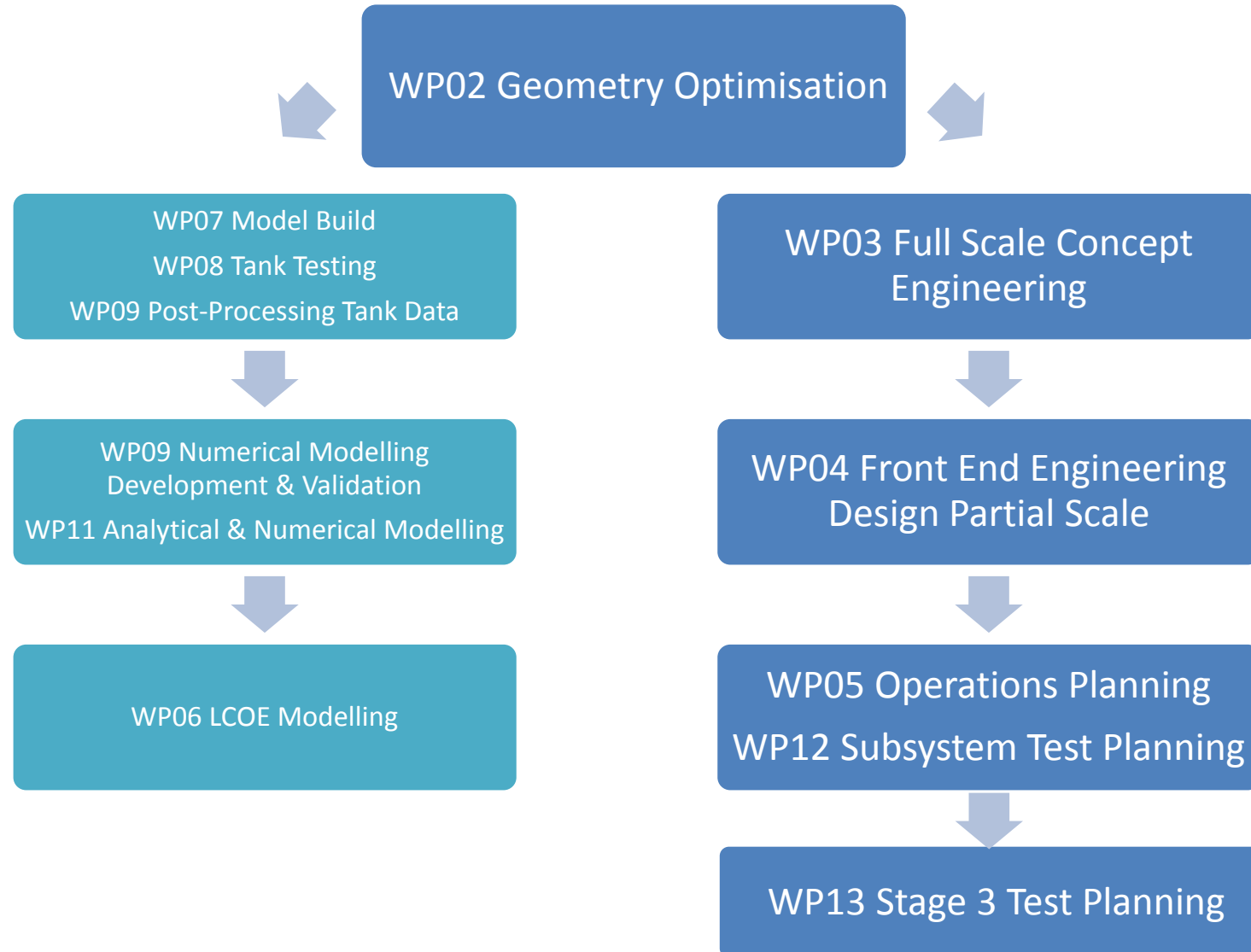
- Findings from ACER 1
 - Geometry needed to change
 - Structural CAPEX (pontoons/chassis) too high
 - Opportunity for greater optimisation at target sites

- Aims for ACER 2

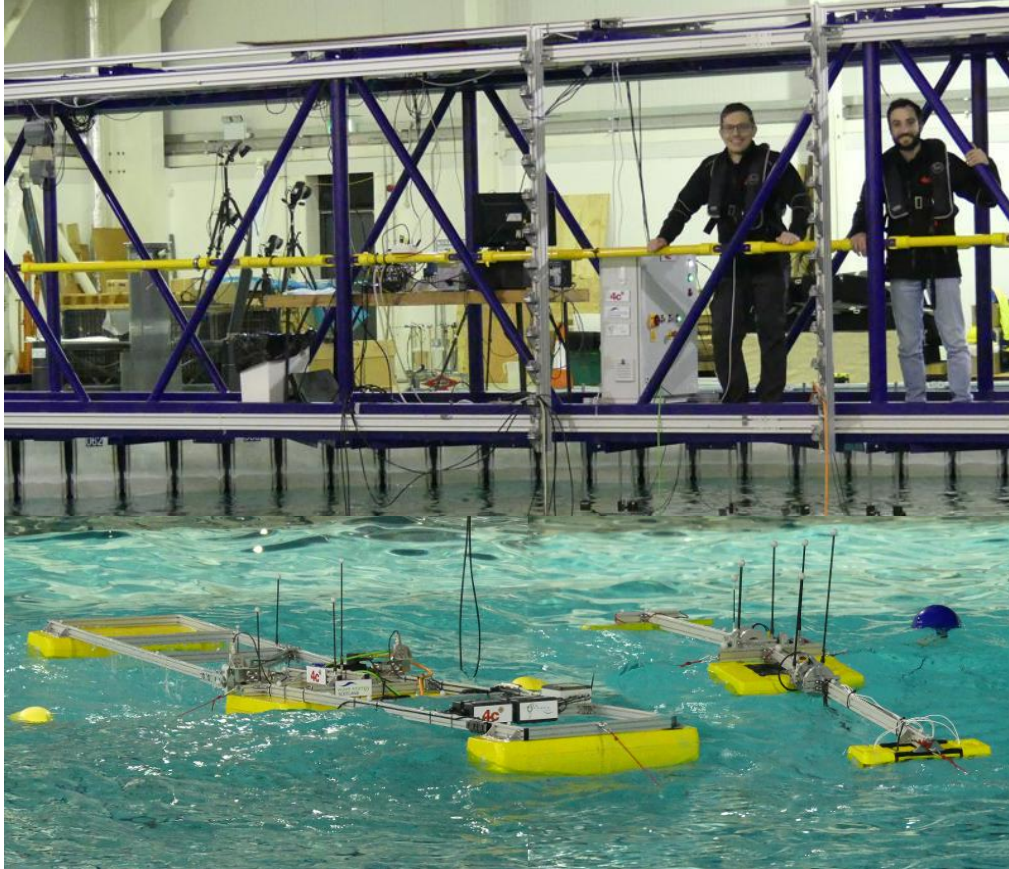
- Optimise geometry & reduce CAPEX
- Continue excellent international collaboration
- Develop in-house numerical modelling



ACER 2 Project Overview



ACER 2 Project Overview



- 2 x Successful tank test campaigns at FloWave
 - 1:25 Performance
 - 1:50 Loading Characterisation
- Measurements of:
 - Power capture
 - WEC motion
 - Hull pressure
 - Impulse pressures
 - Chassis moments
 - Mooring loads
 - Hinge loads
 - PTO torque

ACER 2 Project Overview

- Cost Targets

- CAPEX of pontoon reduced from 48% of total WEC CAPEX to 23%
- Path to LCOE <150 £/MWh still on track

- Performance Targets

$\frac{\textit{Capture Width}}{\textit{Displaced Mass}} \rightarrow \sim 40\% \text{ improvement from ACER 1}$

$\frac{\textit{Mean Annual Energy Production}}{\textit{Displaced Mass}} \rightarrow >220\% \text{ improvement from ACER 1}$

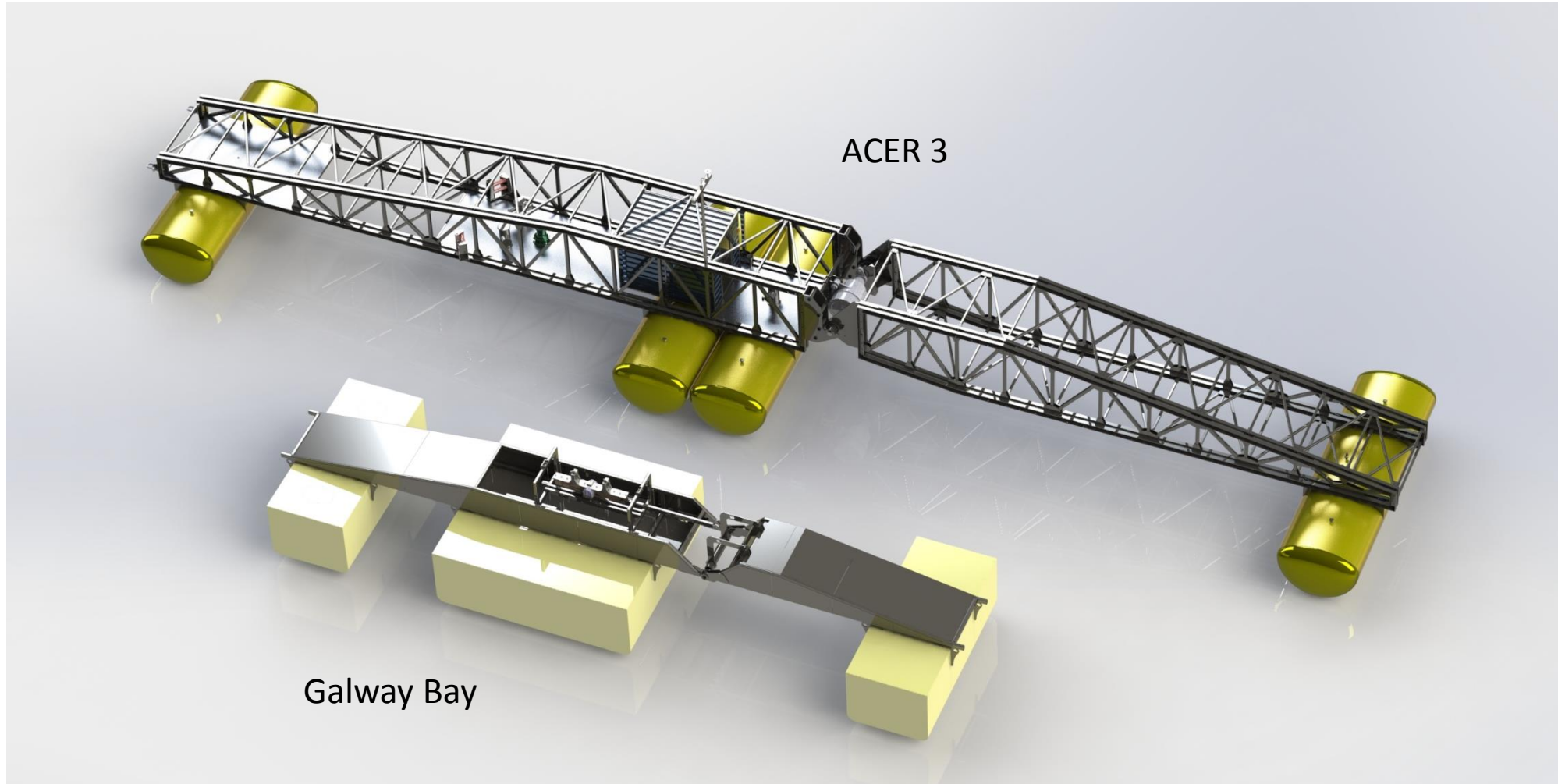
- Future Planning

- Storyboarding of construction, assembly & deployment activities
- Suite of operational plans produced for open water WEC
- Testing plans developed for WEC & subsystems to progress to TRL 6
- Supply chain visits

ACER 3 Project Overview

- ACER 3
 - Build on experience from ACER 2 & Sea Power's SmartBay (Galway) demonstrator
 - Planning & design of safe, successful open water WEC testing
 - 2 stage test campaign at EMEC throughout 2020
 - Scapa Flow shake down tests & build operational experience
 - Billia Croo deployment for real sea learning
 - Full scale concept development & commercial activities

WEC development Galway Bay → ACER 3



AWS Ocean Energy Ltd

WES Annual Conference 2018

Simon Grey



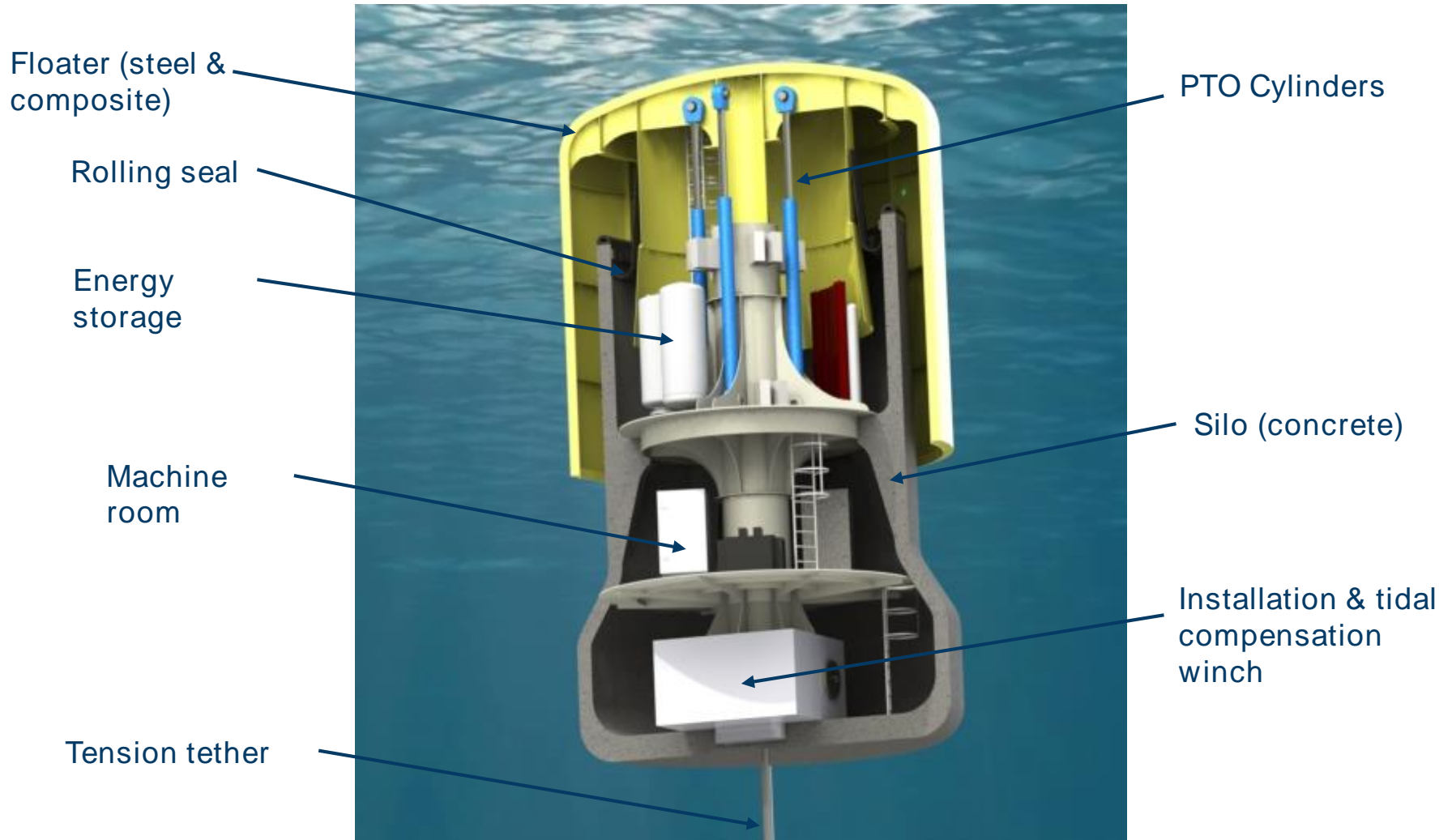
Stage 2 project outcomes



- > 3X increase in performance
- Full validation of numerical performance model
- Feasible full-scale solutions identified for all sub-systems
- Further structural and cost optimisation
- Full technical risk analysis to set basis for the technology qualification programme
- FEED completed for half-scale at-sea technology demonstrator
- Marine operations for deployment and recovery developed and confirmed as safe and practical by third-party experts
- Stage 3 project fully defined, costed and ready to start!



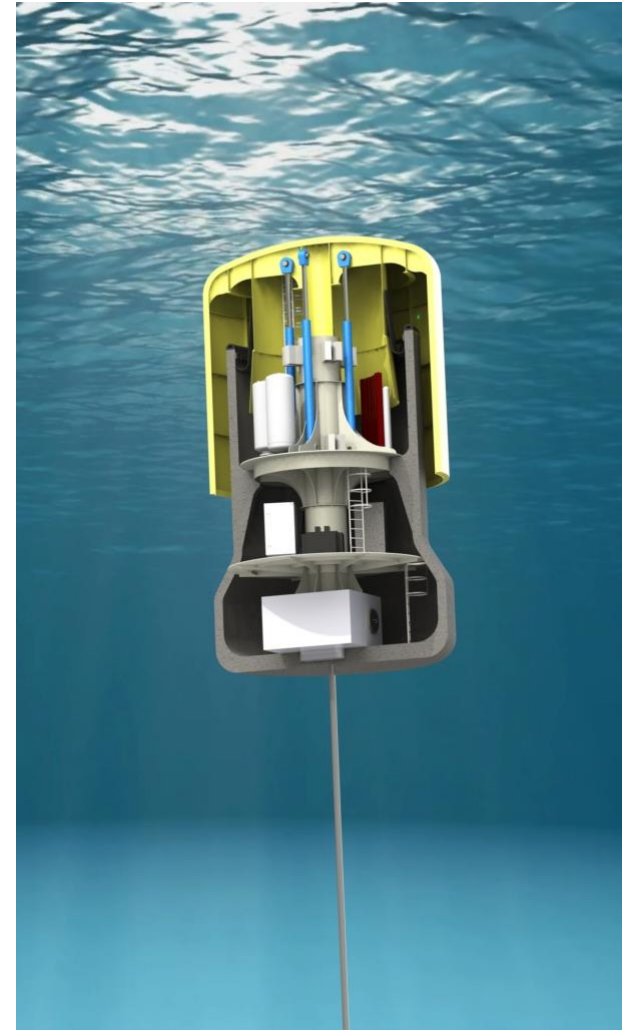
Waveswing explained



Current expected performance - commercial



- 250 kW rated continuous output
- 8.0m diameter floater with 3.0m stroke
 - ~ 55 ton of structural steel
- 832 MWh/year in 33kW/m achievable
 - Raw capture factor approaching 50%
 - 7.3 MWh mechanical energy per m³ of swept volume
 - 20 MWh / ton of structural steel
- FOAK demonstration project cost ~ £5.0 million
- Long term LCOE £150/MWh in 33kW/m
 - Or better in more energetic resource



Key lessons learned



- Theoretical power limit for Waveswing is 2X that for floating point-absorber
- Optimal control does not need future knowledge of wave
- High natural frequency of the absorber can be advantageous when using smart control
- Hydraulics provide the most cost-effective and capable PTO solution with all functional and performance requirements met
- Being subsea does not preclude rapid recovery and an effective maintenance strategy with high availability
- Achieving cost-competitiveness with offshore wind is possible with 1GW of installed capacity



Waveswing fundamentals



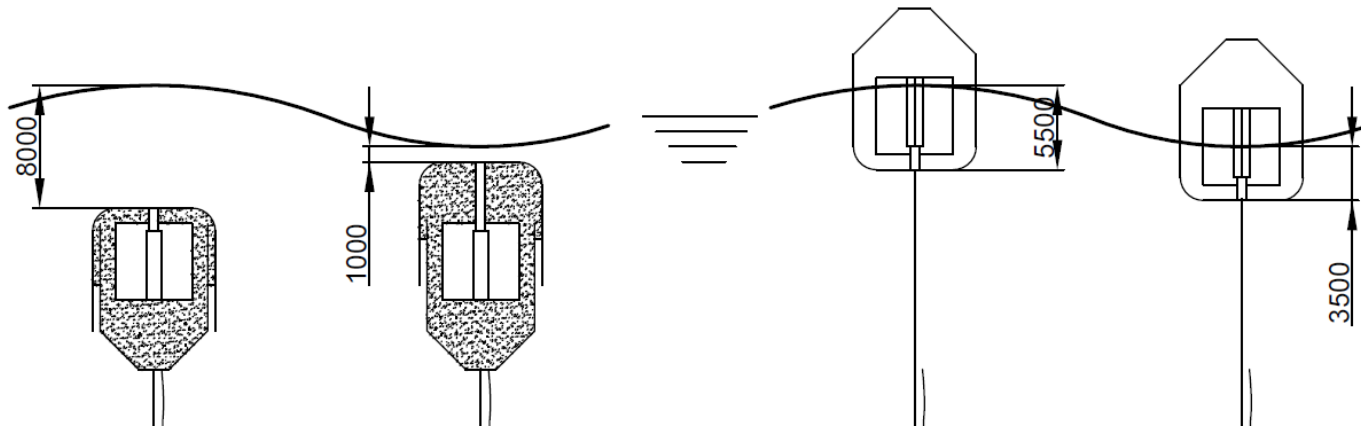
- Power per unit volume double surface-piercing devices

- Wave forcing from pressure – double the power of equivalent floating device

$$\text{Surface piercing: } P/V = \frac{\rho g \pi A}{2T}$$

- Waveswing amplitude of motion not constrained to half wave amplitude so limit doubles!

$$\text{Waveswing: } \frac{P}{V} = \frac{\rho g \pi A}{\cancel{2}T}$$



Technology advantages



- Potential for best in class LCOE due to fundamentals
- Can be scaled to 500kW for single device and combined on multi-MW platforms
- Survivability & safety – shut-down and hide from waves
- Zero visual impact – may be issue in early markets
- High power density (low use of real-estate)
- Low impact on fishing due to single-point moorings
- Self deploying – only requires tow to/from site with local vessels
- Major fabrications and marine ops can be local
- Key technology can be packaged for export (from Scotland)

Technology risk



- Key technical uncertainties that will affect the long-term viability of the technology:
 - Longevity of rolling seal
 - Performance of PTO
 - Effect of biofouling
 - Unforeseen deployment / recovery issues
 - Device loads and stability as volume is reduced
- Engineering risks – challenges to be overcome by good design
 - Durability and longevity of sensors in harsh environment
 - Functionality and reliability of survival systems
 - Functionality and reliability of internal pressure control
 - General system reliability and availability

Risk Identification								Baseline Risk Analysis (at point)			
Category	Risk	Date raised	Revision D	Risk Owner	Status	Risk	Cause	L'hood	Impact	Risk sol	Desc
Technical	51	22/02/2017	16/10/2018	AWS/SG	Open	Electrical / control / instrumentation hardware failure	Environmental conditions within Waveswing	3	4	12	Conc cons varyi hum
Technical	64	20/08/2018	16/10/2018	AWS/SG	Open	Excessive pitch motion following silo inundation as a result of vacuum seal failure	Air is lost from silo into vacuum chamber to equalise pressures, water then overtops silo until equilibrium re-established. Approx 40m3 which is 25% of device displacement.	4	3	12	tens main
Technical	66	20/08/2018	16/10/2018	AWS/SG	Open	Silo inundation	Combinations of environmental factors	3	4	12	The i as th deviv pres. cont. sion
Technical	74	20/08/2018	16/10/2018	AWS/SG	Open	Failure to enter survival mode	Failure of control systems, PTO, survival lock or pull down winch	3	4	12	The i float large Coul enhy
Technical	77	16/10/2018	16/10/2018	AWS/SG	Open	Failure to power survival systems (PTO pull down, winch pull down controls)	Loss of grid	3	4	12	Coul = br
Technical	78	16/10/2018	16/10/2018	AWS/SG	Open	Failure to control survival systems	Loss of comms to shore	3	4	12	Per c
Technical	69	20/08/2018	16/10/2018	AWS/SG	Open	Unintended release from survival mode	Malicious, inadvertent or spurious control action	2	5	10	Per c
Technical	57	22/02/2017	16/10/2018	AWS/SG	Open	Device cannot maintain continuous operation	Heat build-up due to inadequate cooling or other thermodynamic effects	3	3	9	Conf dissi man over
Technical	72	16/10/2018	16/10/2018	AWS/SG	Open	Premature seal failure	Inadequate design, manufacture or installation	3	3	9	Can : - ino - ino and - cha

Next steps

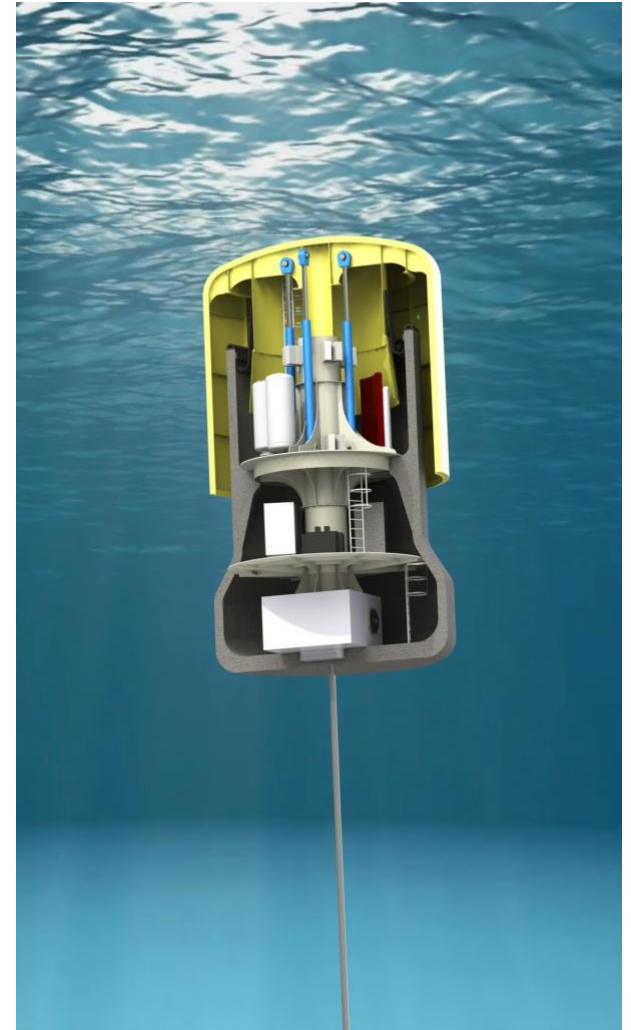


- WES NWECC 3 project to demonstrate and de-risk technology:
 - Half-scale prototype to be deployed at EMEC nursery site in 2020
 - Fully functional WEC containing all sub-systems as per full-scale design
 - Test and demonstrate PTO function
 - Test and demonstrate rolling seal
 - Test and demonstrate deployment / tidal compensation systems
 - Demonstrate and refine marine operations
 - Collect data for load and performance model validation
 - Gain experience ahead of design of FOAK

Summary



- Highly successful project delivering significant advancement of technology
- Best-in-class performance underpinned by fundamental physics
- Engineering of commercial system fully feasible
- Confident that remaining technology risks can be met in Stage 3
- Excellent team-work – thank you!
- Looking forward to Stage 3 demonstration and engaging with potential investors





ANACONDA MK2

SEA ENERGY ANACONDA
SHAPING THE FUTURE OF WAVE ENERGY

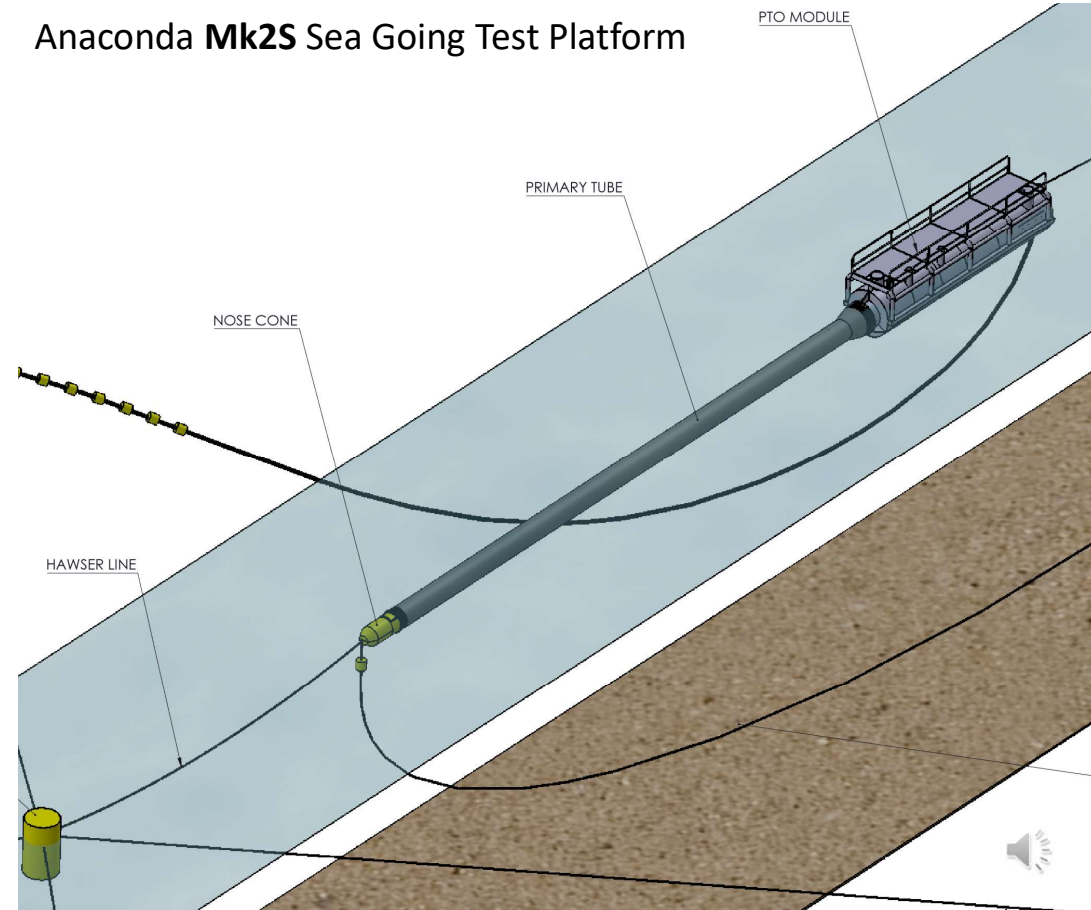




ANACONDA Mk2 - BREAKTHROUGH POTENTIAL

1. “Continuum” Absorber: independent of PTO
2. Self-referencing, based on flexible materials. Integrity independent of absorber structure
3. Operations: Low-draft, horizontal orientation
4. Unique Scaling with further “step change” learning opportunities

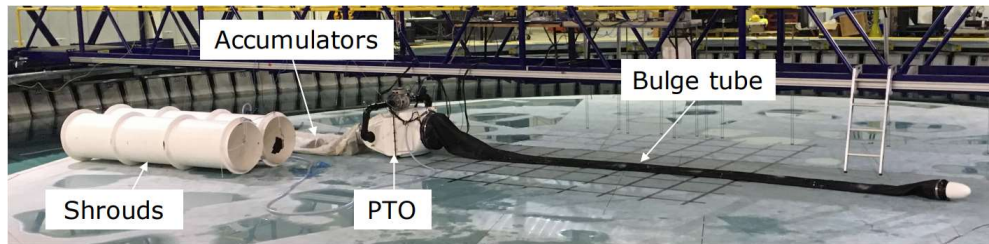
Anaconda **Mk2S** Sea Going Test Platform



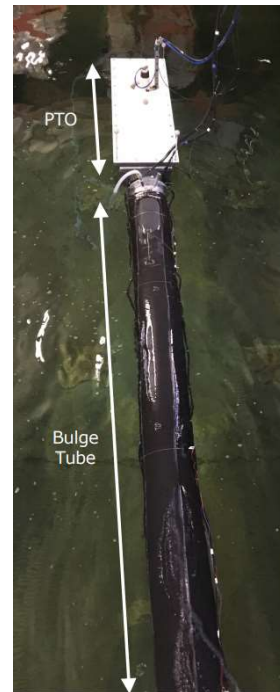


STAGE 2 DEVELOPMENTS

Concept Iteration Mk1 to Mk2



Mk1 Tests (Strathclyde, Flowave, Lir)

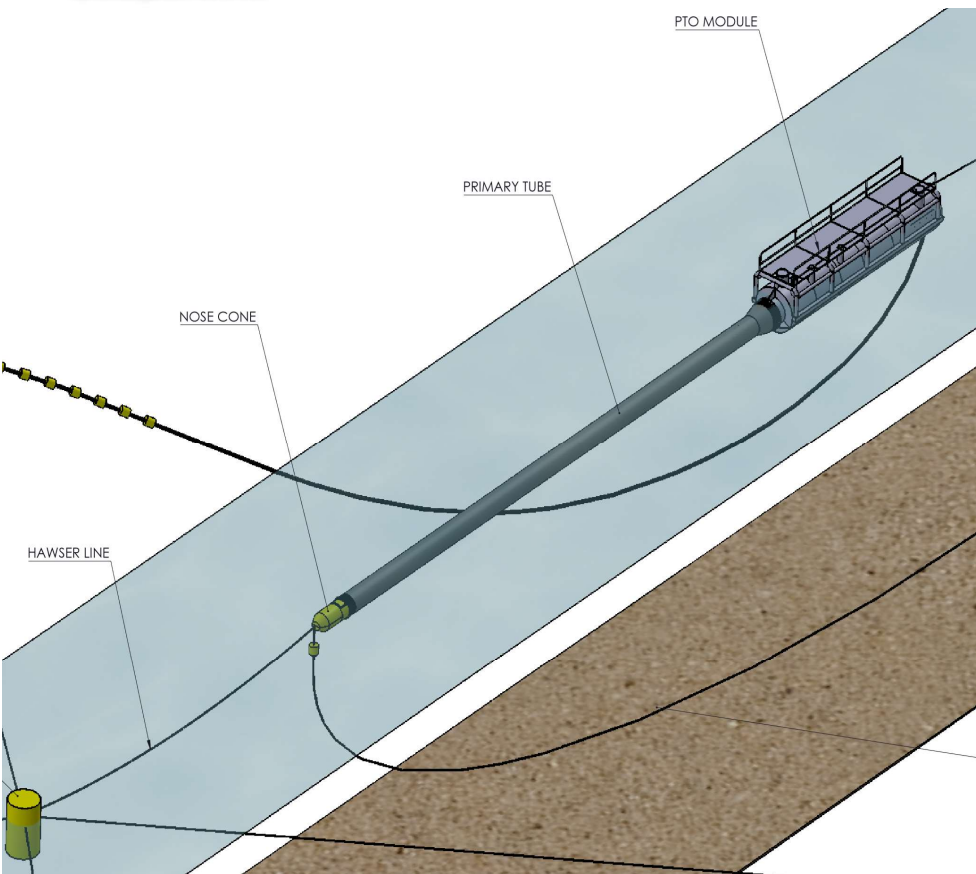


Mk2 Tests (Strathclyde, Lir)

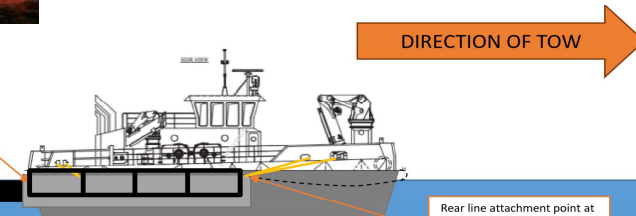




STAGE 3 PROPOSAL



Box frame around top of PTO hull provides reaction area for fenders / tyres and possible additional attachment points.



Rear line attachment point at top of PTO hull to permit access for disconnection / recovery





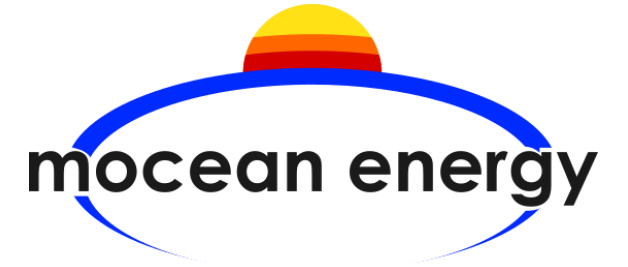
CONTACT Us

Thank You!

<http://www.checkmateukseaenergy.com/contact/>

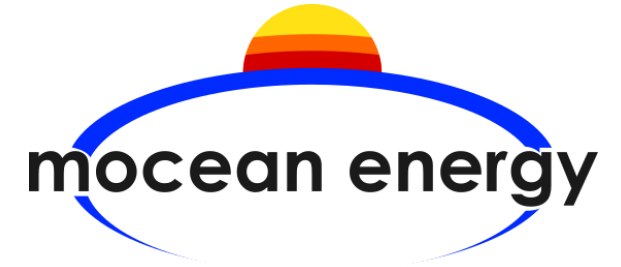


Mocean WEC: Next-level Hydrodynamics and Engineering

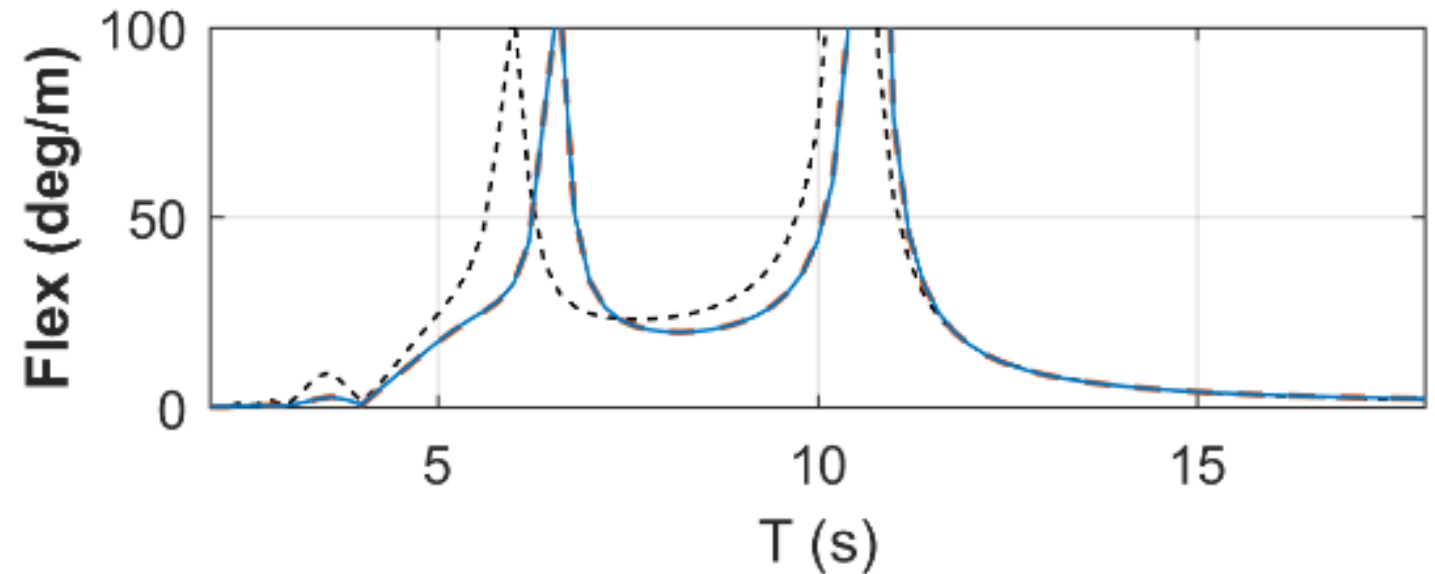


Performance

- Geometry induces high excitation force per unit mass
- DoF cross-coupling and wave channels broaden bandwidth – resonances at 2x and 5x WEC length
- Well-validated numerical model – further increases in performance expected

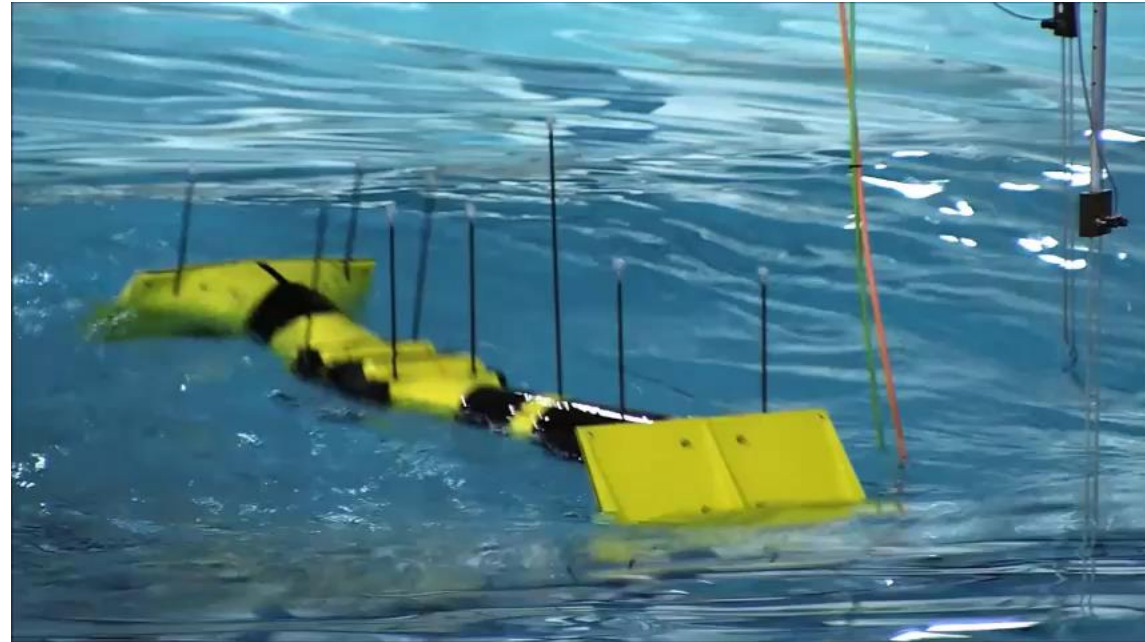
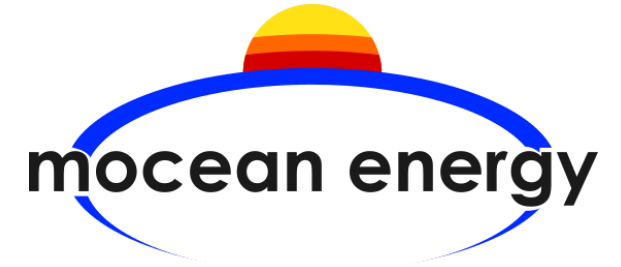


Undamped resonant response



Survival

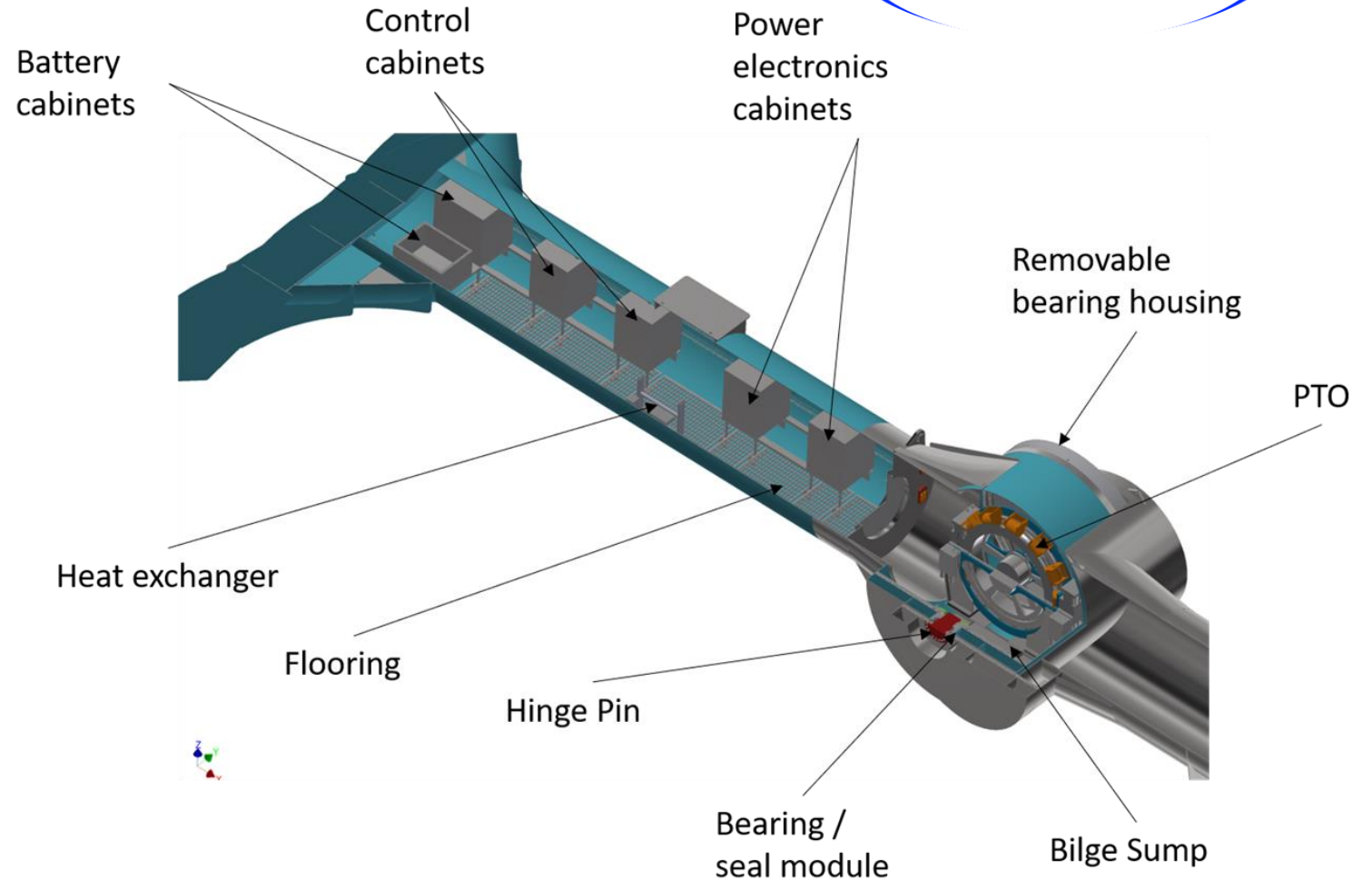
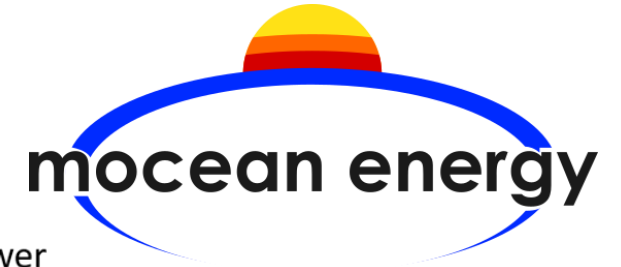
- Steep waves overtop the WEC
- Rotary PTO has infinite rotation
- Maximum hinge rotation (currently 90°) limited only by clash of hulls
- Damped compliant fender absorbs residual energy
- Unconditional roll stability
- No slam forces



Overtopping in steep waves

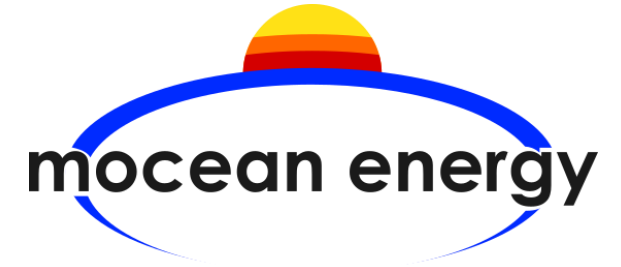
Reliability

- Single hinge, single DoF, integrated bearings & seals
- Non-contact magnetic gear
- All electric PTO, low parts count
- Redundancy from multiple generators
- WEC self-referenced, reduced mooring forces
- Sealed aft section – no cable transits

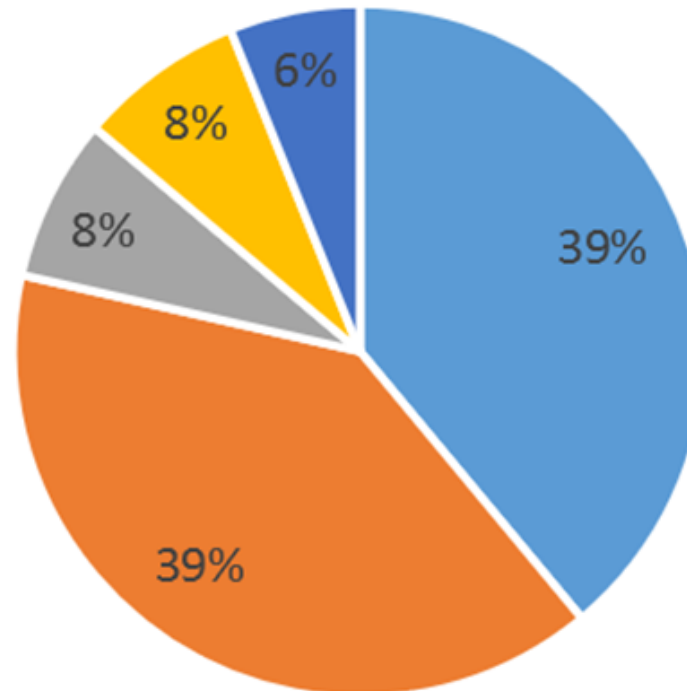


Affordability

- Bulk of cost is for structure and PTO (torque)
- 45% less structural mass per power than NWECC1
- 66% lower torque per power than NWECC1
- All-electric PTO will leverage advances in solar, wind and vehicle markets (batteries, power electronics, control)



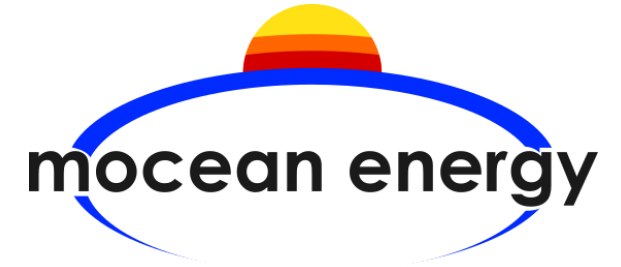
% Total CAPEX - This Project



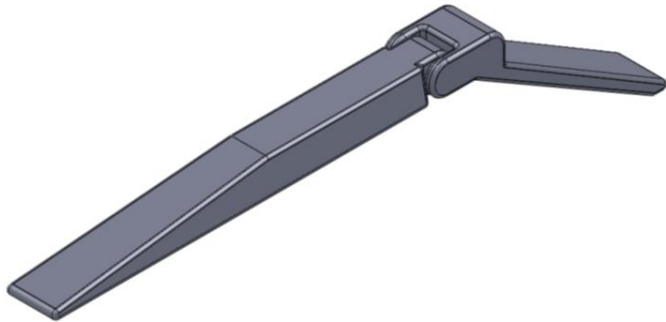
- Structure and prime mover (£k)
- Power Take-off & control (£k)
- Foundations and mooring (£k)
- Connection (£k)
- One-off installation (£k)

Mocean WEC Evolution

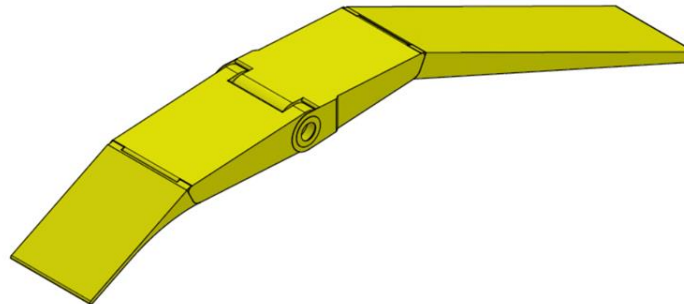
step-change improvements at each NWECC stage.



NWECC Application



NWECC Stage 1



Advanced geometrics in numerical optimisation
Identified issue with model validation
50% increase in mean power/mass

NWECC Stage 2



Added nonlinear spectral modelling.
Added torque cost to optimisation
Initial working model of wave channels
Reduced draft, improved manufacturability
Further 80% increase in mean power/mass
3x improvement in power/torque

WES Annual Conference 2018



Project Progress Updates: Power Take-Off, Stage 3

File Contents

- Artimus – Quantor Hybrid Hydraulic PTO [10 pages]
- Oceaneering – Power Electronic Controlled Magnetic Gear [5 pages]
- Umbra Group – Electro-Mechanical Reciprocating Generator [14 pages]
- University of Edinburgh – Project Neptune [12 pages]

Wave Energy Scotland Annual Conference, 8 December 2018

Elevator Pitches

Quantor hybrid hydraulic PTO – Stage 3

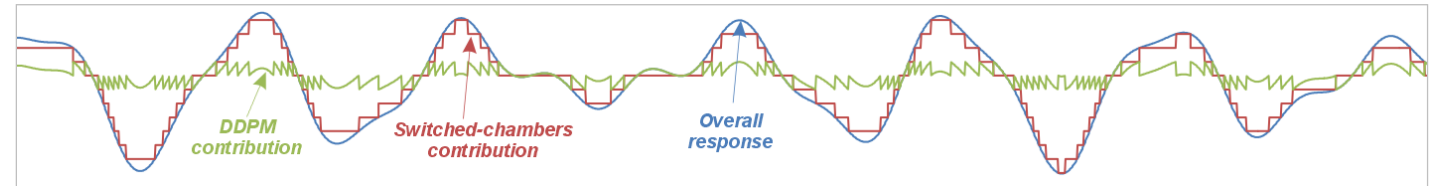
Lead Contractor: Artemis Intelligent Power



Sub-contractor: Quoceant



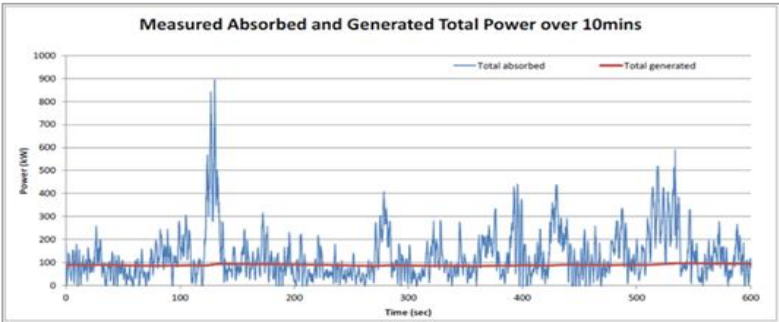
Presenter: Jamie Taylor, Artemis



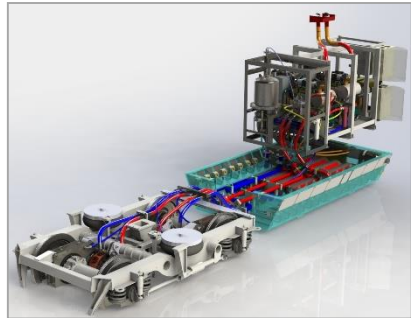
Quantor - Combination of 'Quantised' & Digital Displacement® (DD) systems



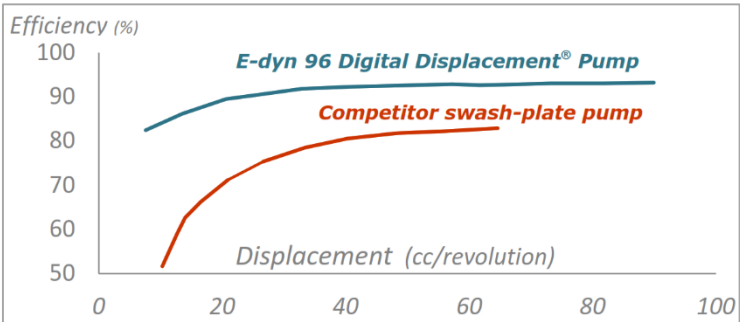
Pelamis with Quantised hydraulic PTO



Ocean-proven, high WEC to wire efficiency and steady power to grid.



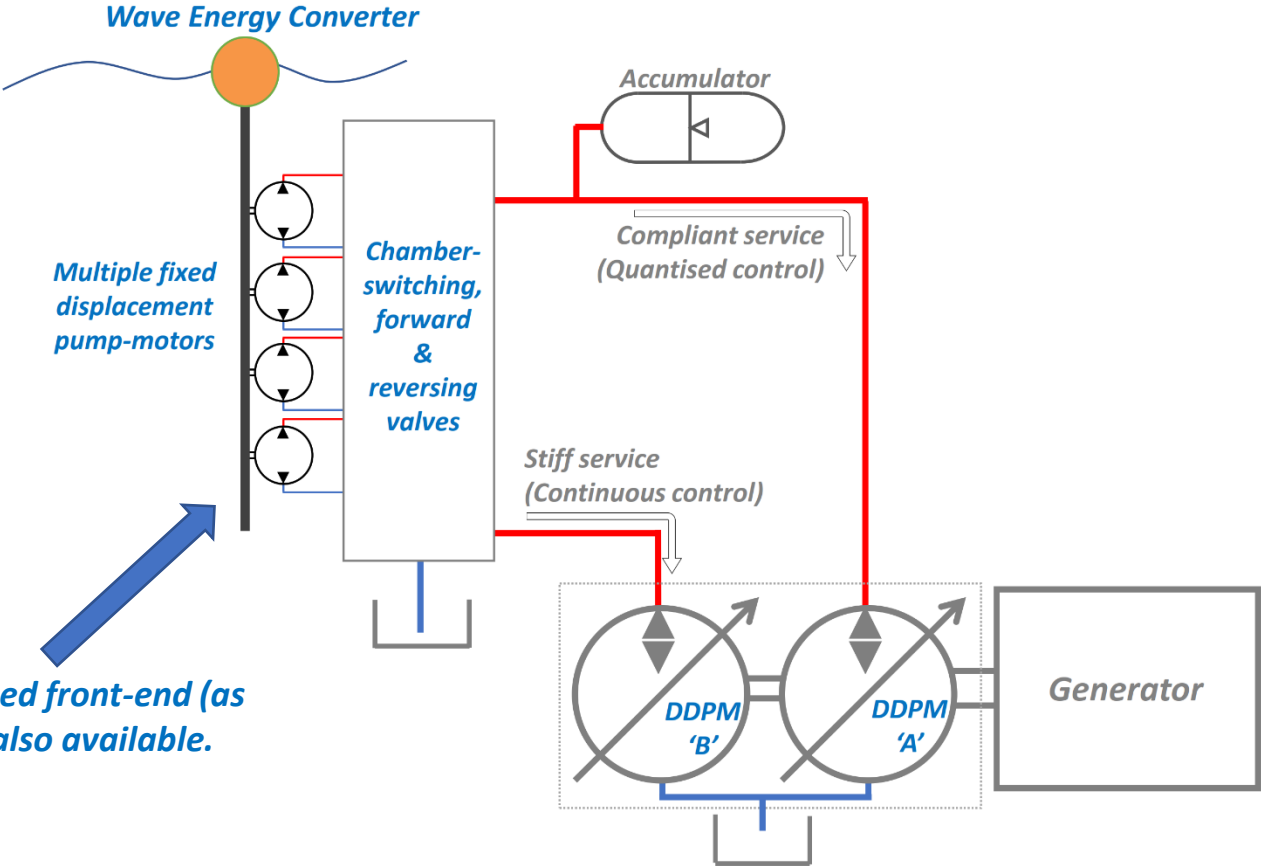
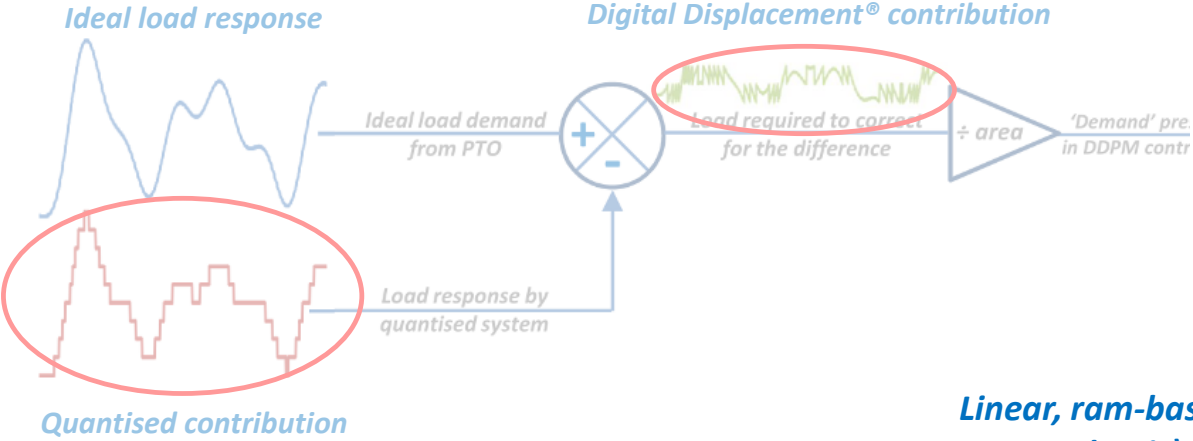
Rail vehicle with Digital Displacement hybrid drive



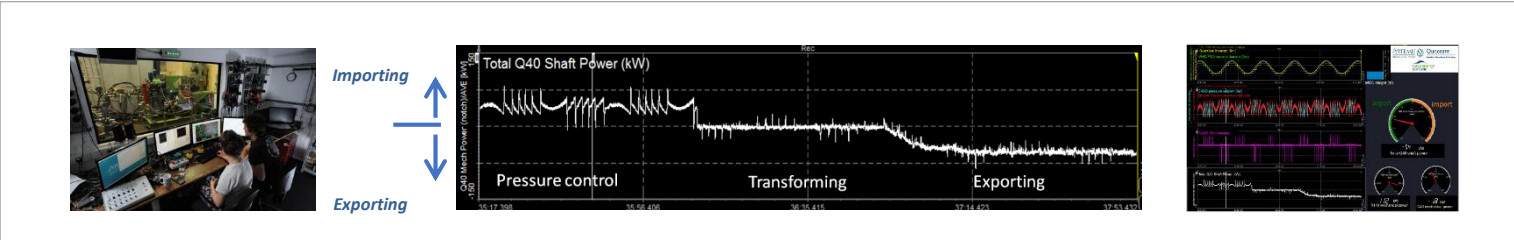
Generic hydraulic machines with high efficiency and controllability.

Quantor aim: improve hydrodynamic controllability of WEC and hence increase energy captured from it.

Quantor – How it works

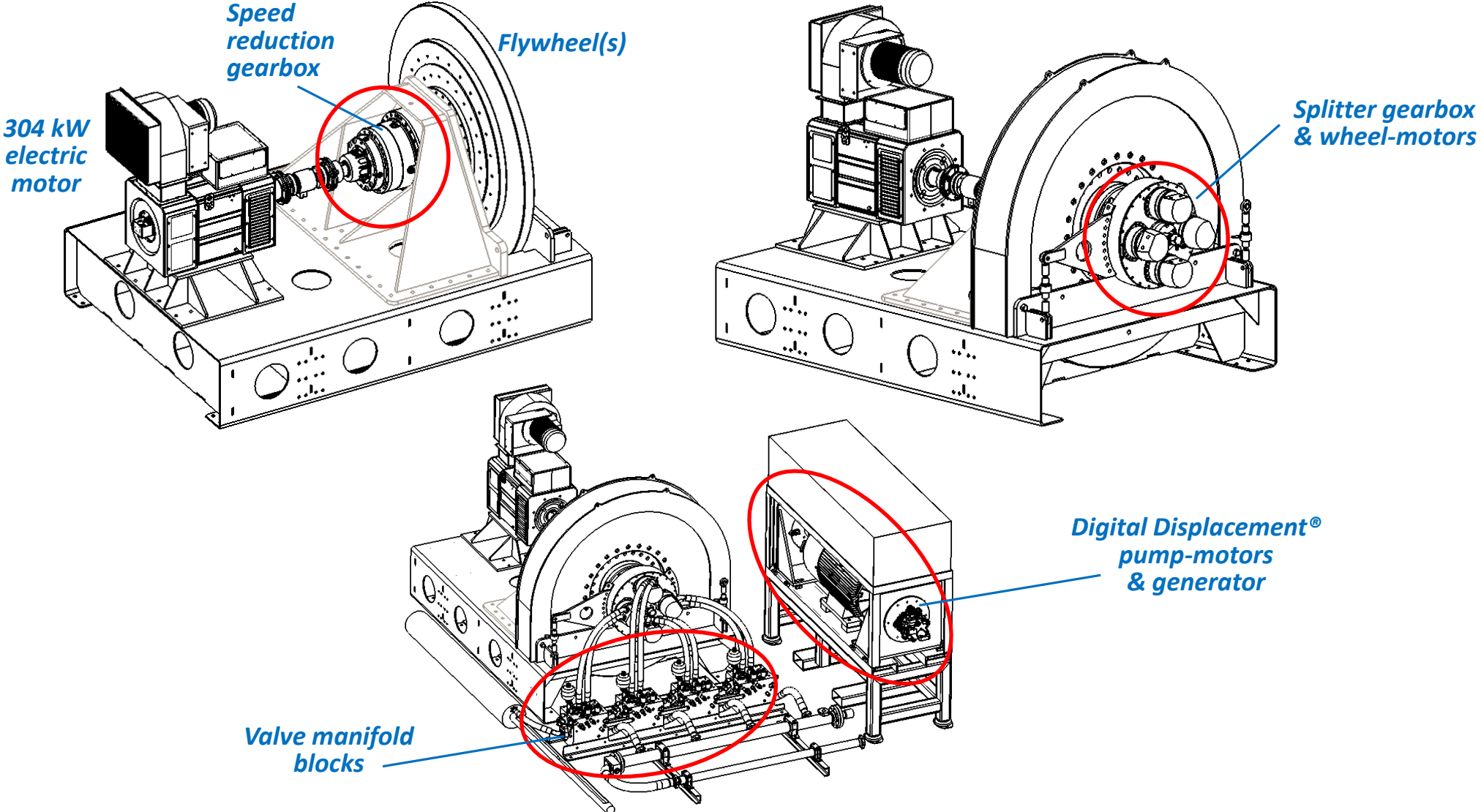


Linear, ram-based front-end (as per Pelamis) also available.

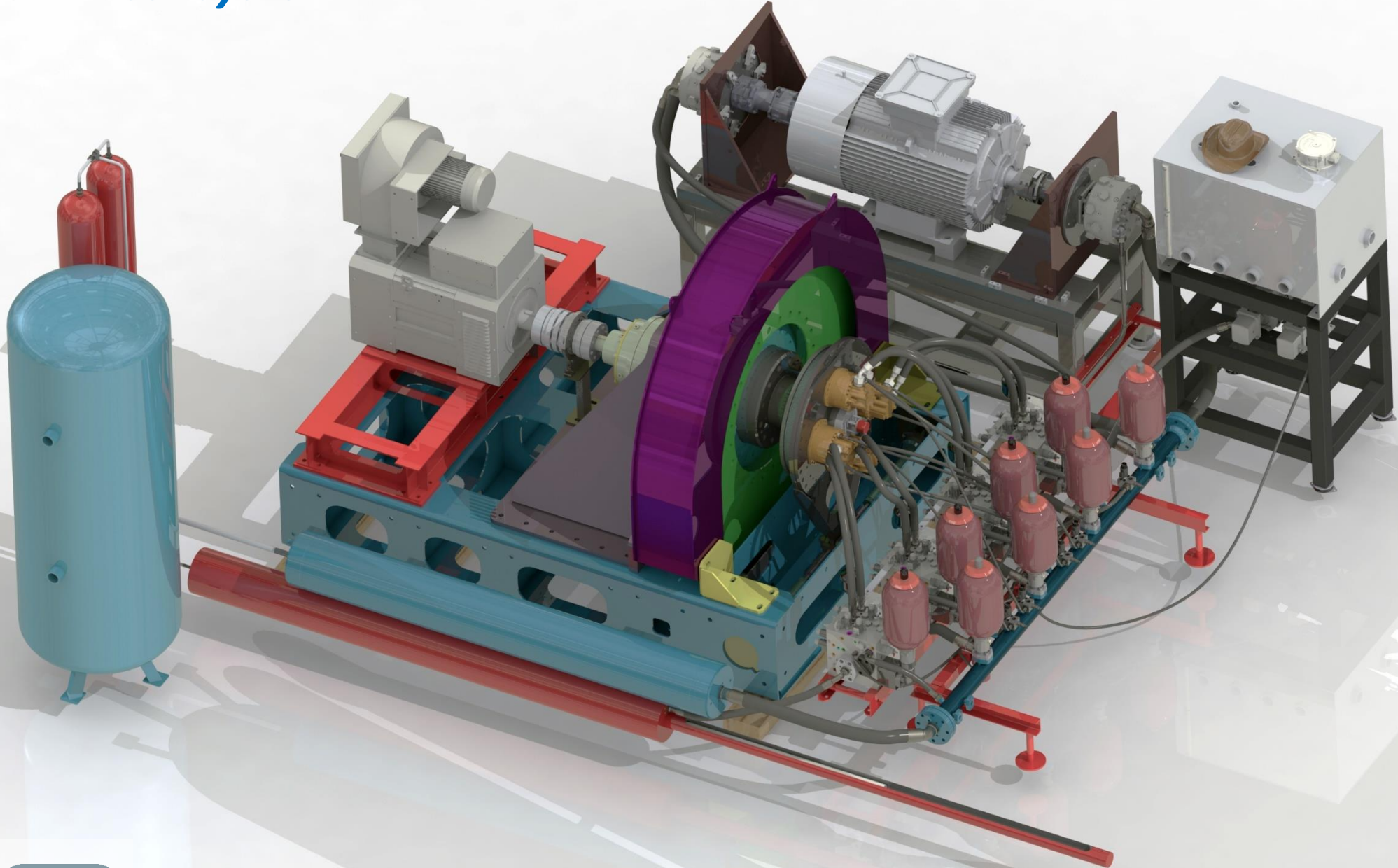


Stage 2 project demonstrated the technical feasibility

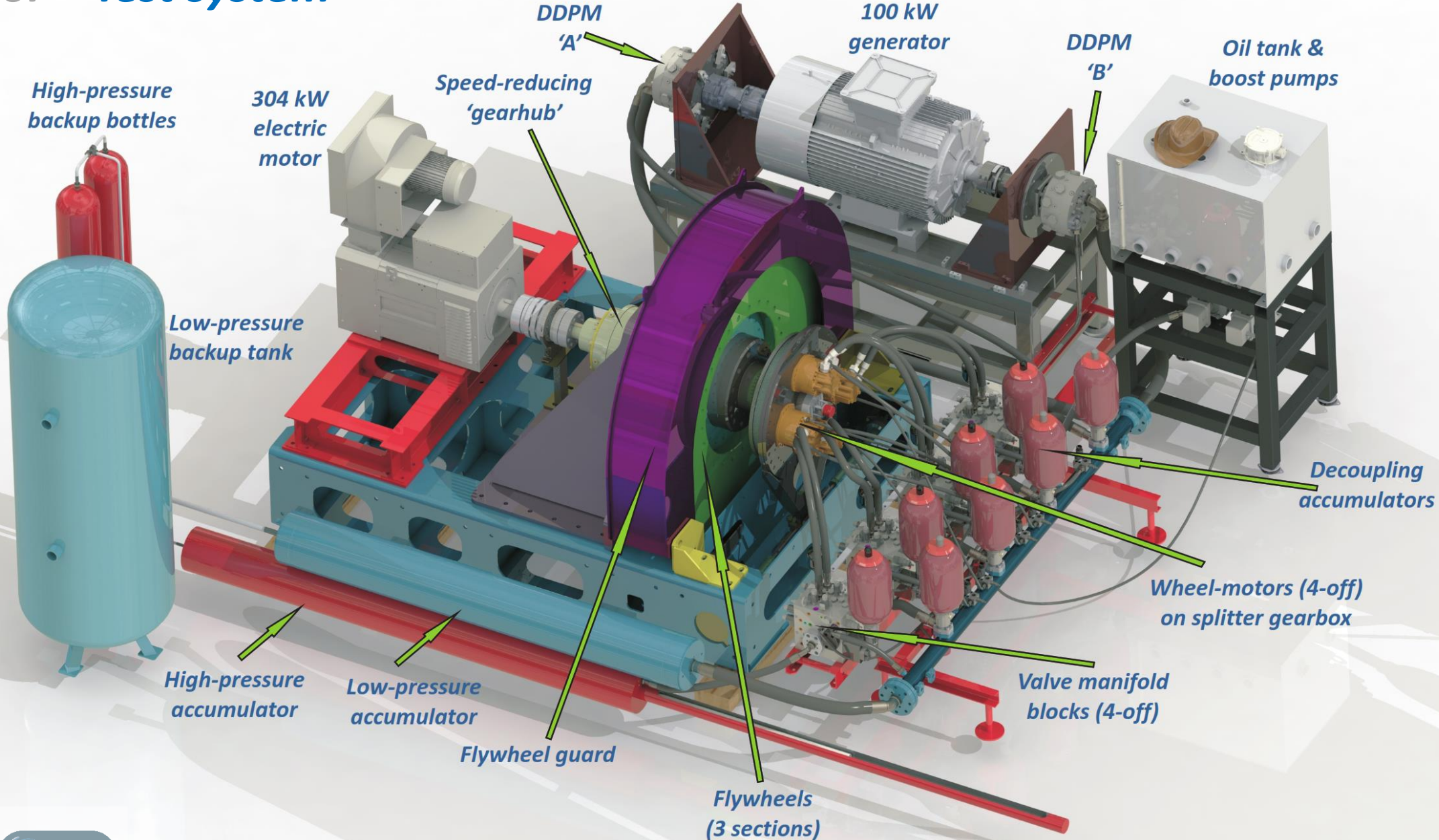
Quantor – Test system



Quantor – Test system



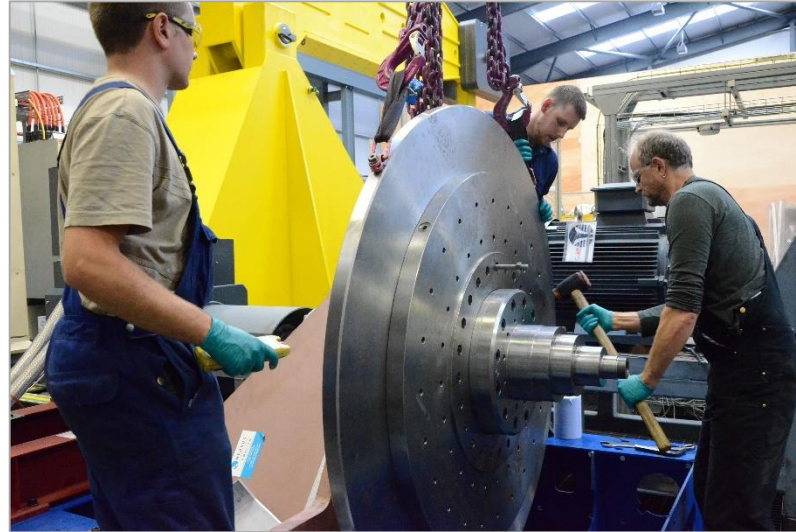
Quantor – Test system



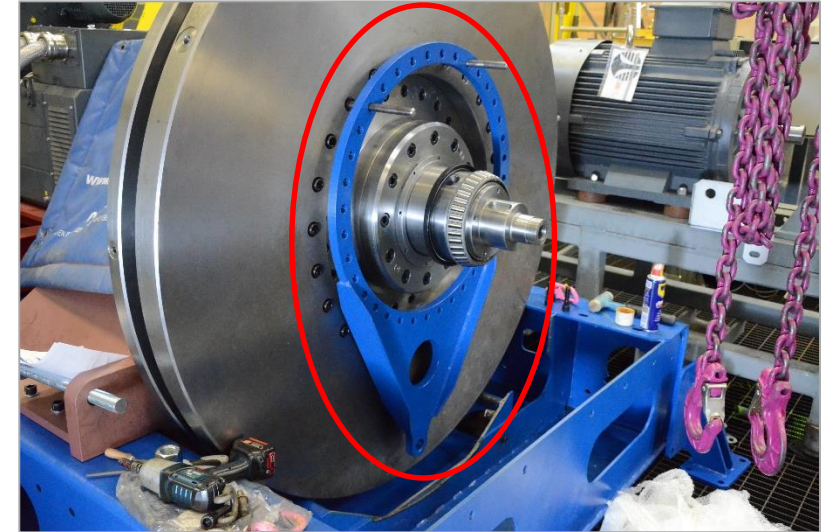
Quantor – Flywheel & gearbox



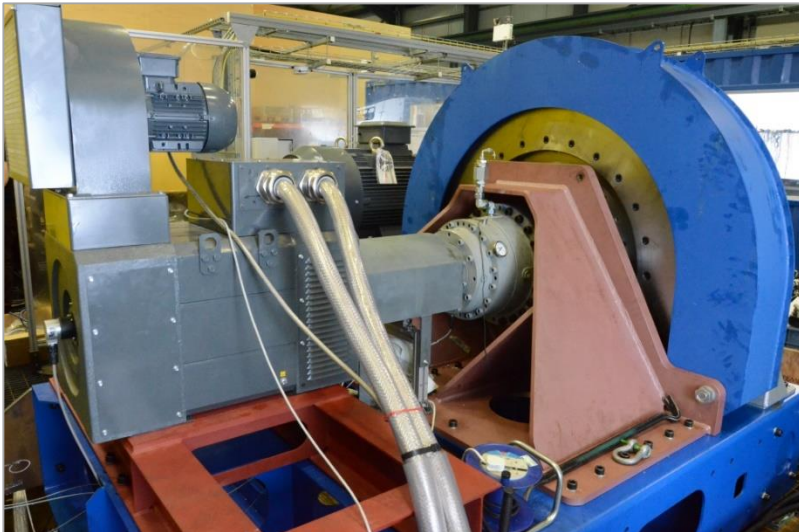
Flywheel preparation



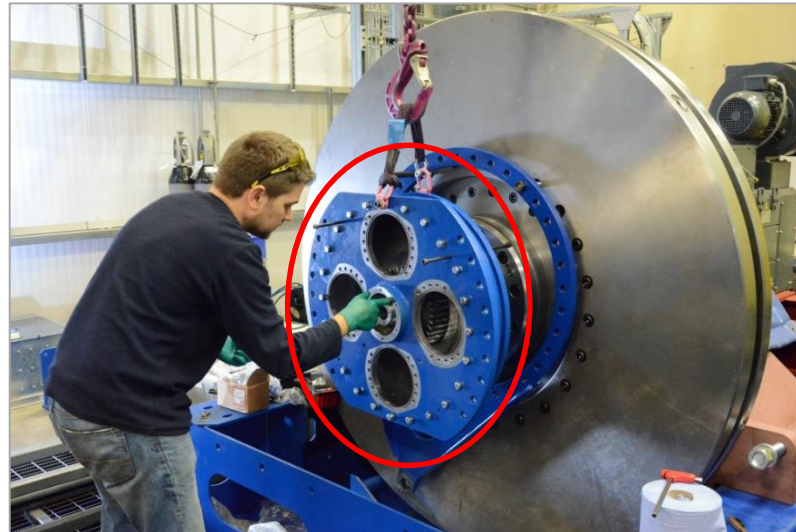
Flywheel installation



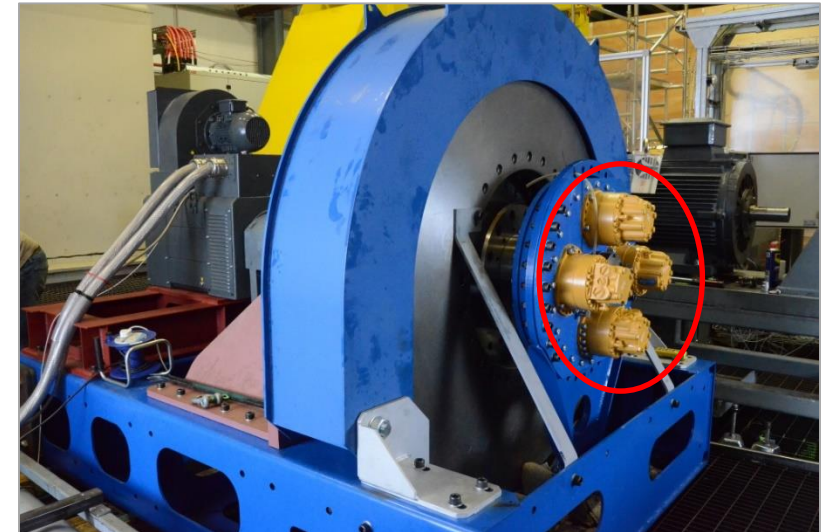
Torque arm



Drive motor, gearbox & flywheel guard

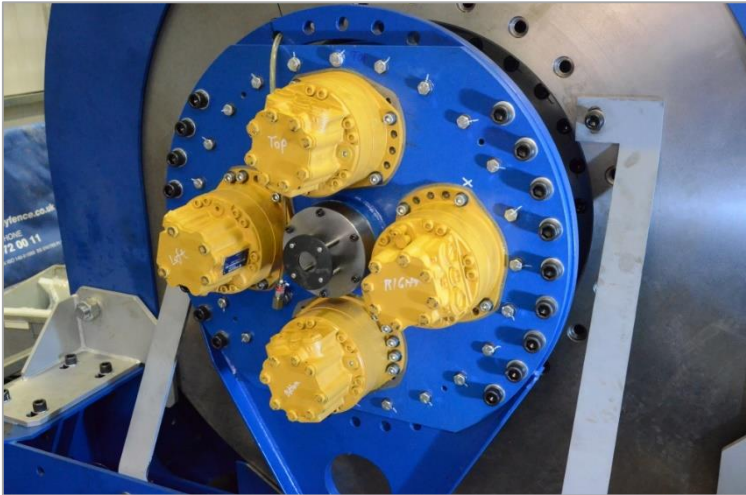


Assembly of splitter gearbox



Wheel motors in position

Quantor – Wheel-motors, manifold blocks & DD pump-motor



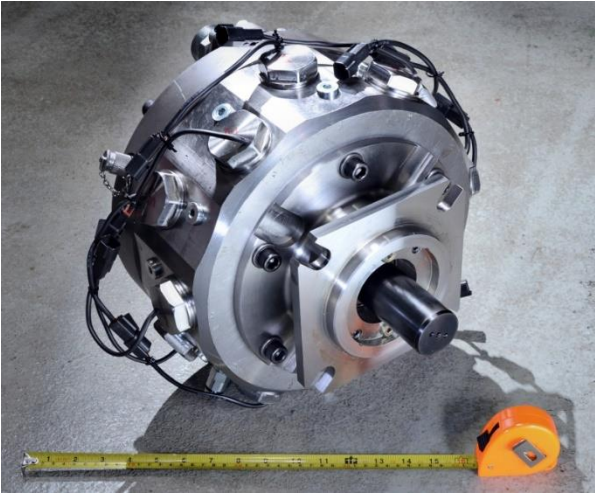
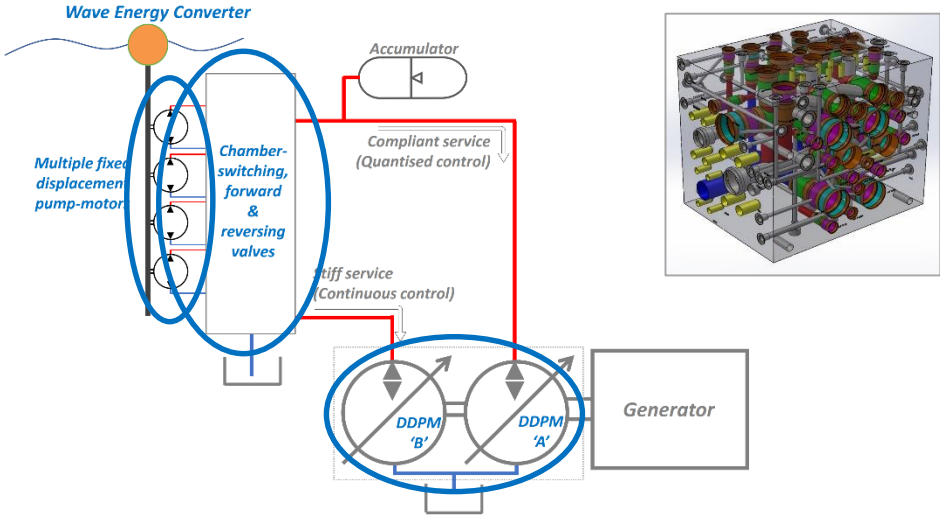
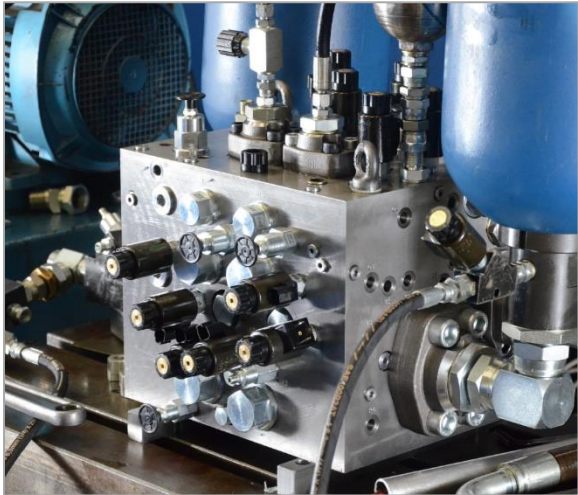
Four wheel-motors



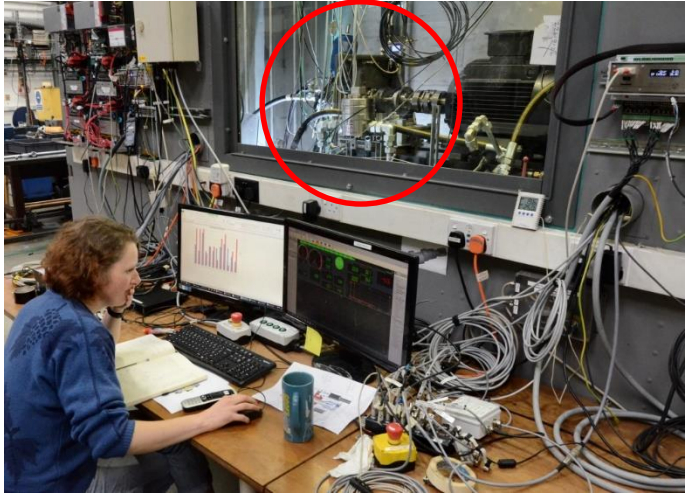
Poclair MS02



Prototype manifold block

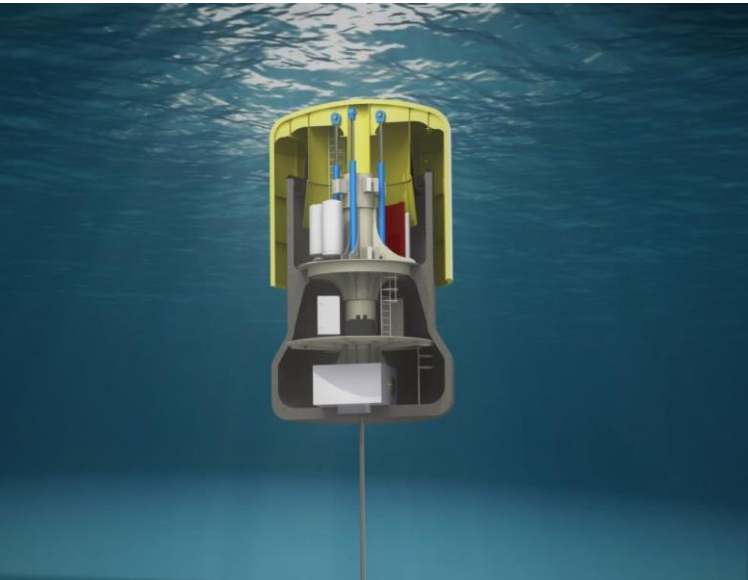


Artemis 'M96' pump-motor

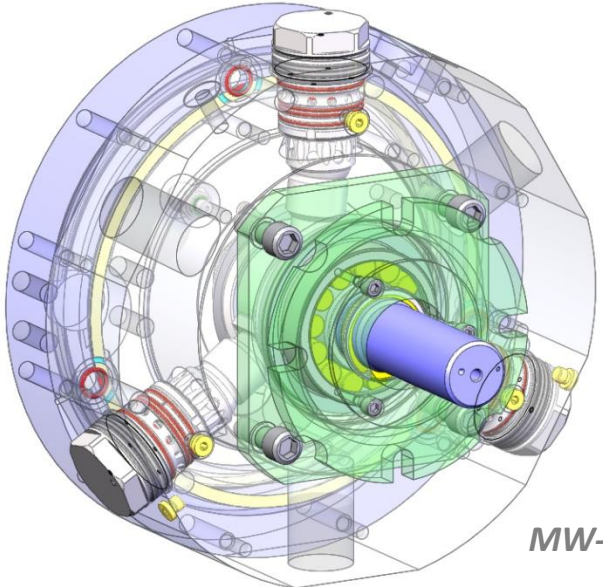
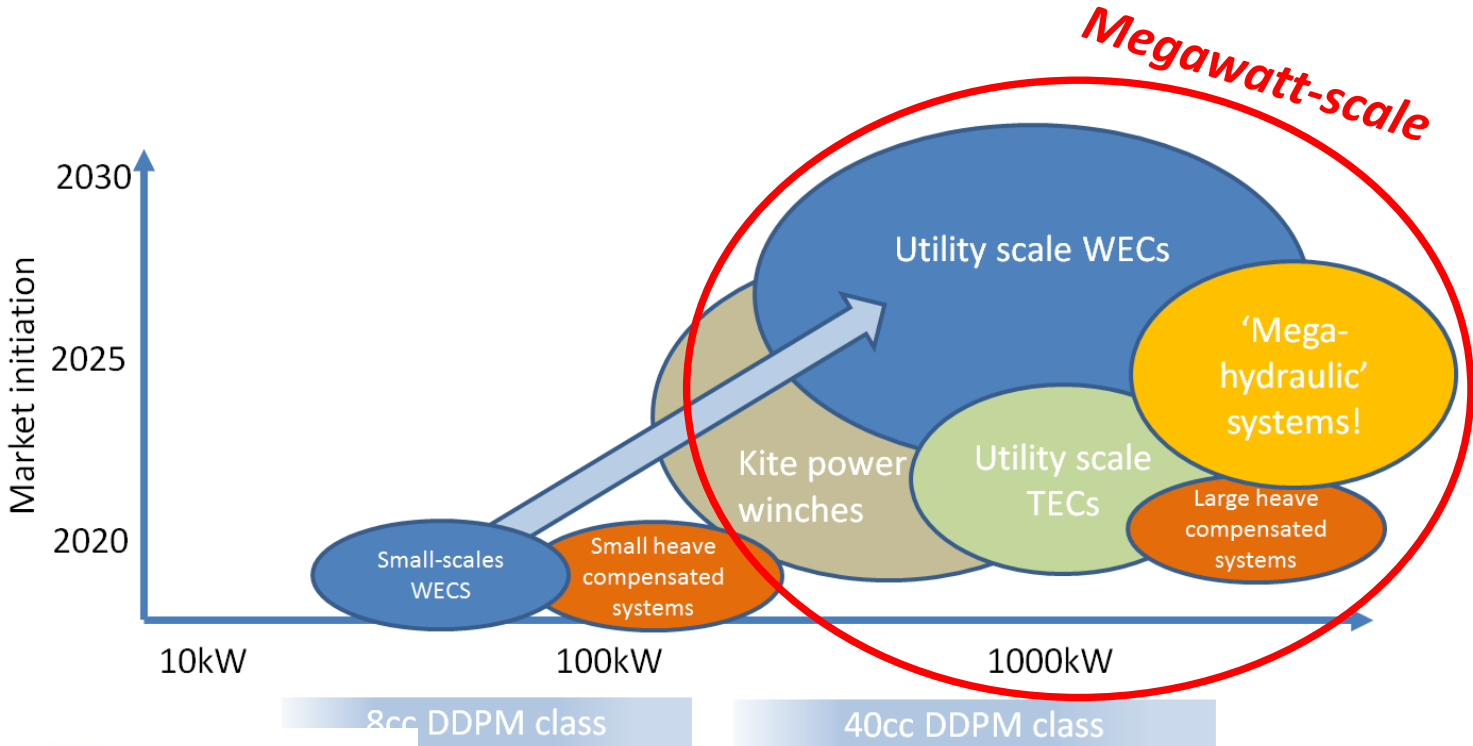


Testing 'M96' pump-motor

Quantor – Exploitation



WEC with linear variant of Quantor
(Courtesy: AWS Ocean Energy)



MW-scale prototype DD pump-motor

www.artemisip.com

www.queocean.com



Stage 3 PTO: PECMAG

WES 3rd Annual Conference, Edinburgh, 6th December 2018

Mark Brown, Engineering Manager - Renewables & Subsea Projects (Europe)

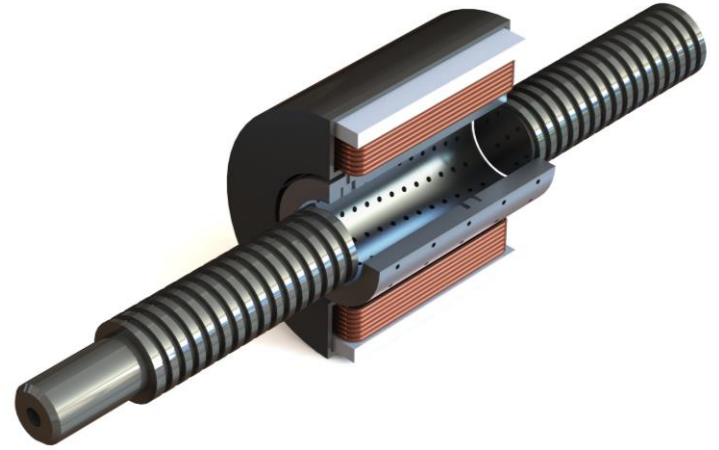


PECMAG

| POWER ELECTRONIC CONTROLLED MAGNETIC GEAR |

All electric system; magnetic gear and generator coupled to an integrated power and control system.

- **Integrated system** | Gear, generator, power electronics and control system developed as a single package
- **Improved Survivability** | Non contact gear allows damage free slippage in extreme sea states
- **Leading Efficiency** | Gear enhanced by highly configurable power system to maximize capture efficiency
- **Increased Availability** | Redundant configurations to enable degraded system availability



Stage 3 Project

|SCOPE|

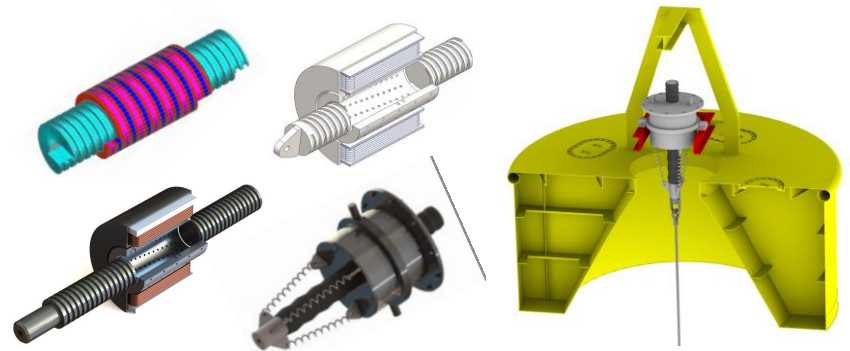
- Develop 10kW linear to rotary system
- Design & manufacture gear, generator, power system, in water test platform and monitoring system
- Onshore bench testing & sea trials (Firth of Forth)
- Develop commercialisation roadmap

|FOCUS AREAS|

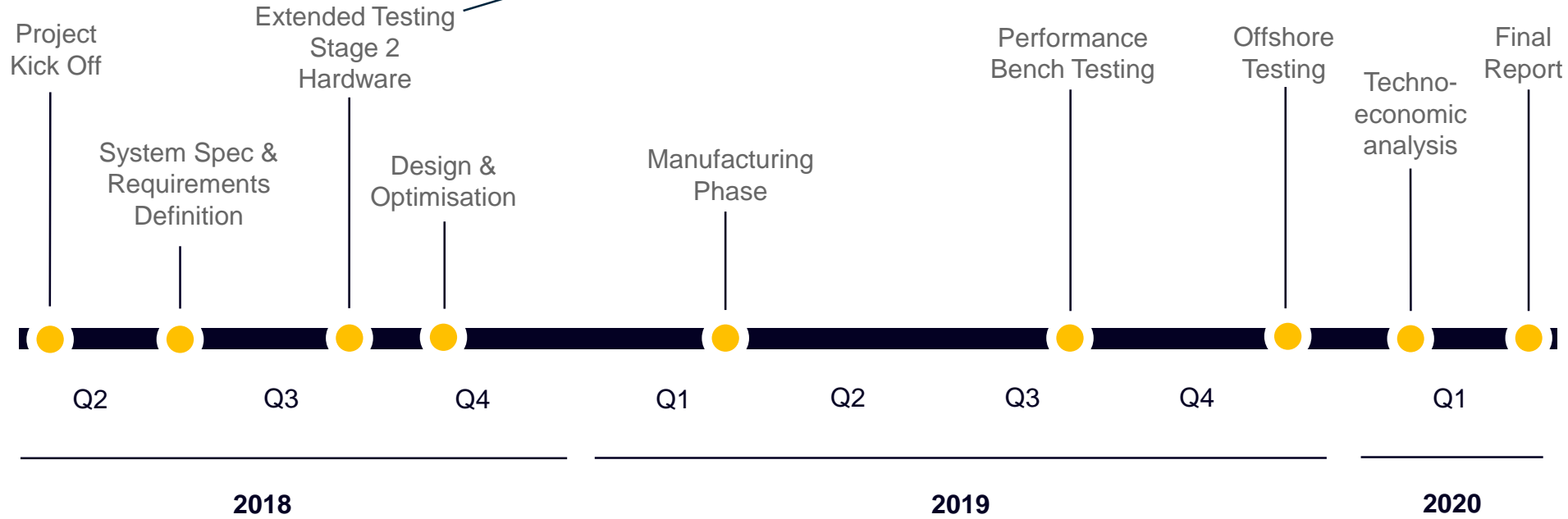
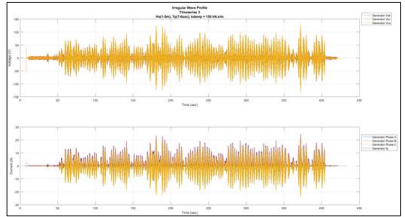
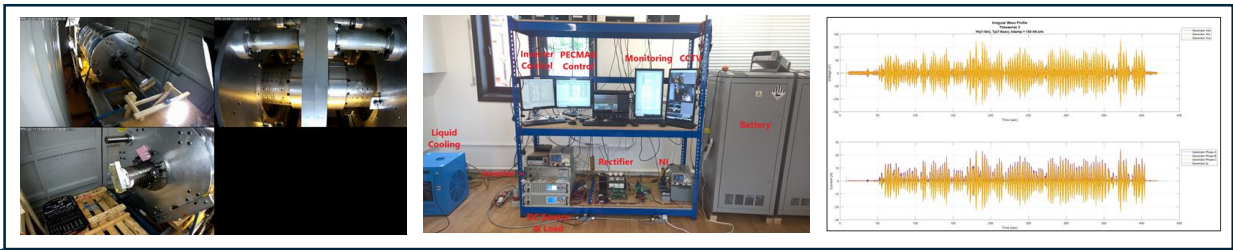
- Optimisation; Geometry & mass, bearing configuration, power & control system
- Seagoing operability; Marinisation and integration with WEC type platform
- Scalability; Design, manufacturing processes & materials
- Modularity; Improved assembly & maintenance

|KEY OBJECTIVES|

- Bring PECMAG to a readiness level for deployment on pre-commercial demonstrator
- Deliver intermediate unit size with the ability to support WEC testing at EMEC
- Meet efficiency targets that satisfy requirements of commercialisation



Timeline



OCEANEERING®

Connecting What's Needed With What's Next™





UMBRA GROUP

umbragroup.com

EMERGE



Electro-MEchanical Reciprocating GEnerator

emerge (/i'mɑ:dʒ/): to appear, or to become recognized

Luca Castellini

Energy R&D and BD Manager

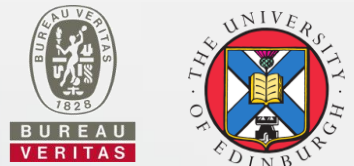
Electro-MEchanical Reciprocating GEnerator - UMB PTO32

Content of this presentation

- ➔ Introduction
- ➔ UMBRAGROUP innovation
- ➔ EMERGE project update
- ➔ Conclusions

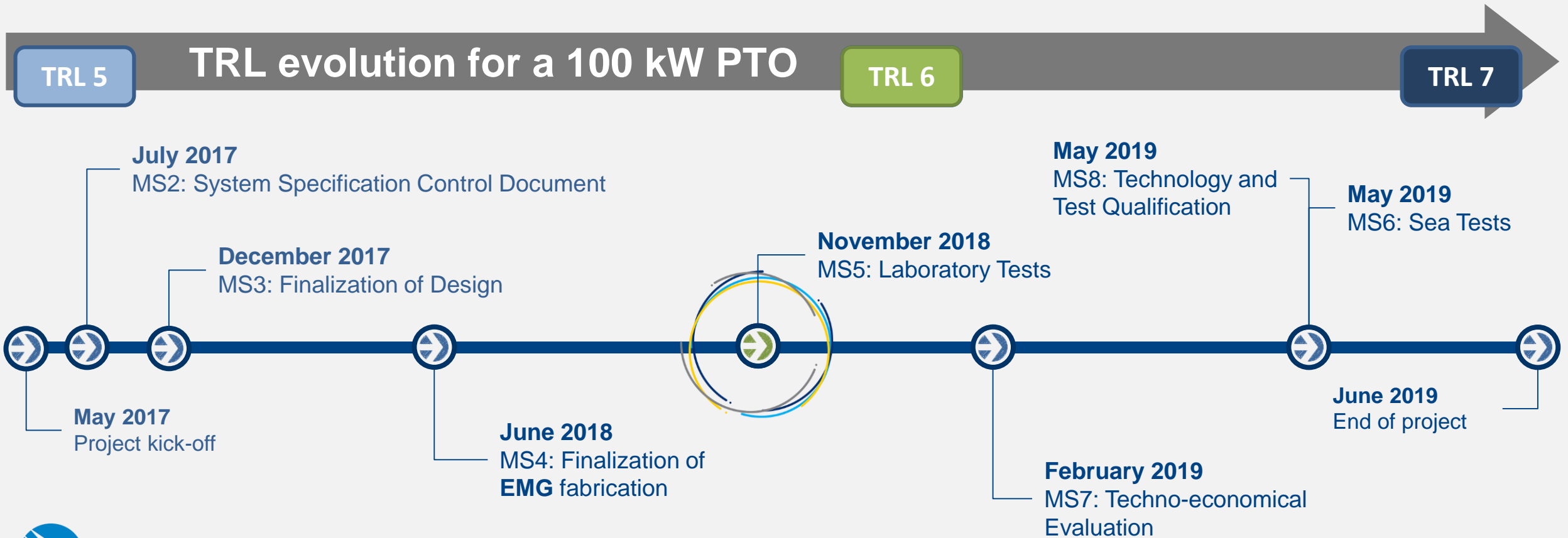


PEOPLE TOGETHER TO MEET
FUTURE CHALLENGES



EMERGE - WES PTO STAGE 3 PROJECT

Introduction



UMBRAGROUP innovation



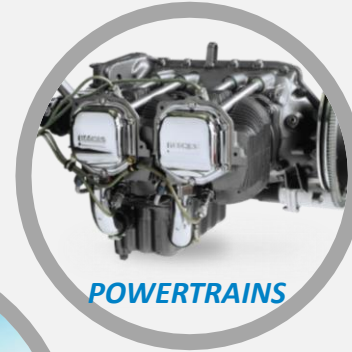
1972

FAG and GEPI found UMBRA to produce high-precision bearings



1978

The company starts producing ballscrews for aviation industries



POWERTRAINS



AEROSPACE



ENERGY



2018

Production of bearings, ballscrews, actuators and **generators** for a wide range of industries

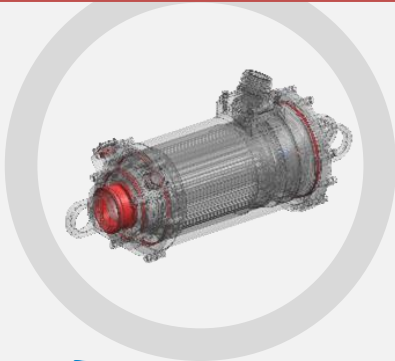


Technology transfer from other sectors to OCEAN REN. ENERGY

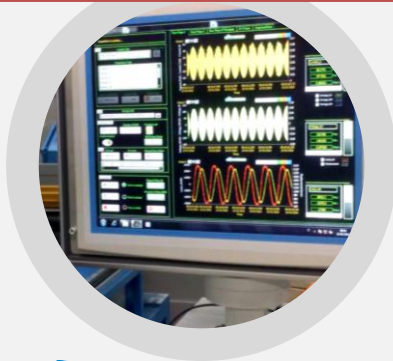
EMERGE - WES PTO STAGE 3 PROJECT

UMBRA GROUP innovation

ANALYSIS & SIMULATIONS



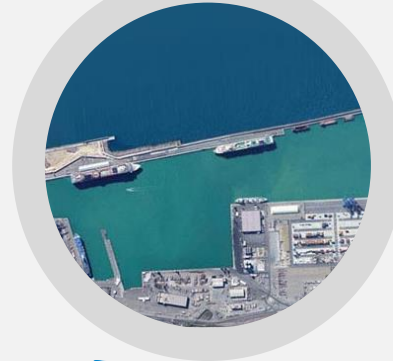
⇒ 2015



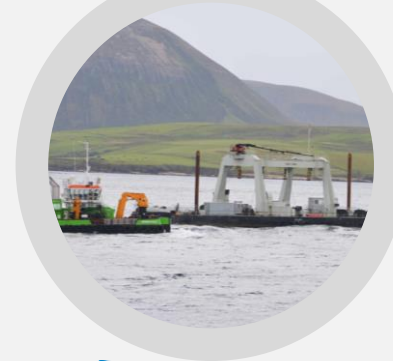
⇒ 2016



⇒ 2017



⇒ 2018



⇒ 2019

DRY TESTS

TANK TESTS

SEA TRIALS



UMBRA GROUP

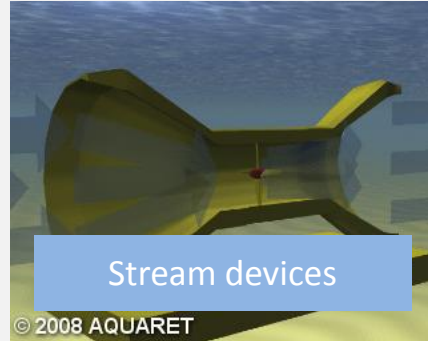
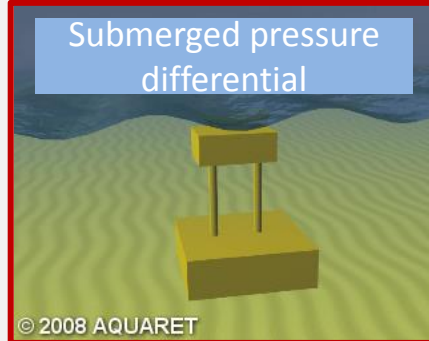
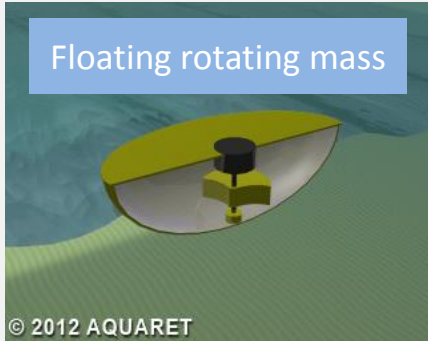
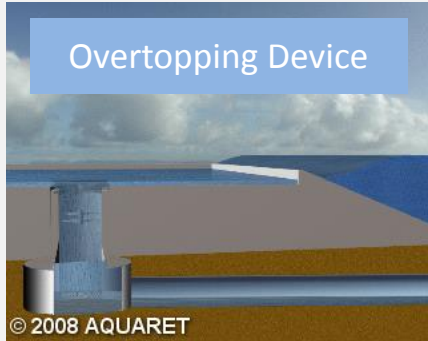
www.umbragroup.it

Umbragroup property information

EMERGE - WES PTO STAGE 3 PROJECT

UMBRA GROUP innovation

EMG best integration

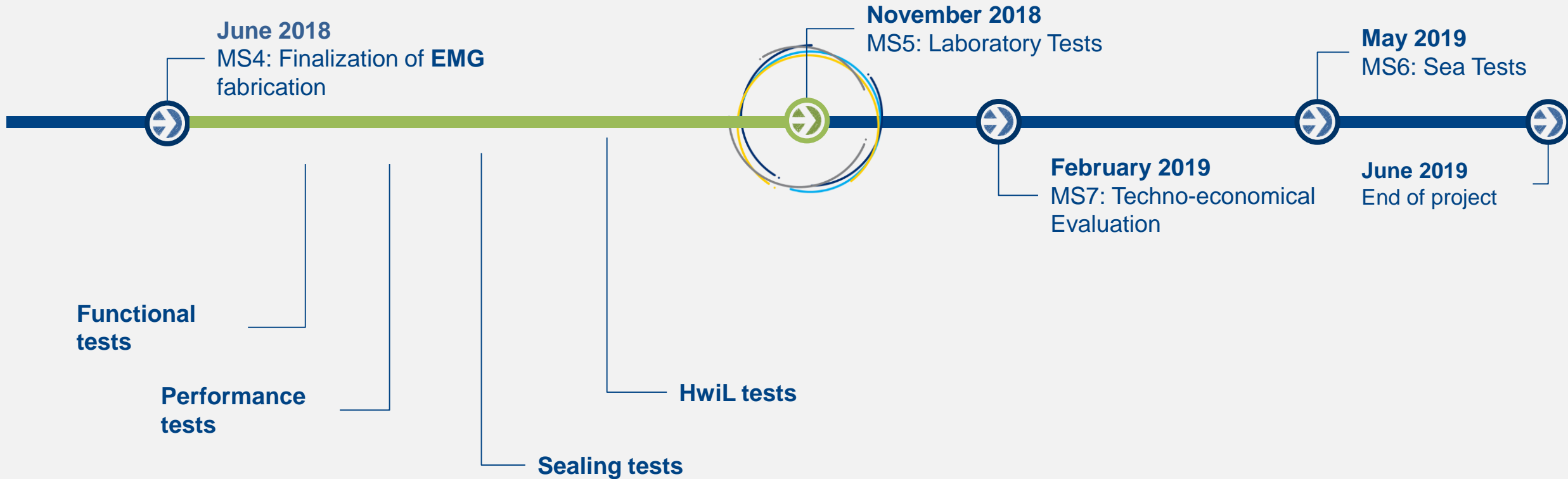


Wave energy conversion concepts that could directly integrate at least one product from UMBRAGROUP (bearings, ballscrews, actuators, rotary or linear generators)



EMERGE - WES PTO STAGE 3 PROJECT

EMERGE project



EMERGE - WES PTO STAGE 3 PROJECT

EMERGE project

MS4: Finalization of **EMG** fabrication (end of June 2018)



EMERGE - WES PTO STAGE 3 PROJECT

EMERGE project

Overview of the test area



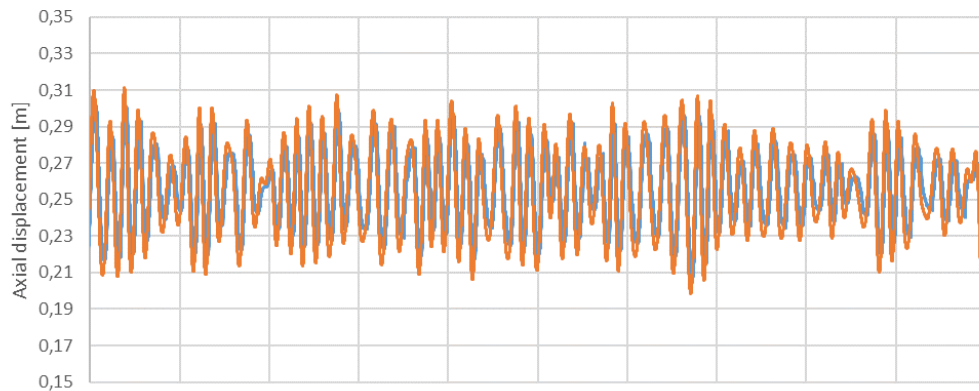
EMERGE - WES PTO STAGE 3 PROJECT

EMERGE project

HWiL test with synthetic sea state profiles

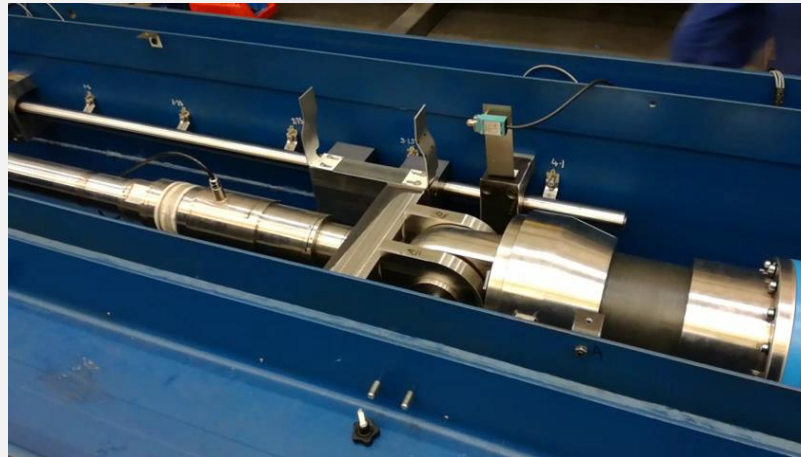
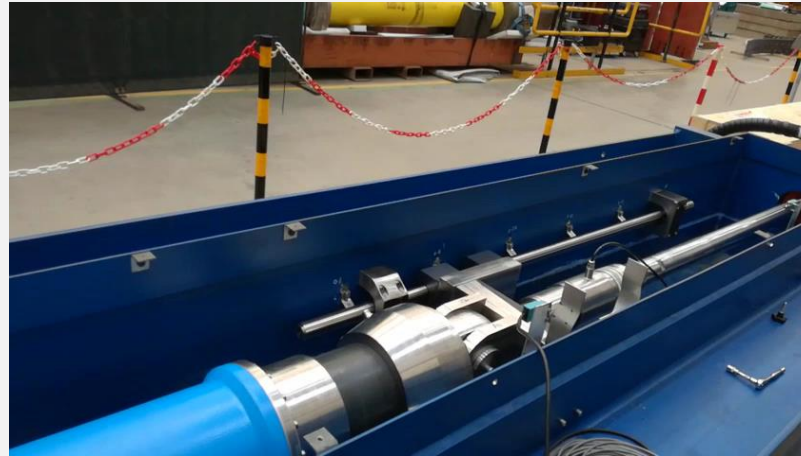
Sample test from TEST_05 - H-TBU transducers

— Feedback from bench — Set from Simulink



EMERGE - WES PTO STAGE 3 PROJECT

EMERGE project




EMERGE - WES PTO STAGE 3 PROJECT

EMERGE project



ENDORSEMENT and TECHNOLOGY FEASIBILITY STATEMENT by BUREAU VERITAS




BUREAU VERITAS MARINE & OFFSHORE SAS

STATEMENT OF FEASIBILITY

100 KW ELECTRO-MECHANICAL RECIPROCATING GENERATOR

Statement Ref.: AT17066 / RRM.18.00012 Rev.0
Technology Owner: Umbra Cuscinetti S.p.a
Name of Technology: Electro-Mechanical Reciprocating Generator (EMERGE)
Technology description: Electro-Mechanical Generator
Technology application: The EMERGE project involves an Electro-Mechanical Generator (EMG), which will be integrated with a Point-Pivoted Buoy (PPB) and a Power, Control and Monitoring (PCM) system to form Wave Energy Converter (WEC).

This is to state that the above technology has been assessed in accordance with qualification procedures and requirements of the guidance Bureau Veritas NI 525 DTM R00 E- Risk Based Qualification of New Technology Methodological Guidelines [1] and Technology Readiness Assessment of Horizon H2020 Work programme 2016-2017 - Annex G.

The technology specification requirements have been defined by the technology owner with regards to component performance requirements, Technology Readiness Level (TRL) requirements, and applicable standards for design and material treatment and raw materials procurement.

BV has been involved in the Technology Assessment, divided in 3 steps:

- Technology Composition Analysis, which describes the functions of the technology components;
- Technology Categorization, which indicates which component of the technology is novel and needs to be focused on during the qualification activities; and
- Qualification-Failure Modes, Effects and Criticality Analysis (Q-FMECA), which identifies threats and weaknesses of the technology, and identifies the technology qualification activities which will be required for the project in order to demonstrate the ability of the technology to meet the specification requirements in the intended environment.



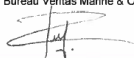
Nineteen (19) qualification activities already exist, and seven (7) additional qualification activities have been identified during the Technology Assessment [2]. These additional activities will be included in the Technology Qualification Plan (TQP) issued by the Technology Owner.

BV considers the technology conceptually feasible as defined and thereby suited for further development and qualification according to Bureau Veritas NI 525 DTM R00 E.

Issued at Paris La Défense, France, on 25th of January 2018.

Diane RUF
Risk, Reliability & Maintenance Manager
Services Department
Bureau Veritas Marine & Offshore SAS

Olivier BENYESSAAD
Ocean Energy Market Leader
Offshore Sales & Marketing Department
Bureau Veritas Marine & Offshore SAS




BUREAU VERITAS MARINE & OFFSHORE SAS

ENDORSEMENT OF TECHNOLOGY QUALIFICATION PLAN

100 KW ELECTRO-MECHANICAL RECIPROCATING GENERATOR

Statement Ref.: AT17066 / RRM.18.00013 Rev.0
Technology Owner: Umbra Cuscinetti S.p.a
Name of Technology: Electro-Mechanical Reciprocating Generator (EMERGE)
Technology description: Electro-Mechanical Generator
Technology application: The EMERGE project involves an Electro-Mechanical Generator (EMG), which will be integrated with a Point-Pivoted Buoy (PPB) and a Power, Control and Monitoring (PCM) system to form Wave Energy Converter (WEC).

This is to endorse that the Qualification Plan [3] of the above mentioned technology is in accordance with the guidance Bureau Veritas NI 525 DTM R00 E- Risk Based Qualification of New Technology Methodological Guidelines [1] and that the technology can be proven Fit for Service through the remaining planned qualification activities identified in the Technology Qualification Plan (TQP).

Technology Qualification Plan (TQP) has been issued by the Technology Owner based on the additional qualification activities identified during the Technology Assessment [2], and more particularly the Qualification-Failure Modes, Effects and Criticality Analysis (Q-FMECA).

BV has checked the technical aspects of the TQP including the consistency of the estimated schedule.

Issued at Paris La Défense, France, on 25th of January 2018.

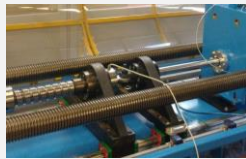
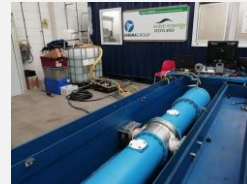
Diane RUF
Risk, Reliability & Maintenance Manager
Services Department
Bureau Veritas Marine & Offshore SAS

Olivier BENYESSAAD
Ocean Energy Market Leader
Offshore Sales & Marketing Department
Bureau Veritas Marine & Offshore SAS



CONCLUSIONS

- ➔ Technology transfer from other sectors to OCEAN REN. ENERGY
- ➔ Highly reliable and efficient solution (proved by robust methodology)
- ➔ Third-party technology validation
- ➔ High TRL and established manufacturing capabilities
- ➔ Clear ROADMAP to commercialization





THANK YOU FOR THE ATTENTION



UmbraGroup property information

Wave Energy Scotland Third Annual Conference:
#wesanconf18

Project Neptune Update: Component Manufacture, Machine Assembly & Testing Overview

Joseph Burchell

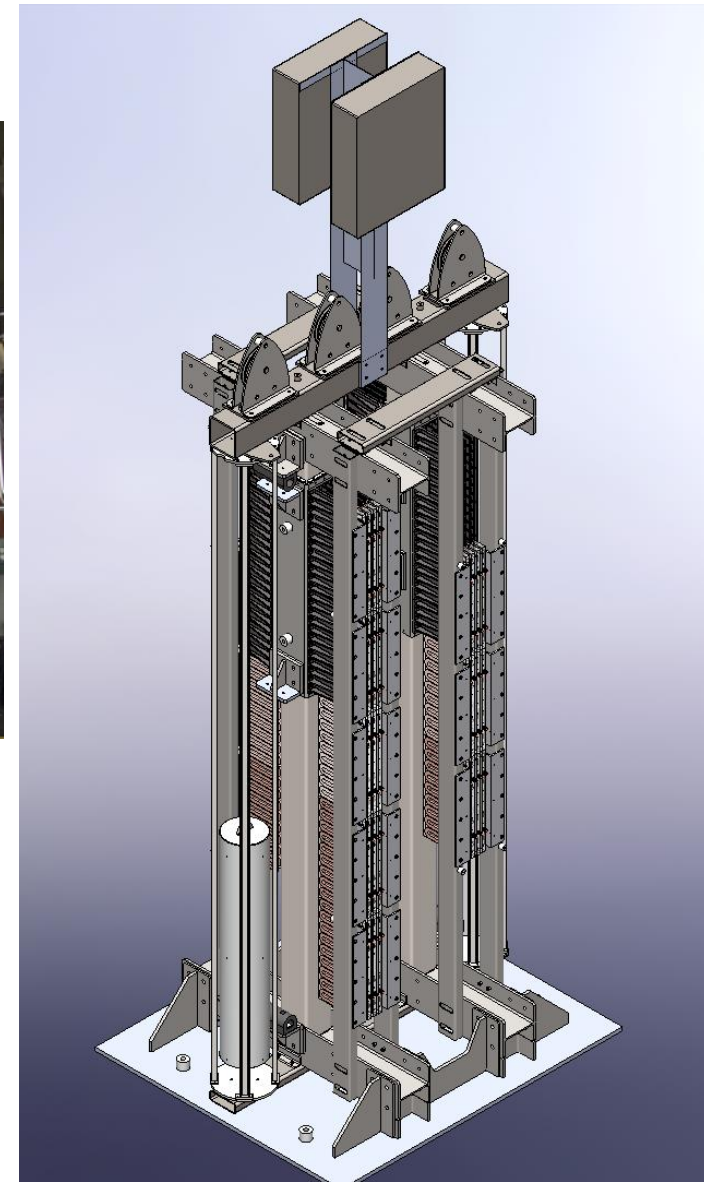
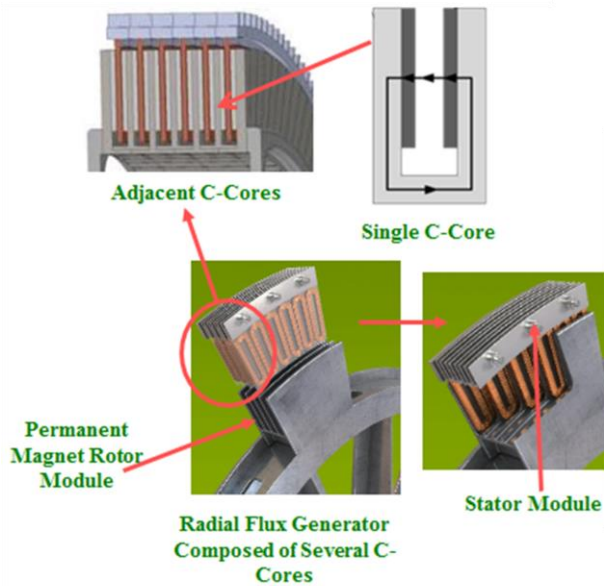
University of Edinburgh, School of Engineering
Institute for Energy Systems

Project Neptune Status

- Project Neptune
- Coil Blade and Module Manufacturing
- Translator and Magnet Module Manufacturing
- Test Rig Manufacture
- Testing at Quartz Elec and Leith docks



Project Neptune

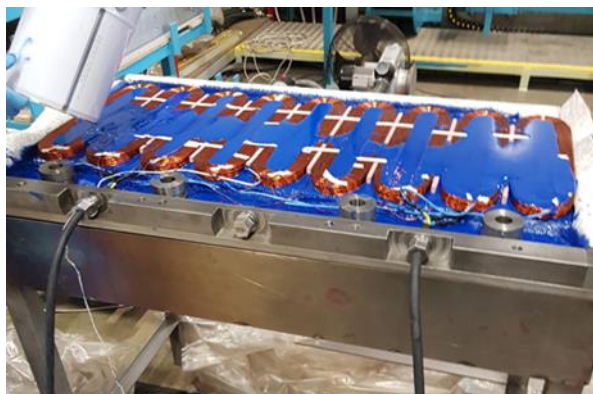


- No magnetic attraction forces closing the airgap,
- No cogging torque, and
- Air cored coils that allow for a high level of modularity leading to multi stage machines for higher energy availability and a reduction of O&M costs.

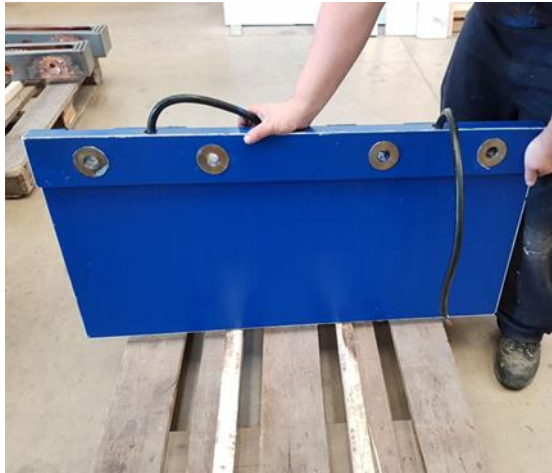
Coil Blade and Module Manufacture



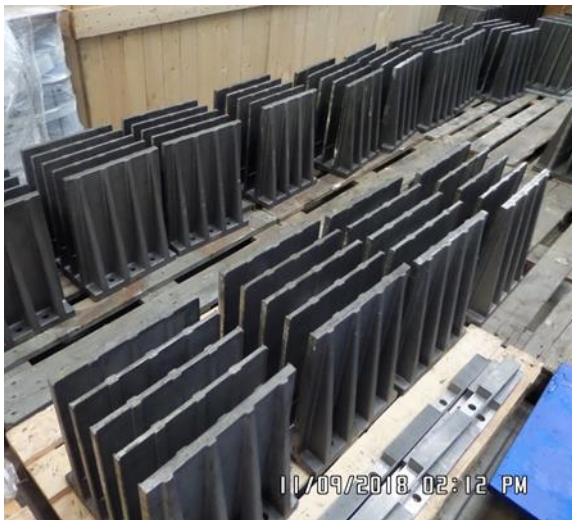
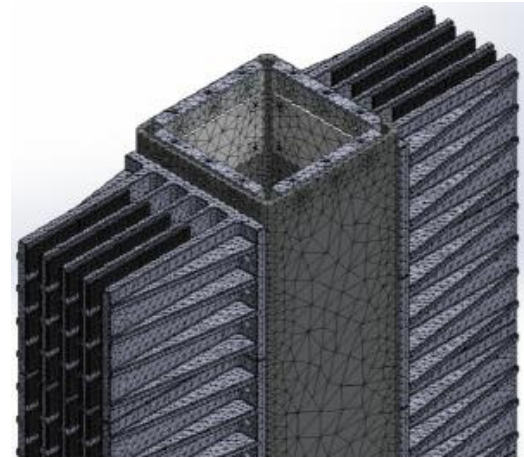
Coil Blade and Module Manufacture



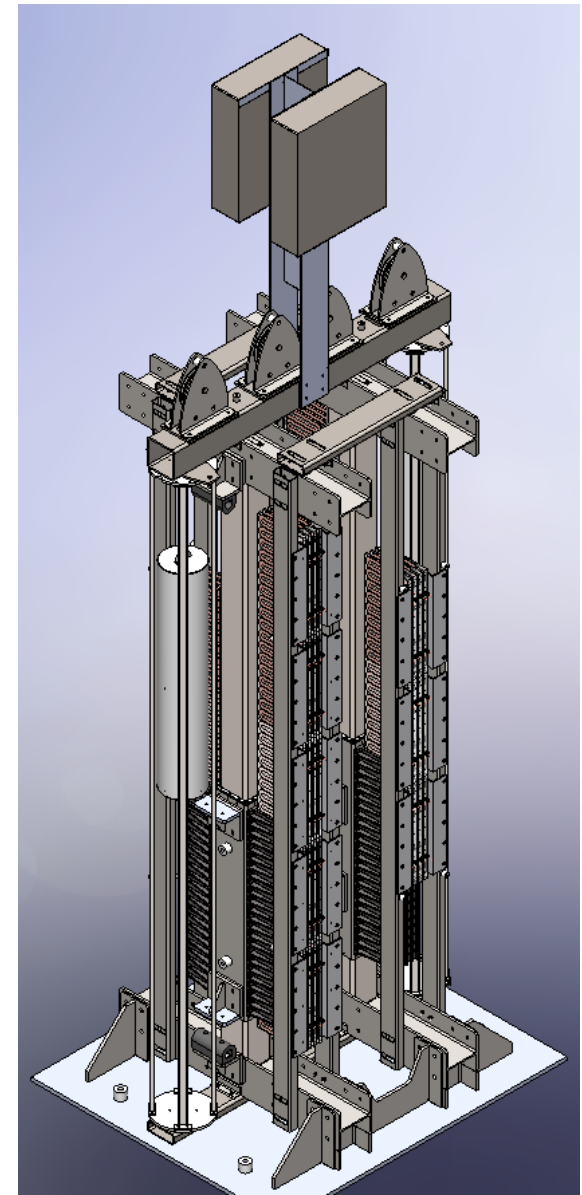
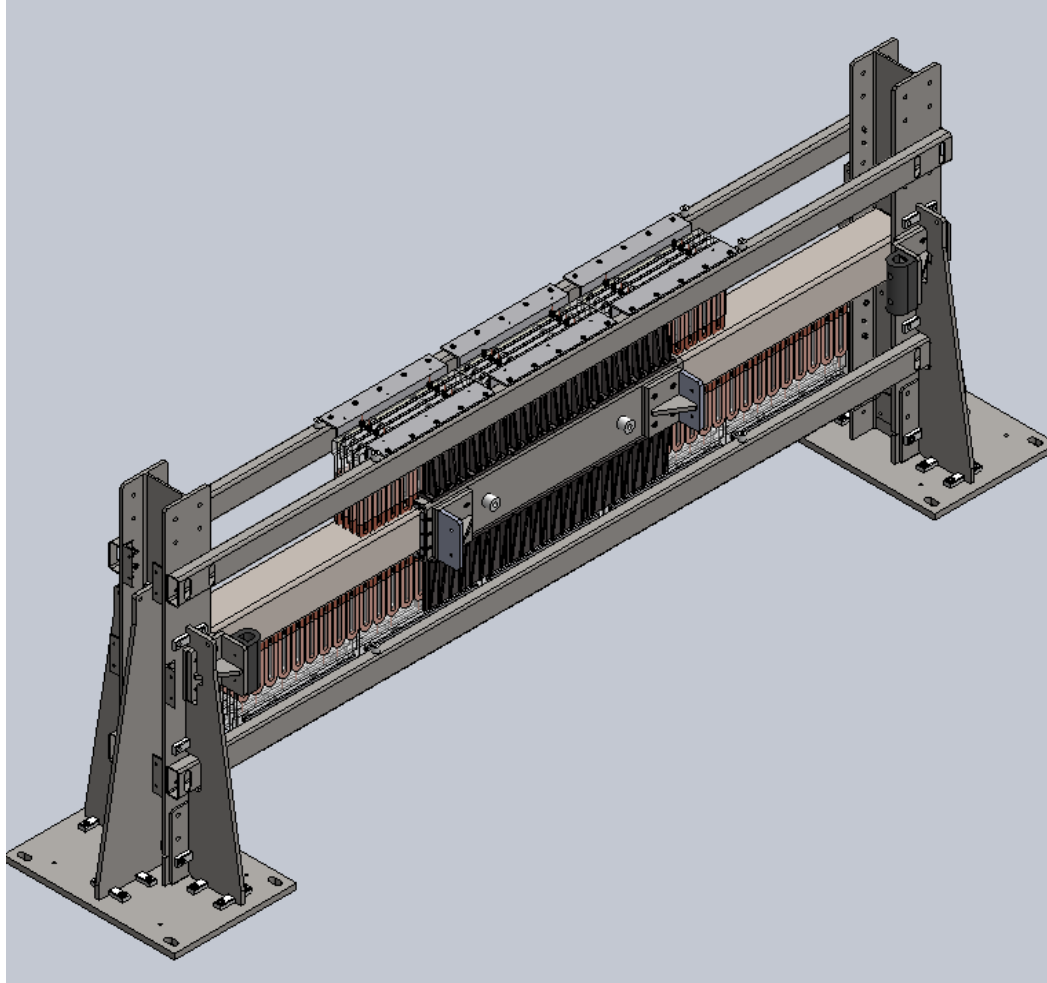
Coil Blade and Module Manufacture



Translator and Magnet Module Manufacturing



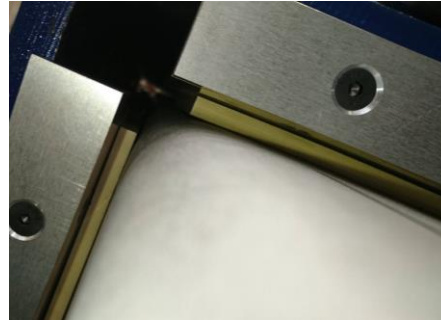
Test Rig Manufacture



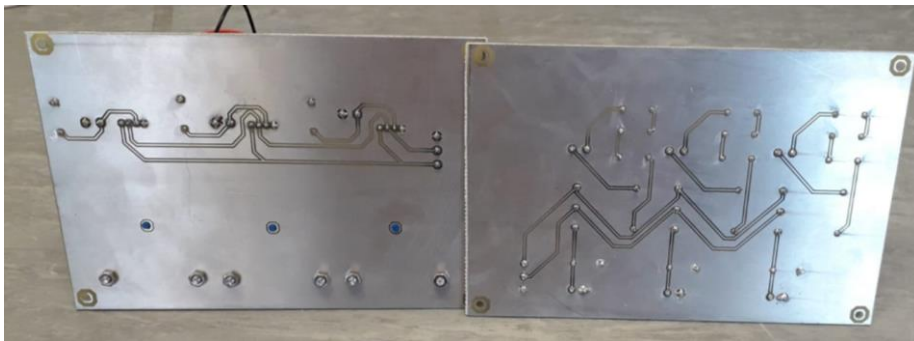
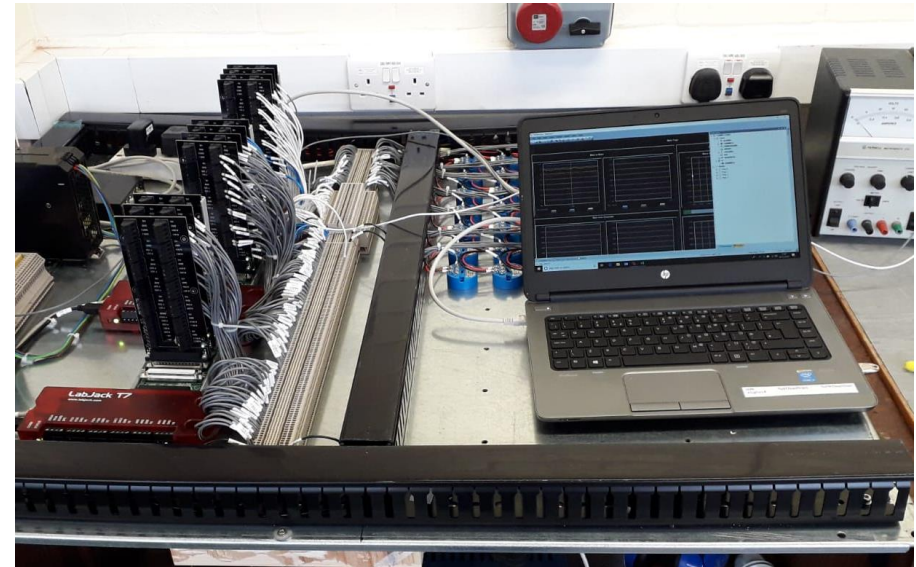
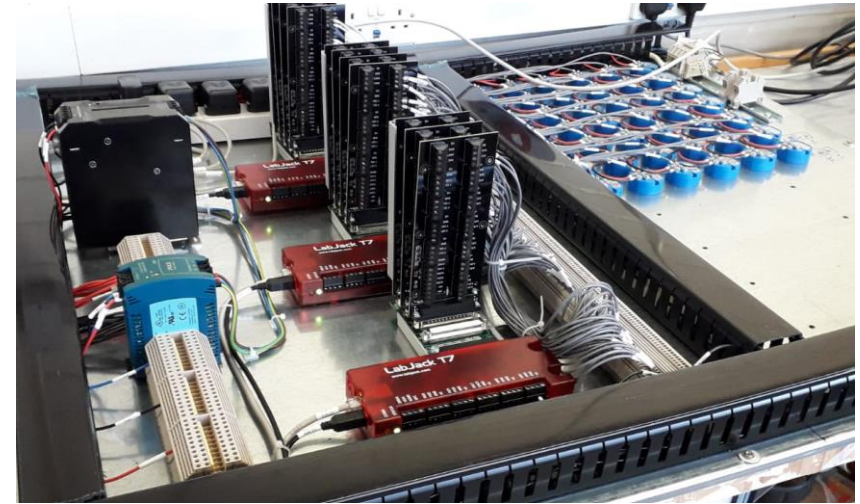
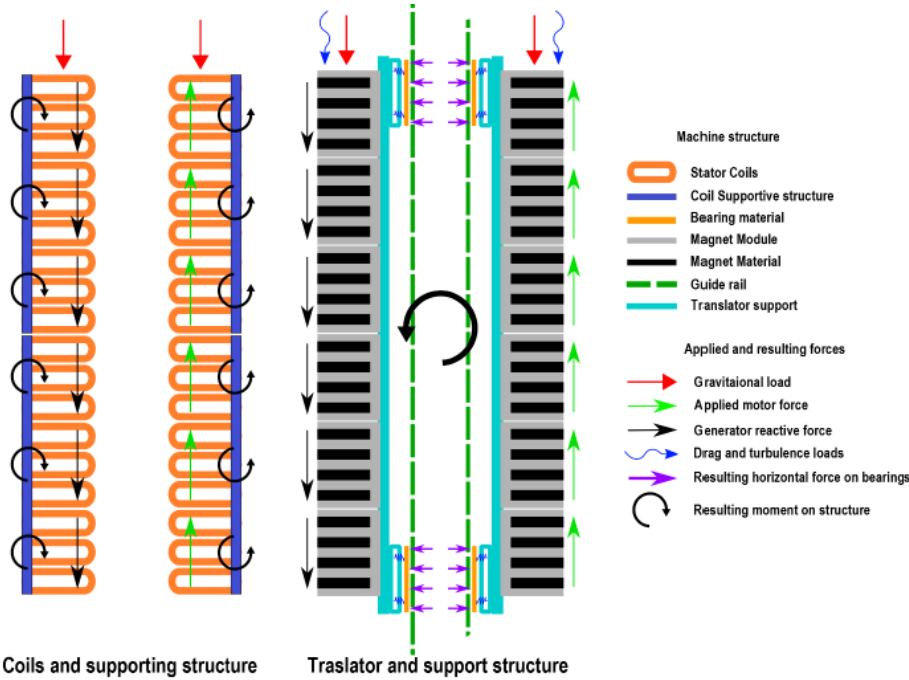
Test Rig Manufacture



Test Rig Manufacture



Testing at Quartz Elec and Leith docks



Testing at Quartz Elec and Leith docks

